

Transport:

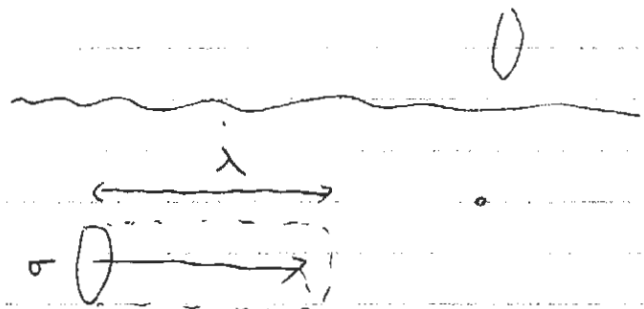
Two limits: Collisionless and hydrodynamic

Mean-free path:

σ scattering cross section

σ cross section

$\lambda \sigma$ contain one collision center on average.



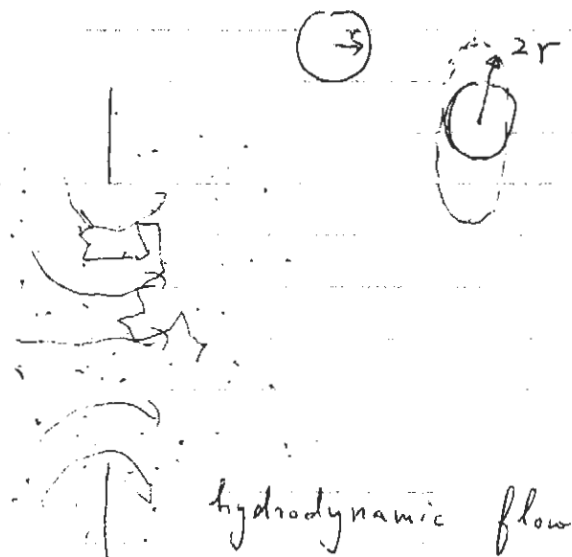
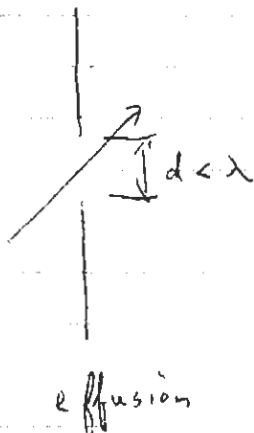
$$\lambda = \frac{1}{\sigma n}$$

• ← collision center

n : density of collision center

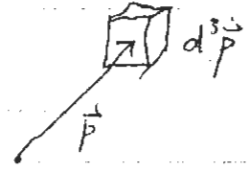
Scattering cross section of two hard balls

$$\sigma = \pi (2r)^2 = 4\pi r^2$$



Effusion

distribution of momentum



$f(\vec{p}) d^3\vec{p}$ = density of particles with momentum
in d^3p

$$f(\vec{p}) = C e^{-\beta \vec{p}^2 / 2m}$$

Boltzmann distribution

$\int d^3p f(\vec{p}) = n$ total density of particles.

$$\Rightarrow C = n (2\pi m k_B T)^{-3/2}$$

Flux of effusion: (# of particles per unit area per second) $n \neq 0$ | $n = 0$

$$I = \int_{v_x > 0} v_x f(p) d^3\vec{p}$$

$$= C \int_{p_x > 0} \frac{p_x}{m} e^{-\beta (p_x^2 + p_y^2 + p_z^2) / 2m} dp_x dp_y dp_z$$

$$= n \sqrt{\frac{k_B T}{2\pi m}}$$

$$I \propto n T^{1/2} m^{-1/2}$$

Why?

Physical picture

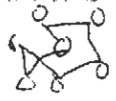
Non-viscous hydrodynamics

- Three equations

$$\lambda/l \rightarrow 0$$

λ : mean-free path
 l : scale of interest

particles are "caged" by their neighbors

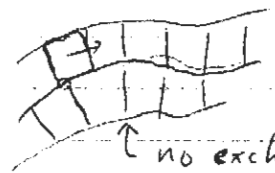


mass density: $\rho(\vec{x}, t) = m n(\vec{x}, t)$
 mass current: $\rho \vec{u}$

\vec{u} average velocity
 of particles.

\sim velocity of gas/fluid

picture



\uparrow no exchange
 of particle,
 heat, ...

① Mass conservation

$$\boxed{\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \vec{u}) = 0} \quad \text{continuity equation}$$

$$\Rightarrow \frac{d}{dt} \int_V d^3\vec{x} \rho + \oint_{\partial V} d\vec{S} \cdot \rho \vec{u} = 0$$

② Newton's law

$$\frac{d\vec{u}}{dt} = \frac{1}{m} \vec{f} \quad \leftarrow \text{force on the particle}$$

\vec{u} if we follow one particle

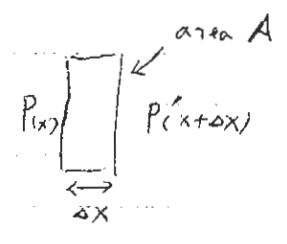
$$\frac{d\vec{u}}{dt} = \underbrace{\left(\frac{\partial}{\partial t} + \vec{u} \cdot \nabla \right)}_{= \frac{d}{dt}} \vec{u}(\vec{x}, t)$$

\uparrow velocity field

$$F_x = A (P_{ix} - P_{ix+\Delta x})$$

$$= -\Delta x A \partial_x P \quad \text{on } N \text{ particles}$$

$$\text{on one particle} \quad f_x = \frac{F_x}{N} = -\frac{1}{n} \partial_x P$$



$$\left(\frac{d}{dt} + \vec{u} \cdot \nabla \right) \vec{u} = -\frac{1}{mn} \nabla P + \frac{1}{m} \vec{f}_{ex}$$

$$\Rightarrow \boxed{\rho \left(\frac{\partial}{\partial t} + \vec{u} \cdot \nabla \right) \vec{u} + \nabla P = n \vec{f}_{ex}} \quad \text{Euler's eqn.}$$

↑
force per particle

③ Adiabatic condition conservation of entropy per particle $-s$:

s does not change with the flow

$$S = Nk \left[\frac{5}{2} - \ln(n \lambda^3) \right], \quad s = \frac{S}{N}, \quad \lambda = \sqrt{\frac{2\pi \hbar^2}{mk_B T}}$$

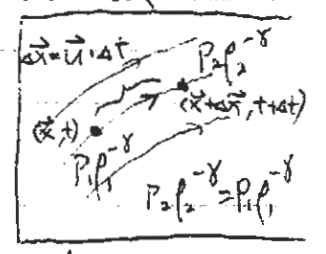
$$\Rightarrow n T^{-3/2} \quad \text{is conserved}$$

$$P = n k_B T \quad \text{or} \quad T = \frac{P}{n k_B}$$

$$\Rightarrow n \left(\frac{n}{P} \right)^{3/2} = n^{5/2} P^{-3/2} \quad \text{is conserved}$$

$$\text{or} \quad \boxed{P \rho^{-5/3} \quad \text{is conserved}}$$

$$\boxed{\left(\frac{\partial}{\partial t} + \vec{u} \cdot \nabla \right) (P \rho^{-5/3}) = 0} \quad \delta = \frac{5}{3} \quad \text{Adiabatic condition}$$



5 unknown ρ, P, \vec{u} & 5 equations.

