

Class 26: Outline

Hour 1:

Driven Harmonic Motion (RLC)

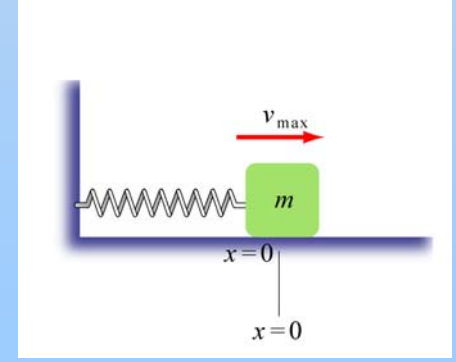
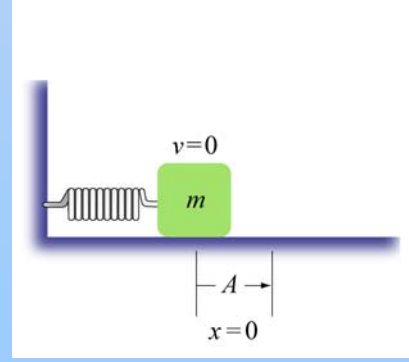
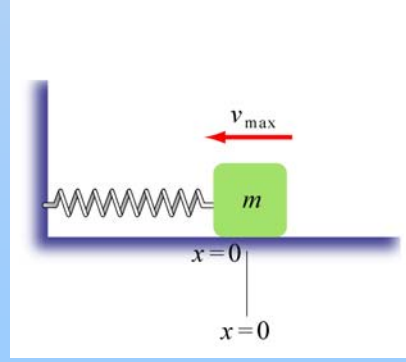
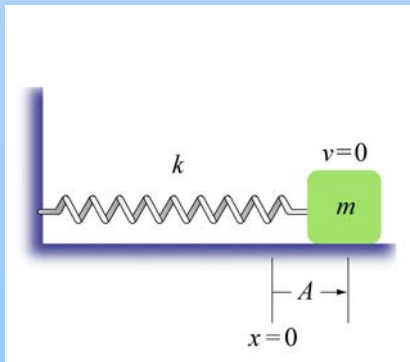
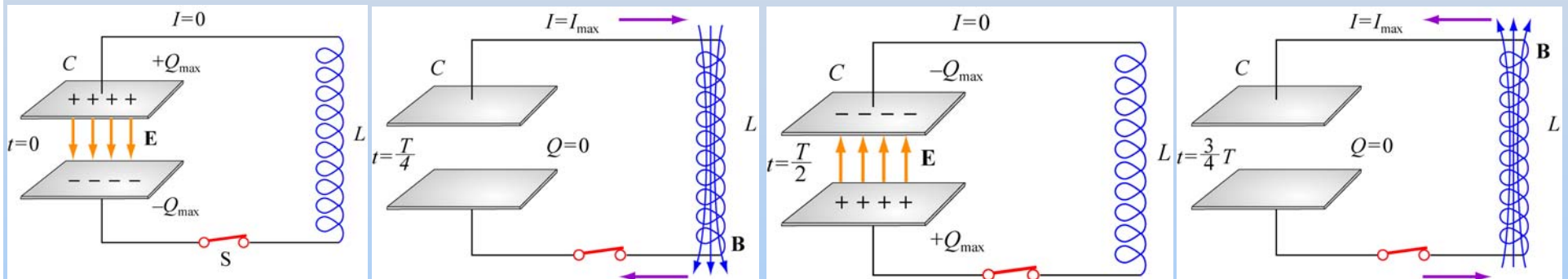
Hour 2:

Experiment 11: Driven RLC Circuit

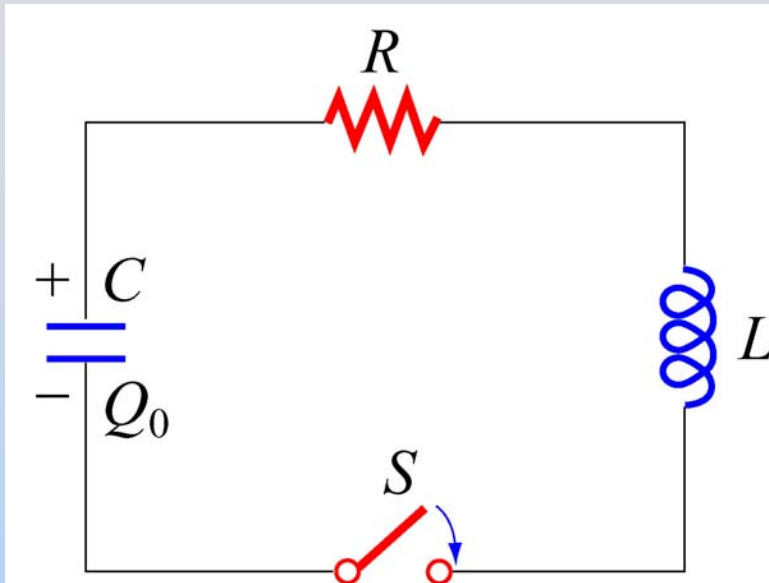
Last Time: Undriven RLC Circuits

LC Circuit