★ Linearized equation

$$P = P_0 + \delta P$$

$$P = P_0 + \delta P$$

$$\vec{u} = 0 + \vec{u}$$

$$\frac{\partial \delta P}{\partial t} + P_0 \nabla \cdot \vec{u} = 0$$

$$P_0 \frac{\partial \vec{u}}{\partial t} + \nabla \delta P = 0$$

$$\frac{\partial}{\partial t} (P P^{-\gamma}) = P_0^{-\gamma} \frac{\partial}{\partial t} \delta P - \gamma P_0 P_0^{-\gamma-1} \frac{\partial}{\partial t} \delta P = 0$$

$$\frac{\partial}{\partial t} \delta P - \gamma \frac{P_0}{P_0} \frac{\partial}{\partial t} \delta P = 0$$

★ Sound waves

$$\hookrightarrow \frac{\delta P}{P_0} = \gamma \frac{\delta P}{P_0}$$

$$\frac{\partial^2 \delta P}{\partial t^2} + P_0 \nabla \cdot \frac{\partial \vec{u}}{\partial t} = 0$$

$$\frac{\partial^2 \delta P}{\partial t^2} - \nabla^2 \delta P = 0$$

$$\frac{\partial^2 \delta P}{\partial t^2} - \nabla^2 \delta P \gamma \frac{P_0}{P_0} = 0$$

$$\Rightarrow \frac{\partial^2 \delta P}{\partial t^2} - c^2 \nabla^2 \delta P = 0$$

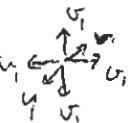
$$P = n k_B T$$

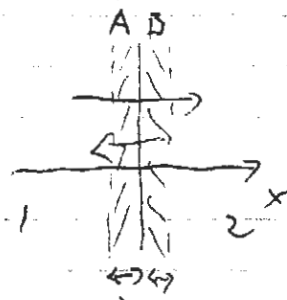
$$c = \sqrt{\frac{\gamma P_0}{\rho_0}} = \sqrt{\frac{\gamma k_B T}{m}}$$

$$\gamma = \frac{5}{3}$$

$c \sim$ thermal velocity of particle

* Diffusion
estimate

$$\langle \vec{v}_i \rangle = 0$$




Net flux: 6 directions

$$j_x = \frac{1}{6} \bar{v}_1 n_1 - \frac{1}{6} \bar{v}_2 n_2$$

$$= \frac{1}{6} \bar{v} (n_1 - n_2)$$

assume \bar{v} is the same

what $n_1 - n_2$?

n_1 density of particles coming
from region A

n_2 for region B

$$n_1 - n_2 = -\partial_x n \cdot \lambda$$

$$j_x = -\frac{1}{6} \bar{v} \lambda \partial_x n$$

\hat{L} diffusion flux.

in hydrodynamical limit

we set $\lambda = 0$ no diffusion

in general

$$\vec{j} = -D \nabla n$$



$$D \approx \frac{\lambda \bar{v}}{6}$$

Continuity equation (with diffusion)

$$\frac{\partial n}{\partial t} + \nabla \cdot \vec{j} = 0$$

$$\vec{j} = n \vec{u} - D \nabla n$$

$$\Rightarrow \boxed{\frac{\partial n}{\partial t} + \nabla \cdot n \vec{u} - D \nabla^2 n = 0}$$

$$\text{or } \boxed{\frac{\partial \rho}{\partial t} + \nabla \cdot \rho \vec{u} - D \nabla^2 \rho = 0}$$

diffusion equation (set $\vec{u} = 0$)

$$\frac{\partial n}{\partial t} - D \nabla^2 n = 0$$

$$\text{if } n(t=0, \vec{x}) = N \delta(\vec{x}) \quad (\text{N particles at } \vec{x}=0)$$

in k-space

$$\frac{\partial \tilde{n}}{\partial t} + D k^2 \tilde{n} = 0$$

$$\tilde{n}(t, k) = e^{-D k^2 t}$$

$$\tilde{n}(t, \vec{x}) = \int \frac{d^3 k}{(2\pi)^3} e^{-D k^2 t} e^{i \vec{k} \cdot \vec{x}}$$

$$= \int \frac{d^3 k}{(2\pi)^3} e^{-D t \left(\vec{k} - \frac{i}{2} \frac{\vec{x}}{Dt} \right)^2} e^{-\frac{1}{4} \frac{\vec{x}^2}{Dt}}$$

$$\Rightarrow n(\vec{x}, t) = \frac{N}{(4\pi Dt)^{3/2}} e^{-\frac{|\vec{x}|^2}{4Dt}} \quad (*)$$

$$\langle x^2 \rangle = \int d^3x \frac{1}{x^2} \frac{e^{-|\vec{x}|^2/4Dt}}{(4\pi Dt)^{3/2}}$$

$$= 4Dt \times \frac{3}{2}$$

$$= 6Dt$$

$$\int dx e^{-x^2} = \sqrt{\pi}$$

$$\int dx x^2 e^{-x^2}$$

$$= \frac{1}{2} \sqrt{\pi}$$

$$\overline{x} \equiv \sqrt{\langle x^2 \rangle} = \sqrt{6Dt}$$

Random walk & diffusion

each step λ

N step later

$$\vec{x} = \Delta\vec{x}_1 + \Delta\vec{x}_2 + \dots$$

$$|\Delta\vec{x}_1| = |\Delta\vec{x}_2| = \dots = \lambda$$



Distribution of \vec{x}

$$n(\vec{x}, N) = \frac{1}{(\pi\alpha)^{3/2}} e^{-\frac{|\vec{x}|^2}{\alpha}} \quad \alpha = ?$$

$$\langle \vec{x}^2 \rangle = \Delta x_1^2 + \Delta x_2^2 + \dots$$

$$= N\lambda^2 \Rightarrow \overline{x} = \lambda\sqrt{N}$$

$$= \int d^3x \vec{x}^2 n = \frac{3}{2}\alpha \Rightarrow \alpha = \frac{2N\lambda^2}{3}$$

$$D = \frac{\lambda^2}{6\tau} = \frac{\lambda v}{6}$$

\Rightarrow see (*)

$$n(\vec{x}) = \frac{1}{(\pi \frac{2N\lambda^2}{3})^{3/2}} e^{-\frac{|\vec{x}|^2}{\frac{2N\lambda^2}{3}}} = \frac{e^{-\frac{|\vec{x}|^2}{\frac{2\lambda^2}{3\tau} t}}}{(\pi \frac{2\lambda^2}{3\tau} t)^{3/2}}$$

Damping of sound wave due to diffusion

Linearized:

$$\frac{\partial \delta p}{\partial t} + \rho_0 \nabla \cdot \vec{u} - D \nabla^2 \delta p = 0$$

$$\rho_0 \frac{\partial \vec{u}}{\partial t} + \nabla \delta p = 0$$

$$\frac{\partial^2 \delta p}{\partial t^2} + \rho_0 \nabla \cdot \frac{\partial \vec{u}}{\partial t} - D \nabla^2 \frac{\partial \delta p}{\partial t} = 0$$

$$\frac{\partial^2 \delta p}{\partial t^2} - c^2 \nabla^2 \delta p - D \nabla^2 \frac{\partial \delta p}{\partial t} = 0$$

$$\delta p = A e^{i(kx - \omega t)}$$

$$-\omega^2 + c^2 k^2 + D k^2 (-i\omega) = 0$$

small D

$$\omega^2 = c^2 k^2 - i D k^3 c = c^2 k^2 \left(1 - i \frac{Dk}{c}\right)$$

$$\omega = ck \left(1 - \frac{1}{2} i \frac{Dk}{c}\right)$$

$$\delta p = A e^{i(kx - ckt)} e^{-t/\tau}$$

$$\boxed{\tau = \frac{2}{Dk^2}} = \frac{12}{\lambda \sigma k^2} \sim \frac{1}{\omega} \frac{1}{\lambda k}$$

$\uparrow \sim c$

A sound wave can oscillate $\frac{1}{\lambda k}$ times

$$\frac{1}{\tau} = \frac{Dk^2}{2}$$

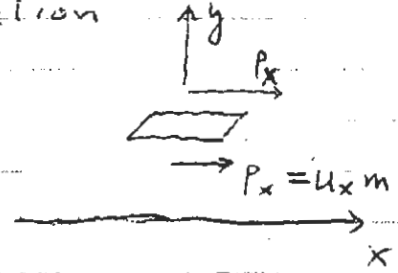
damping rate

damping coefficient

Viscosity — momentum conduction
(due to diffusion)

Flux of P_x momentum

= Force per area F_x



$$F_x = \frac{1}{6} n \bar{v} (u_{1x} m - u_{2x} m)$$

$$= -\frac{1}{6} n m \bar{v} \lambda \frac{\partial u_x}{\partial y}$$

$$F_x = -\nu \frac{\partial u_x}{\partial y} = \text{flux of } x \text{ momentum in } y \text{-direction}$$

$$\nu = \frac{1}{6} n \bar{v} m \lambda$$

$$= \frac{\sqrt{2mk_B T}}{3\sigma}$$

= Force in x -direction on a surface normal to y .

independent of n .

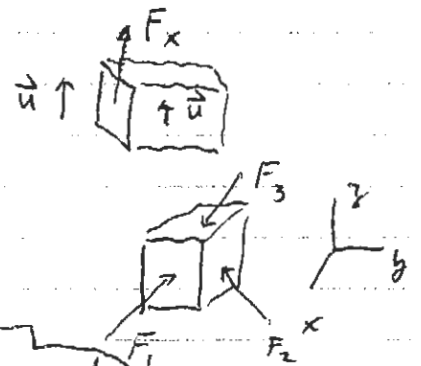
Pressure tensor P_{ij} :

$$\vec{F}_1 = (F_{1x}, F_{1y}, F_{1z}) = A(P_{11}, P_{12}, P_{13})$$

$$\vec{F}_2 = A(P_{21}, P_{22}, P_{23})$$

$$\vec{F}_3 = A(P_{31}, P_{32}, P_{33})$$

\vec{F}_i = force on surface normal to \hat{x}_i



$$P_{ij} = \underbrace{\delta_{ij} P}_{\text{usual pressure}} + \underbrace{P'_{ij}}_{\text{traceless part}} \quad \& \quad P'_{ij} = -\nu \left(\frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i} - \frac{2}{3} \delta_{ij} \nabla \cdot \vec{u} \right)$$

Navier - Stokes equation

$$\underbrace{\Delta V}_{\text{mass}} \rho \underbrace{\left(\frac{\partial}{\partial t} + \vec{u} \cdot \nabla \right)}_{\frac{d \cdot u_i}{dt}} u_i = \text{force in } i\text{-direction}$$

$$= + A \int_j (P_{ij}(x + \Delta x_j) + P_{ij}(x))$$

$$\Rightarrow \rho \left(\frac{\partial}{\partial t} + \vec{u} \cdot \nabla \right) u_i + \frac{\partial P_{ij}}{\partial x_j} = 0$$

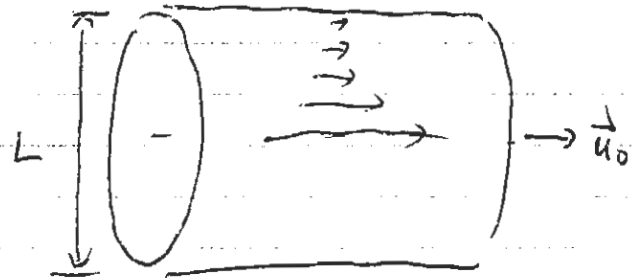
$$\Rightarrow \boxed{\rho \left(\frac{\partial}{\partial t} + \vec{u} \cdot \nabla \right) \vec{u} + \nabla \cdot \left(P - \frac{\nu}{3} \nabla \cdot \vec{u} \right) - \nu \nabla^2 \vec{u} = 0}$$

$\nu = \frac{\eta}{\rho}$

Any quantity can be set to 1 by changing the unit.

$$\boxed{\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \vec{u}) = 0}$$

$$\boxed{\left(\frac{\partial}{\partial t} + \vec{u} \cdot \nabla \right) (\rho \rho^{-\delta}) = 0}$$



The above three equations determine the flow in the pipe. quantities characters the effect of viscosity.

Inputs:

$$\boxed{u_0, L, \nu, \rho}$$

$$\boxed{R \gg 1 \text{ turbulent}}$$

$$\boxed{R \ll 1 \text{ streamline}}$$

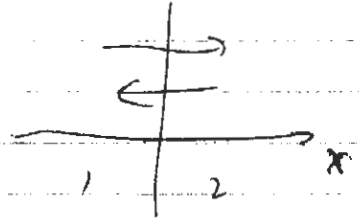
$$[\nu] = \frac{\text{force/area}}{\text{velocity/length}} = \frac{m \nu}{t L^2} \frac{L}{\nu} = \frac{m}{t L}$$

$$R = \frac{\rho L u_0}{\nu} \quad \text{dimensionless Reynolds number}$$

Heat conduction - energy exchange without particle exchange.

$$\vec{j}_x = \frac{1}{6} (n_1 \bar{v}_1 - n_2 \bar{v}_2) = 0$$

$$n_1 \approx n_2 \quad \bar{v}_1 \approx \bar{v}_2$$



$$\vec{j}_x = \frac{1}{6} n \bar{v} \left(l \frac{k_B T_1}{2} - l \frac{k_B T_2}{2} \right)$$

l number of degrees of freedom

$l = 3$ for point particles

$$T_1 - T_2 = -\partial_x T \lambda$$

λ mean free path.

$$\vec{j}_x = -\frac{1}{12} \lambda l n \bar{v} k_B \partial_x T$$

$$\boxed{\vec{j} = -K \nabla T}$$

$$K = \frac{l n \bar{v} k_B \lambda}{12}$$

$$= \frac{1}{6} n \bar{v} \lambda c_V$$

c_V specific heat
heat conductance per particle

$$c_V = \frac{l k_B}{2}$$

Using $\bar{v} = \sqrt{2k_B T/m}$

$$\lambda = 1/n\sigma$$

σ scattering cross-section

$$\boxed{K = \frac{c_V}{3} \frac{2k_B T}{m}}$$

independent of n

Energy conservation $\frac{\partial u}{\partial t} + \nabla \cdot \vec{j} = 0$

heat conductance equation

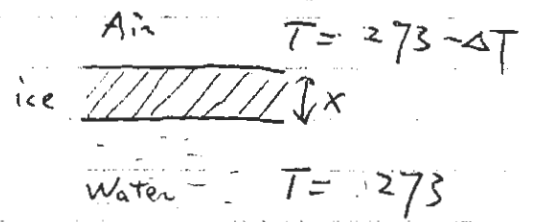
since $\vec{j} = -K \nabla T$ $u = n c_V T \Rightarrow$

with heat source

$$\boxed{W = \frac{1}{n c_V} \frac{\partial T}{\partial t} - K \nabla^2 T = 0}$$

$$\boxed{\frac{\partial T}{\partial t} - \frac{K}{n c_V} \nabla^2 T = 0}$$

* Speed of freezing



— heat transport per unit area
per unit time $q = K \frac{\Delta T}{x}$

— heat generated by freezing:

ΔS — change of entropy per atom

$l = \Delta S T$ — latent heat per atom.

heat generated per ^{unit} area per unit time

$$\frac{dx}{dt} n \cdot l = K \frac{\Delta T}{x}$$

\hat{L} number density

$$\Rightarrow \frac{dx}{dt} = \frac{K \Delta T}{n l} \frac{1}{x}$$

$$\Rightarrow x^2 = 2 \frac{K \Delta T}{n l} t \quad \text{or} \quad \boxed{x = \sqrt{\frac{2 K \Delta T}{n l} t}}$$

Numerical estimate

ΔS : Ideal gas $S = k_B \left(\frac{5}{2} + \ln \frac{V}{\lambda^3} \right)$ per atom

assume $V_{\text{water}} = 2 V_{\text{ice}} \Rightarrow \boxed{\Delta S = k_B}$

$$\boxed{l = k_B T_0}$$

$$C_V \sim k_B$$

$$K = \frac{C_V}{30 N} \sqrt{\frac{2 k_B T}{m}} = \frac{k_B}{\sigma} \sqrt{\frac{k_B T}{m}}$$

$$\sqrt{\frac{2 K \Delta T}{n l}} \sim \sqrt{\frac{\frac{k_B}{\sigma} \sqrt{\frac{k_B T}{m}} \Delta T}{n k_B T_0}} = \sqrt{\frac{\bar{v} \Delta T}{\sigma n T_0}}$$

a : lattice constant

$$a \sim 3 \text{ \AA} \quad \bar{v} = 300 \text{ m/s} \quad \sqrt{a \bar{v}} = 0.3 \text{ mm} \frac{1}{\sqrt{\text{sec}}}$$

$$\boxed{x = 0.3 \text{ mm} \sqrt{\frac{\Delta T}{T} \frac{t}{\text{sec}}}}$$

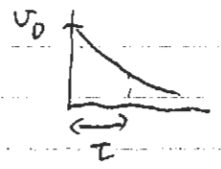
Transport in a metal

★ Drude model:

fraction with no collision
 $\Delta \langle u \rangle = (1 - \frac{\Delta t}{\tau}) \langle u \rangle + \frac{\Delta t}{\tau} \langle 0 \rangle$

average velocity
 $\frac{du}{dt} = -\frac{1}{\tau} u$
 collision

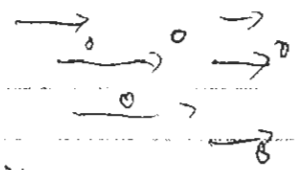
$u = u_0 e^{-t/\tau}$



with external electric field

τ a mean-free "time"
 $\tau = \lambda / \bar{v}$ from scattering with impurity

$\frac{du}{dt} = -\frac{1}{\tau} u + \frac{e}{m} E$



$j = enu$ - charge current density

$j + \tau \frac{dj}{dt} = \frac{e^2 n \tau}{m} E$

steady state

$\vec{j} = \sigma \vec{E}, \sigma = \frac{e^2 n \tau}{m}$

Ohm's law.

Temperature dependence of σ .

Only τ depend on T .

$\tau \sim \lambda / \bar{v}$

no T dependence
 impurity density
 is fixed

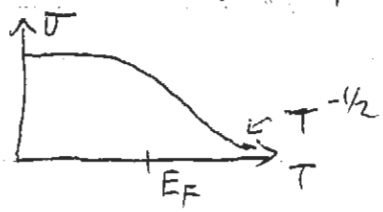
$\bar{v} \approx \sqrt{\frac{k_B T}{m}}$

$\bar{v} \approx \sqrt{\frac{E_F}{m}} \propto \frac{\hbar n^{1/3}}{m}$

$\sigma \propto T^0 \checkmark$

$\Rightarrow \tau \propto T^{-1/2}$

$\sigma \propto T^{-1/2} \times$



* Hall effect

$$\frac{d\vec{u}}{dt} = -\frac{1}{\tau} \vec{u} + \frac{e}{m} \vec{E} + \frac{e}{mc} \vec{u} \times \vec{B} \quad (\text{cgs})$$

$$\vec{j} = en\vec{u}$$

$$\frac{d\vec{j}}{dt} = -\frac{1}{\tau} \vec{j} + \frac{e^2 n}{m} \vec{E} + \frac{e}{mc} \vec{j} \times \vec{B}$$

steady flow

$$\vec{j} = \frac{e^2 n \tau}{m} \vec{E} + \frac{e \tau}{mc} \vec{j} \times \vec{B}$$

Let $\vec{B} = (0, 0, B)$ $\vec{j} \times \vec{B} = (j_y B, -j_x B, 0)$

$$j_z = \frac{e^2 n \tau}{m} E_z$$

$$\omega_c = \frac{eB}{mc}$$


$$\begin{pmatrix} j_x \\ j_y \end{pmatrix} = \underbrace{\sigma_0}_{\frac{e^2 n \tau}{m}} \begin{pmatrix} E_x \\ E_y \end{pmatrix} + \begin{pmatrix} 0 & \omega_c \tau \\ -\omega_c \tau & 0 \end{pmatrix} \begin{pmatrix} j_x \\ j_y \end{pmatrix} \quad \text{cyclotron frequency}$$

$$\begin{pmatrix} E_x \\ E_y \end{pmatrix} = \sigma_0^{-1} \begin{pmatrix} 1 & -\omega_c \tau \\ \omega_c \tau & 1 \end{pmatrix} \begin{pmatrix} j_x \\ j_y \end{pmatrix} = \begin{pmatrix} \rho_{xx} & \rho_{xy} \\ \rho_{yx} & \rho_{yy} \end{pmatrix} \begin{pmatrix} j_x \\ j_y \end{pmatrix}$$

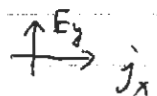
$$|\rho_{xy}| = |\rho_{yx}| = \frac{\omega_c \tau}{\sigma_0} = \frac{eB\tau}{mc} \frac{m}{e^2 n \tau} = \frac{B}{ec n}$$

$$|\rho_{xy}| = \frac{B}{enc} = R_H B$$

$$R_H = \frac{1}{enc}$$

meaning: if $\begin{pmatrix} j_x \\ j_y \end{pmatrix} = \begin{pmatrix} j_x \\ 0 \end{pmatrix}$ $\begin{pmatrix} E_x \\ E_y \end{pmatrix} = \begin{pmatrix} \rho_{xx} \\ \rho_{yx} \end{pmatrix} j_x$

$$E_y = \rho_{yx} j_x = R_H B j_x$$



Boltzmann equation (fluid in (\vec{x}, \vec{k}))

$$g(\vec{r}, \vec{k}, t) : dN = g(\vec{r}, \vec{k}, t) \frac{d^3\vec{r} d^3\vec{k}}{(2\pi)^3}$$

\hat{I}
 number of particle in $d^3\vec{r} d^3\vec{k}$
 number of particle in a \vec{k} level

Equilibrium distribution

$$g_0 = \frac{1}{e^{\beta(\epsilon_{\vec{k}} - \mu)} + 1} \quad \text{fermion}$$

$$g_0 = \frac{1}{e^{\beta(\epsilon_{\vec{k}} - \mu)} - 1} \quad \text{boson}$$

$$g_0 = e^{-\beta(\epsilon_{\vec{k}} - \mu)} \quad \text{classical gas}$$

If $g(\vec{r}, \vec{k}, t) \neq g_0$ non-equilibrium distribution

Diffusionless motion (hydrodynamic motion)

$$dN(t) = dN(t - dt)$$

$$g(\vec{r}, \vec{k}, t) \underbrace{d^3\vec{r}(t) d^3\vec{k}(t)}_{\substack{\text{Liouville's Theorem} \\ d^3\vec{r} d^3\vec{k}}} = g(\vec{r} - \vec{v}(t) dt, \vec{k} - \vec{F} \frac{dt}{\hbar}, t - dt) \times$$

$$\underbrace{d^3\vec{r}'(t-dt) d^3\vec{k}'(t-dt)}_{d^3\vec{r}' d^3\vec{k}'}$$

$$\text{Liouville's Theorem}$$

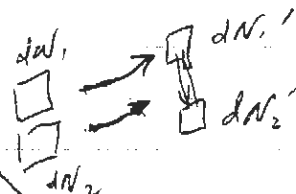
$$d^3\vec{r} d^3\vec{k} = d^3\vec{r}' d^3\vec{k}'$$

$$g(\vec{r}, \vec{k}, t) = g(\vec{r} - \vec{v}_k dt, \vec{k} - \vec{F} \frac{dt}{\hbar}, t - dt)$$

$$\frac{\partial g}{\partial t} + \vec{v} \cdot \frac{\partial g}{\partial \vec{r}} + \frac{1}{\hbar} \vec{F} \cdot \frac{\partial g}{\partial \vec{k}} = 0$$

no diffusion
(collision effect)

relaxation-time approximation



$$\frac{\partial g}{\partial t} + \vec{v} \cdot \frac{\partial g}{\partial \vec{r}} + \frac{1}{\hbar} \vec{F} \cdot \frac{\partial g}{\partial \vec{k}} = -\frac{1}{\tau} (g - g_0)$$

Let $\delta g = g - g_0$

Steady state:

$$\delta g = -\tau \vec{v} \cdot \frac{\partial g_0}{\partial \vec{r}} - \frac{\tau}{\hbar} \vec{F} \cdot \frac{\partial g_0}{\partial \vec{k}}$$

$$-\tau \vec{v} \cdot \frac{\partial \delta g}{\partial \vec{r}} - \frac{\tau}{\hbar} \vec{F} \cdot \frac{\partial \delta g}{\partial \vec{k}} \leftarrow O\left(\frac{\partial \delta g}{\partial \vec{r}}, \vec{F}\right)^2$$

Assume $\frac{\partial g_0}{\partial \vec{r}}$ and \vec{F} is small

$$\delta g = O\left(\frac{\partial g_0}{\partial \vec{r}}, \vec{F}\right)$$

$$\frac{\partial f}{\partial \vec{v}} = T \frac{\partial f}{\partial \epsilon} \frac{\partial \epsilon(\vec{v})}{\partial \vec{v}} = + \frac{\partial f}{\partial \epsilon} (-\nabla \mu - \frac{\epsilon - \mu}{T} \nabla T)$$

$$\delta g = -\tau \vec{v} \cdot \frac{\partial g_0}{\partial \vec{r}} - \frac{\tau}{\hbar} \vec{F} \cdot \frac{\partial g_0}{\partial \vec{k}}$$

$g_0(T(\vec{r}), \mu(\vec{r}), \vec{k})$ for fermion $g_0 = f = \frac{1}{e^{\beta(\epsilon - \mu)} + 1}$

For fermion $g_0 = f = \frac{1}{e^{\beta(\vec{r})} [e_{\vec{k}} - \mu(\vec{r})] + 1}$

$$\frac{\partial f}{\partial \vec{r}} = \frac{1}{\beta} \frac{\partial f}{\partial \epsilon} \frac{\partial [\beta(\epsilon - \mu)]}{\partial \vec{r}}$$

$$= T \frac{\partial f}{\partial \epsilon} \left(-\beta \frac{\partial \mu}{\partial \vec{r}} - \frac{\epsilon - \mu}{T^2} \frac{\partial T}{\partial \vec{r}} \right)$$

$$= -\frac{\partial f}{\partial \epsilon} \left(\nabla \mu + \frac{\epsilon - \mu}{T} \nabla T \right)$$

$$\frac{\partial f}{\partial \vec{k}} = \frac{\partial f}{\partial \epsilon} \frac{\partial \epsilon}{\partial \vec{k}}$$

$$= \hbar \vec{v}_{\vec{k}} \frac{\partial f}{\partial \epsilon}$$

$$\delta g_{(\vec{r}, \vec{k})} = \left(-\frac{\partial f}{\partial \epsilon} \right) \left[\hbar \vec{v}_{\vec{k}} \left(\nabla \mu + \frac{\epsilon - \mu}{T} \nabla T \right) + \vec{F} - \frac{\epsilon - \mu}{T} \nabla T \right]$$

$$\delta g_{(\vec{r}, \vec{k})} = \left(-\frac{\partial f}{\partial \epsilon} \right)_{(\vec{r}, \vec{k})} \left[\hbar \vec{v}_{\vec{k}} \left(-\nabla \mu(\vec{r}) + \vec{F}_{(\vec{r}, \vec{k})} - \frac{\epsilon_{\vec{k}} - \mu(\vec{r})}{T(\vec{r})} \nabla T \right) \right]$$

$$\vec{F}_{(\vec{r}, \vec{k})} = e \vec{E}(\vec{r}) + \frac{e}{c} \vec{v}_{(\vec{r}, \vec{k})} \times \vec{B}(\vec{r})$$

One we know $\vec{E}(\vec{r})$, $\vec{B}(\vec{r})$, $T(\vec{r})$, $\mu(\vec{r})$

we know $g_{(\vec{r}, \vec{k})} = g_0 + \delta g$

we can calculate anything

Also works for boson gas if we replace

$$f = \frac{1}{e^{\beta(\epsilon - \mu)} + 1} \quad \text{by} \quad f_b = \frac{1}{e^{\beta(\epsilon - \mu)} - 1}$$

$$\text{or classical gas by } f_c = \frac{1}{e^{\beta(\epsilon - \mu)}}$$

Application: electric current

$$\vec{B} = 0$$

$$\vec{g} = \vec{g}_0 + \tau \left(-\frac{\partial f}{\partial \epsilon} \right) \vec{v}_k \cdot \left[+e\vec{E} + \frac{\epsilon - \mu}{T} (-\nabla T) \right]$$

$$\vec{E} \equiv \vec{E} - \frac{\nabla \mu}{e} \quad \delta g$$

electric current

$$\vec{j}_x = \int \frac{d^3k}{(2\pi)^3} e v_x(\vec{k}) \vec{g}(\vec{k}) = \int \frac{d^3k}{(2\pi)^3} e v_x \delta g$$

$$= \int \frac{d^3k}{(2\pi)^3} \tau e^2 \left(-\frac{\partial f}{\partial \epsilon} \right) v_x \vec{v} \cdot \vec{E}$$

$$+ \int \frac{d^3k}{(2\pi)^3} e \tau \left(-\frac{\partial f}{\partial \epsilon} \right) \frac{\epsilon - \mu}{T} v_x \vec{v} \cdot (-\nabla T)$$

$$= L^{11} E_x + L^{12} (-\partial_x T)$$

$$d^3k = 4\pi k^2 dk$$

$$= 2\pi k dk^2$$

$$= 2\pi k \frac{2m}{\hbar^2} d\epsilon$$

$$L^{11} = \int \frac{d^3k}{(2\pi)^3} \tau e^2 \left(-\frac{\partial f}{\partial \epsilon} \right) v_x^2$$

$$\int d\epsilon \left(-\frac{\partial f}{\partial \epsilon} \right) = 1$$

$$= \frac{1}{3} \int \frac{d^3k}{(2\pi)^3} \tau e^2 \left(-\frac{\partial f}{\partial \epsilon} \right) v^2$$

$$= \frac{1}{3} \frac{1}{(2\pi)^3} 2\pi k_F \frac{2m}{\hbar^2} \tau e^2 v_F^2$$

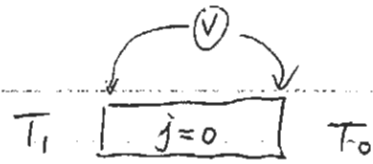
$$= \frac{1}{3} \frac{1}{(2\pi)^3} \frac{4\pi}{m} \tau e^2 k_F^3$$

$$n = \frac{4}{3} \pi k_F^3 \frac{1}{(2\pi)^3}$$

$$= \frac{e^2 \tau n}{m}$$

(result of Drude model) ✓

Thermopower.



$$\vec{E} = Q \nabla T \quad (\vec{j} = 0)$$

$$Q = \frac{L^{12}}{L^{11}}$$



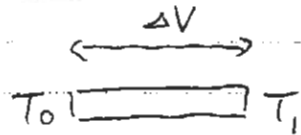
$$\sim \frac{n^{1/3} e \pi^2 k_B^2 T}{\hbar^2} / \frac{e^2 \pi n}{m}$$

inter electron spacing

$$= \frac{k_B}{e} \left(\frac{m k_B T}{n^{2/3} \hbar^2} \right) \sim \frac{k_B}{e} \frac{1}{(n^{1/3} \lambda_T)^2} \sim \frac{k_B}{e} \left(\frac{\ell}{\lambda_T} \right)^2$$

$$\text{Let } Q = Q_0 \frac{k_B}{e}$$

$$eL E = Q_0 k_B (T_1 - T_0)$$



$$1 \text{ eV} \sim 1160 \text{ K}$$

$$E = \frac{1}{1160} Q_0 (\nabla \cdot T) \frac{\text{Kelvin}}{\text{meter}} \left(\frac{\text{Volts}}{\text{meter}} \right)$$

Einstein relation:

One particle in a gas in $V = \frac{1}{2} K x^2$ potential

Boltzmann distribution

$$P(x) = \cdot e^{-\frac{\beta}{2} K x^2}$$



$$\langle \frac{1}{2} K x^2 \rangle = \frac{1}{2} k_B T \Rightarrow \langle x^2 \rangle = \frac{k_B T}{K}$$

$\langle x^2 \rangle$ from point view of diffusion

When $V=0$,

Prob. distribution $P(x,t)$ satisfies diffusion equation

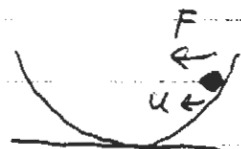
$$\frac{\partial P}{\partial t} - D \frac{\partial^2 P}{\partial x^2} = 0$$

$$\langle x^2 \rangle = 2Dt \quad (\text{in 1D})$$

\uparrow diffusion const.

$$\langle x^2 \rangle = 2dDt \quad (\text{in } d\text{-dimensions})$$

$= Nt \lambda_0 \leftarrow$ step length.
 \uparrow # of steps



When $V \neq 0$, particle experience a force

F . F induces a drift

$$u = \eta F$$

\uparrow mobility

drift make $\langle x^2 \rangle$ finite

in $t \rightarrow \infty$ limit

We require $\langle x^2 \rangle = \frac{k_B T}{K}$

$$\Rightarrow \text{friction } \eta \text{ related to diffusion } D$$

Diffusion with Force.

$$(n_0 = NP_{(w)})$$

$$\vec{j} = n\vec{u} - D\nabla n$$

Diffusion equation: from $\frac{\partial n}{\partial t} + \nabla \cdot \vec{j} = 0$

$$\vec{u} = \eta \vec{F}$$

$$\Rightarrow \boxed{\frac{\partial n}{\partial t} + \eta \nabla \cdot (\vec{F} n) - D \nabla^2 n = 0}$$

Steady state (equilibrium state)

$$\frac{\partial n}{\partial t} = 0$$

$$\eta \nabla \cdot (\vec{F} n) - D \nabla^2 n = 0$$

$$\text{or } \eta \vec{F} n = D \nabla n$$

$$\text{if } \vec{F} = -\nabla V \Rightarrow \begin{aligned} D \nabla n &= -\eta n \nabla V \\ \nabla \ln n &= -\frac{\eta}{D} \nabla V \end{aligned}$$

In equilibrium, we should have

$$n \propto e^{-\beta V} \Rightarrow \nabla \ln n = -\beta \nabla V$$

$$\Rightarrow \frac{\eta}{D} = \beta \quad \text{or} \quad \boxed{D = \eta k_B T} \quad \text{Einstein relation}$$

fluctuation \leftrightarrow dissipation (diffusion \leftrightarrow friction)

$$\uparrow$$

$$\boxed{\langle x^2 \rangle = 2dDt}$$

$$\uparrow$$

$$\boxed{D = \eta k_B T}$$

$$D$$

$$\boxed{\frac{\partial n}{\partial t} - D \nabla^2 n = 0}$$

$$\eta$$

$$\boxed{\vec{u} = \eta \vec{F}}$$

Random walk of particle in water
viscosity of H₂O at 20°C:

$$\eta = 0.01 \text{ Poise (dyne}\cdot\text{sec/cm}^2)$$

$$\eta = \text{Pressure} / \frac{du}{dx} = \text{dyne/cm}^2 / \frac{\text{cm}}{\text{sec/cm}} = (\text{dyne}\cdot\text{cm}^2) \cdot \text{sec}$$

$$\vec{F} = ?$$

$$F = p \cdot a^2$$

$$= a^2 \cdot \eta \cdot \frac{du}{dx} = a^2 \eta \frac{u}{a} = a \eta u$$



valid only when
 $a \gg \lambda$

$$\vec{F} = \frac{6\eta}{18} a \eta u \Rightarrow \eta = (6\pi a \eta)^{-1}$$

Einstein's relation

$$D = k_B T \eta$$

$$\langle \vec{x}^2 \rangle = 6Dt = \frac{6k_B T \eta t}{\pi a \eta}$$

$$k_B = \frac{\langle \vec{x}^2 \rangle \pi a \eta}{T t}$$

$$R = k_B N_A$$

Avogadro's number

$$\sqrt{\langle \vec{x}^2 \rangle} = 8.9 \mu\text{m} \sqrt{\frac{t}{1 \text{ min}} / \left(\frac{a}{1 \mu\text{m}}\right)} \quad \text{in water}$$

For gas $\eta \sim \frac{\bar{p}}{\sigma}$ ← average momentum $\eta = \frac{2mk_B T}{3\sigma}$
 σ ← scattering cross section

$$\langle \vec{x}^2 \rangle \sim \frac{k_B T t}{a \bar{p}/\sigma} = \frac{\sigma k_B T}{a \bar{p}} t$$

$$= \frac{\sigma \bar{v}}{a} t = \sigma \frac{\bar{v} t}{a}$$

Langevin equation - Dynamics in random walk.

$$\frac{dU}{dt} = \frac{F_{ex}}{m} + \frac{F'}{m}$$

I collision force

but $\frac{d\langle U \rangle}{dt} = \frac{F_{ex}}{m}$ if $\langle F' \rangle = 0$

no friction $\Rightarrow \langle F' \rangle = -\gamma U$ ↖ damping coeff

$$\frac{dU}{dt} + \gamma U = \frac{F_{ex}}{m} + \frac{\tilde{F}}{m} \quad \langle \tilde{F} \rangle = 0$$

steady state $\langle U \rangle = \frac{1}{m\gamma} F_{ex}$
 describe the true motion of $\frac{1}{m\gamma} = \eta$ mobility
 Brownian particle.

$$\langle x^2 \rangle: \quad x \frac{dx}{dt} + \gamma x \frac{dx}{dt} \pm \frac{\tilde{F}}{m} x \quad (\text{Let } F_{ex} = 0)$$

$$\langle x \frac{d^2x}{dt^2} + \gamma x \frac{dx}{dt} \rangle = 0 \quad \langle \tilde{F} x \rangle = 0$$

$$\int \frac{d}{dt} x \frac{dx}{dt} - \left(\frac{dx}{dt} \right)^2 = \frac{1}{2} \frac{d^2}{dt^2} x^2 - \left(\frac{dx}{dt} \right)^2$$

$$\frac{1}{2} \frac{d^2}{dt^2} \langle x^2 \rangle + \frac{1}{2} \gamma \frac{d\langle x^2 \rangle}{dt} - \langle \left(\frac{dx}{dt} \right)^2 \rangle = 0$$

Let $Y = \langle x^2 \rangle$ ↖ $\frac{k_B T}{2}$
m/2

$$\frac{d^2}{dt^2} Y = - \gamma \frac{dY}{dt} + 2 \frac{k_B T}{m}$$

I "mass" I "friction" I "Force"

$t \rightarrow \infty$ $\gamma \frac{dY}{dt} = 2 \frac{k_B T}{m}$

$$D = \frac{k_B T}{m\gamma} = k_B T \eta$$

$$Y = \langle x^2 \rangle = \frac{2 k_B T}{m\gamma} t = 2 D t$$

In general

$$\langle x^2 \rangle = A + B e^{-\gamma t} + \frac{2k_B T}{m\gamma} t$$

at $t=0$

$$\langle x \rangle = 0$$

$$\langle x^2 \rangle = \gamma t^2$$

$$\frac{d\langle x^2 \rangle}{dt} = \langle x^2 \rangle = 0 \quad | \quad t=0$$

$$A + B = 0$$

$$A - \gamma B + \frac{2k_B T}{m\gamma} = 0$$

$$\langle x^2 \rangle = \frac{2k_B T}{m\gamma} \left[t - \gamma^{-1} (1 - e^{-\gamma t}) \right]$$

$$= 2k_B T \eta \left[\underbrace{t}_{\substack{\uparrow \\ \text{random} \\ \text{walk}}} - \underbrace{m\eta (1 - e^{-t/m\eta})}_{\substack{\uparrow \\ \text{crossover}}} \right]$$

$$t \Rightarrow \infty : \langle x^2 \rangle = 2k_B T \eta t - m\eta$$

$$t \Rightarrow 0 : \langle x^2 \rangle = 2k_B T \eta \cdot \frac{1}{2} \frac{1}{(m\eta)^2} t^2$$

$$= \frac{k_B T}{m} t^2$$

$$\frac{1}{2} m v^2 = \frac{1}{2} k_B T$$

$\langle v^2 \rangle :$

$$v \frac{dv}{dt} + \gamma v^2 = \frac{v \tilde{F}}{m}$$

$$\frac{1}{2} \frac{d\langle v^2 \rangle}{dt} + \gamma \langle v^2 \rangle = \frac{\langle v \tilde{F} \rangle}{m}$$

$$\langle v \tilde{F} \rangle \neq 0$$

\hat{L} generated by \tilde{F}

$$\text{from } \frac{dv}{dt} + \gamma v = \frac{\tilde{F}}{m} \Rightarrow$$

$$v = v_0 e^{-\gamma t} + \int_{-\infty}^t e^{-\gamma(t-t')} \frac{\tilde{F}(t')}{m} dt'$$

$$\frac{dv}{dt} = -\gamma v_0 e^{-\gamma t} + \frac{\tilde{F}(t)}{m} - \gamma \int_{-\infty}^t e^{-\gamma(t-t')} \frac{\tilde{F}(t')}{m} dt'$$

$$\langle v \tilde{F} \rangle = \frac{1}{m} \int_{-\infty}^t \langle \tilde{F}(t) \tilde{F}(t') \rangle e^{-\gamma(t-t')} dt'$$

$$= \frac{1}{m} \int_0^{\infty} K(s) e^{-\gamma s} ds$$

$$K(s) = \langle F(t+s) F(t) \rangle$$

$$\frac{1}{2} \frac{d}{dt} \langle v^2 \rangle + \gamma \langle v^2 \rangle = \frac{1}{m^2} K_\gamma$$

$$K_\gamma = \int_0^\infty K(s) e^{-\gamma s} ds$$

$$\langle v^2 \rangle = A e^{-2\gamma t} + \frac{1}{m\gamma} K_\gamma$$

at $t \rightarrow \infty$ $\langle v^2 \rangle = \frac{1}{m\gamma} K_\gamma$ random force generate fluctuations of v
 $= \frac{k_B T}{m}$

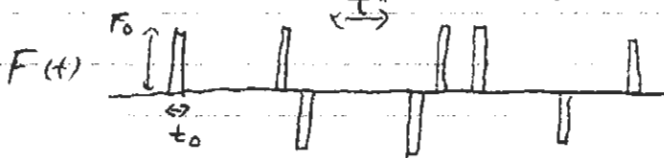
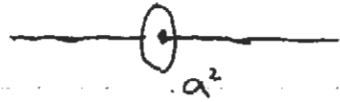
$$\Rightarrow m\gamma = \frac{1}{k_B T} K_\gamma$$

Correlation of random force determine the friction

$$\frac{1}{\eta} = \frac{1}{k_B T} \int_0^\infty \langle F(s) F(0) \rangle e^{-t/\eta m} ds$$

friction coeff $F = \eta v$

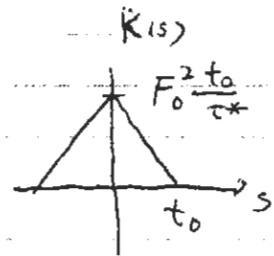
Friction of a disk in gas



$$\langle F(s) F(0) \rangle = 0 \quad \text{if } s > t_0$$

$$\langle F(0) F(0) \rangle = F_0^2 \frac{t_0}{\tau^*}$$

assume $t_0 \ll m\gamma = \tau$ relaxation time

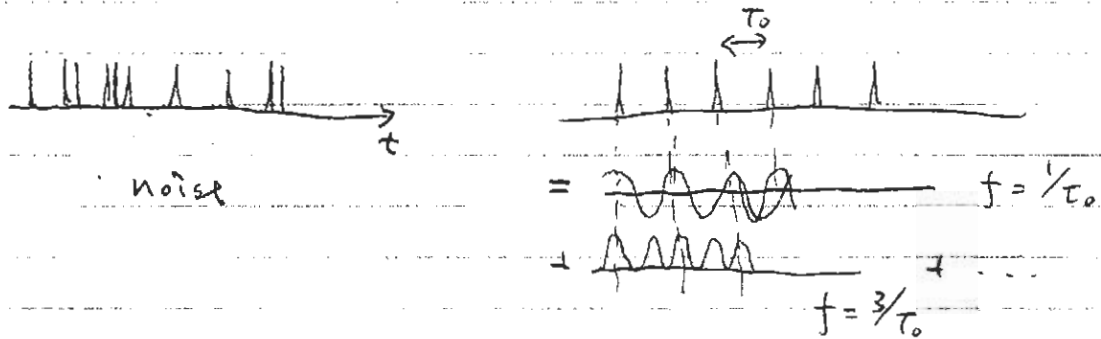


$$\int_0^\infty K(s) e^{-t/\eta m} ds = \frac{F_0^2 t_0^2}{2\tau^*} = \frac{(2m\bar{v}_x)^2}{2\tau^*} = \frac{2m k_B T}{\tau^*}$$

$$\frac{1}{\eta} = \frac{2m}{\tau^*} \approx 2m n a^2 \bar{v} \quad \text{valid if } a \ll \lambda \quad \tau^* \sim 1/n a^2 \bar{v}$$

hydro-dynamics: $\frac{1}{\eta} = 6\pi \eta a = \pi n m \bar{v} a \lambda \quad a^2 \leftrightarrow a \lambda$
 $\propto \frac{1}{6} n \bar{v} m \lambda \quad \text{if } a \gg \lambda$

Noise and Noise spectrum



Power P & amplitude A

$$P \propto A^2$$

Light $P \propto E^2$



$$P = \frac{V^2}{R}$$

Total energy:

$$E = \int_0^{t_0} dt A^2(t)$$

$$A(\omega) = \int dt A(t) e^{i\omega t}$$

$$A(t) = \int \frac{d\omega}{2\pi} A(\omega) e^{-i\omega t}$$

$$= \int \frac{d\omega}{2\pi} A(\omega) A(-\omega)$$

$$= \int_{-\infty}^{\infty} \frac{d\omega}{2\pi} |A(\omega)|^2 = \int_0^{\infty} \frac{d\omega}{\pi} |A(\omega)|^2$$

Total energy in $[\omega, \omega + d\omega]$ $\frac{d\omega}{2\pi} |A(\omega)|^2$

Power in $[\omega, \omega + d\omega] = \frac{|A(\omega)|^2}{\pi t_0} d\omega$

$$\frac{|A(\omega)|^2}{\pi t_0} = \text{Power spectrum}$$

How to calculate $\frac{|A(\omega)|^2}{\pi t_\infty}$?

① $A(\omega) = \int dt A(t) e^{i\omega t}$ but $A(t)$ random

② $\left\langle \frac{|A(\omega)|^2}{\pi t_\infty} \right\rangle = \frac{1}{\pi t_\infty} \left\langle \int dt A(t) e^{i\omega t} \int dt' A(t') e^{-i\omega t'} \right\rangle$

$$= \frac{1}{\pi t_\infty} \int dt dt' \underbrace{\langle A(t) A(t') \rangle}_{\equiv G(t-t')} e^{i\omega(t-t')}$$

$$= \frac{1}{\pi t_\infty} \int dt d\tilde{t} G(\tilde{t}) e^{i\omega \tilde{t}}$$

$$= \frac{1}{\pi} \int_{-\infty}^{\infty} d\tilde{t} G(\tilde{t}) e^{i\omega \tilde{t}} = \frac{S(\omega)}{\pi}$$

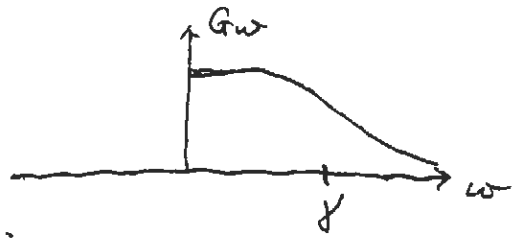
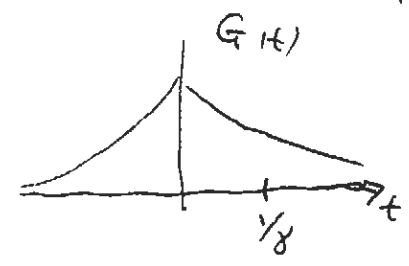
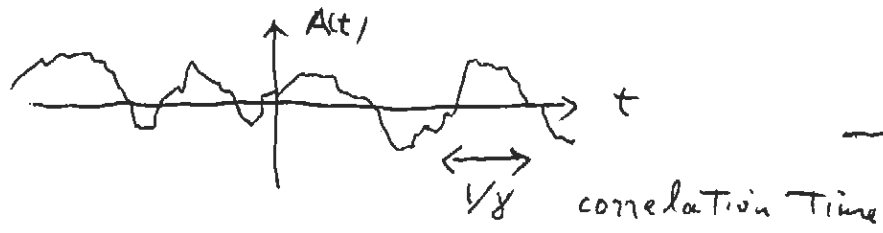
$$\text{Power spectrum} = \left\langle \frac{|A(\omega)|^2}{\pi t_\infty} \right\rangle = \frac{1}{\pi} \int dt G(t) e^{i\omega t} = \frac{S(\omega)}{\pi}$$

$$G(t) = \langle A(t) A(0) \rangle \quad \text{correlation function}$$

$$S(\omega) = \int dt G(t) e^{i\omega t}$$

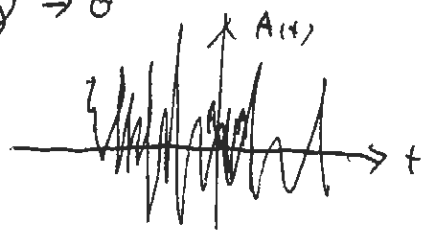
Assume $G(t) = c e^{-\gamma|t|}$

$$S(\omega) = \frac{c \gamma / \pi}{\omega^2 + \gamma^2}$$



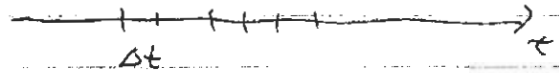
White noise $1/\gamma \rightarrow 0$

$$S(\omega) = \text{const.}$$



$A(t)$ and $A(t+\Delta t)$ have no correlation.

Shot noise



$$I_i = \frac{e}{\Delta t} s_i$$

$$P(s_i = 1) = p$$

$$P(s_i = 0) = (1-p)$$

$$\langle I_i I_j \rangle = \begin{cases} \left(\frac{pe}{\Delta t}\right)^2 & \text{if } i \neq j \\ \left(\frac{e}{\Delta t}\right)^2 p & \text{if } i = j \end{cases}$$

$$= \begin{cases} I^2 & \text{if } i \neq j \\ \frac{e}{\Delta t} I & \text{if } i = j \end{cases}$$

Note that $\sum_i \langle I_i I_j \rangle = I^2 = \frac{e}{\Delta t} I$

$$\Rightarrow \int dt \langle I(t) I(0) \rangle = e I$$

$$\langle I(t) I(0) \rangle = I^2 + e I \delta(t) \equiv G(t)$$

$$\text{Power spectrum} = \left\langle \frac{|I(\omega)|^2}{\pi t_{\infty}} \right\rangle$$

$$= \frac{S(\omega)}{\pi}$$

$$S(\omega) = \int dt G(t) e^{i\omega t} = I^2 (2\pi) \delta(\omega) + e I$$

$$\text{Power spectrum} = 2 I^2 \delta(\omega) + \left(\frac{e I}{\pi}\right)$$

ind. of ω
depend on e !

Shot noise

Noise spectrum in Brownian motion

Langevin equation:

$$\frac{dU}{dt} + \gamma U = \frac{F(t)}{m} \quad \leftarrow \text{random} \quad \langle F(t) \rangle = 0$$

In ω -space

$$-i U_{\omega} + \gamma U_{\omega} = \frac{F_{\omega}}{m}$$

$$U_{\omega} = \frac{F_{\omega}}{m(\gamma - i\omega)}$$

Now consider

$$\begin{aligned} \langle U_{\omega} U_{-\omega} \rangle &= \int dt_1 dt_2 \langle U(t_1) U(t_2) \rangle e^{i\omega(t_1 - t_2)} \\ &= t_0 \int d\tau \langle U(\tau) U(0) \rangle e^{-i\omega\tau} \end{aligned}$$

Similarly

$$\langle F_{\omega} F_{-\omega} \rangle = t_0 \int d\tau \langle F(\tau) F(0) \rangle e^{i\omega\tau}$$

Noise spectrum

$$\begin{aligned} \frac{S(\omega)}{\pi} &= \frac{1}{\pi} \frac{\langle U_{\omega} U_{-\omega} \rangle}{t_0} \\ &= \frac{1}{\pi} \frac{1}{m^2(\gamma^2 + \omega^2)} \frac{\langle F_{\omega} F_{-\omega} \rangle}{t_0} \end{aligned}$$

$$\boxed{\frac{S(\omega)}{\pi} = \frac{1}{\pi} \frac{1}{m^2(\gamma^2 + \omega^2)} \int d\tau \langle F(\tau) F(0) \rangle e^{i\omega\tau}}$$

$$\text{Let } K(\omega) = \int d\tau \langle F(\tau) F(0) \rangle e^{i\omega\tau}$$

$$\boxed{\frac{S(\omega)}{\pi} = \frac{1}{\pi} \frac{K(\omega)}{m^2(\gamma^2 + \omega^2)}}$$

$$\text{Let } \langle F(t_1) F(t_2) \rangle = 2\pi K \delta(t_1 - t_2)$$

$$K(\omega) = 2\pi K$$

$$\boxed{\frac{S(\omega)}{\pi} = \frac{2K}{m^2(\gamma^2 + \omega^2)}}$$

see page 119

$$m\gamma = \frac{1}{k_B T} K_\gamma$$

$$K_\gamma = \int_0^\infty dt \langle F(t) F(0) \rangle e^{-\gamma t}$$

$$= \frac{1}{k_B T} \pi K$$

$$= \pi K_0$$

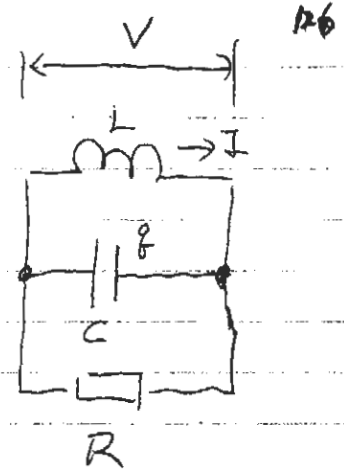
power spectrum of $v(t)$

$$P_{(v)}^\omega = \boxed{\frac{S(\omega)}{\pi} = \frac{2k_B T m \gamma}{\pi m^2(\gamma^2 + \omega^2)} = \frac{2k_B T \cdot \gamma}{\pi m(\gamma^2 + \omega^2)}}$$

$$\langle v_{(t)}^2 \rangle = \int_{-\infty}^{\infty} \frac{d\omega}{2\pi} \frac{\langle v_\omega v_{-\omega} \rangle}{\omega} = \int_{-\infty}^{\infty} d\omega \frac{k_B T \gamma}{\pi m(\gamma^2 + \omega^2)} = \frac{k_B T}{m} \quad \checkmark$$

Power spectrum of velocity is determined
by friction γ and mass m (and temperature T)

Noise in RCL circuit



$$V = \frac{q}{C} = L \frac{dI}{dt}$$

$$I = -\frac{dq}{dt} - \frac{V}{R}$$

Let $x = LI$

$$\frac{1}{C} \frac{dq}{dt} = \frac{d^2x}{dt^2} = \frac{1}{C} (-I - \frac{V}{R})$$

$$\Rightarrow \boxed{C \frac{d^2x}{dt^2} = -\frac{x}{L} - \frac{1}{R} \frac{dx}{dt}}$$

total energy of the system

$$E = \frac{1}{2} LI^2 + \frac{1}{2} CV^2$$

$$= \frac{1}{2} \frac{1}{L} x^2 + \frac{1}{2} C \dot{x}^2$$

RCL circuit = particle of mass $C (=m)$ in $\frac{1}{2L} x^2$ potential

Friction coefficient $\gamma m = \frac{1}{R}$ or $\boxed{\gamma = \frac{1}{RC}}$

Let $L = \infty$:

power spectrum of $V (= \dot{x})$

$$P^V(\omega) = \frac{2k_B T \frac{1}{RC}}{\pi C \left[\left(\frac{1}{RC} \right)^2 + \omega^2 \right]} = \frac{2k_B T R}{\pi (1 + \omega^2 R^2 C^2)}$$

$$P^V(f) = 2\pi P^V(\omega) = 4k_B T R / (1 + \omega^2 R^2 C^2) = 4k_B T R \quad | \quad C=0$$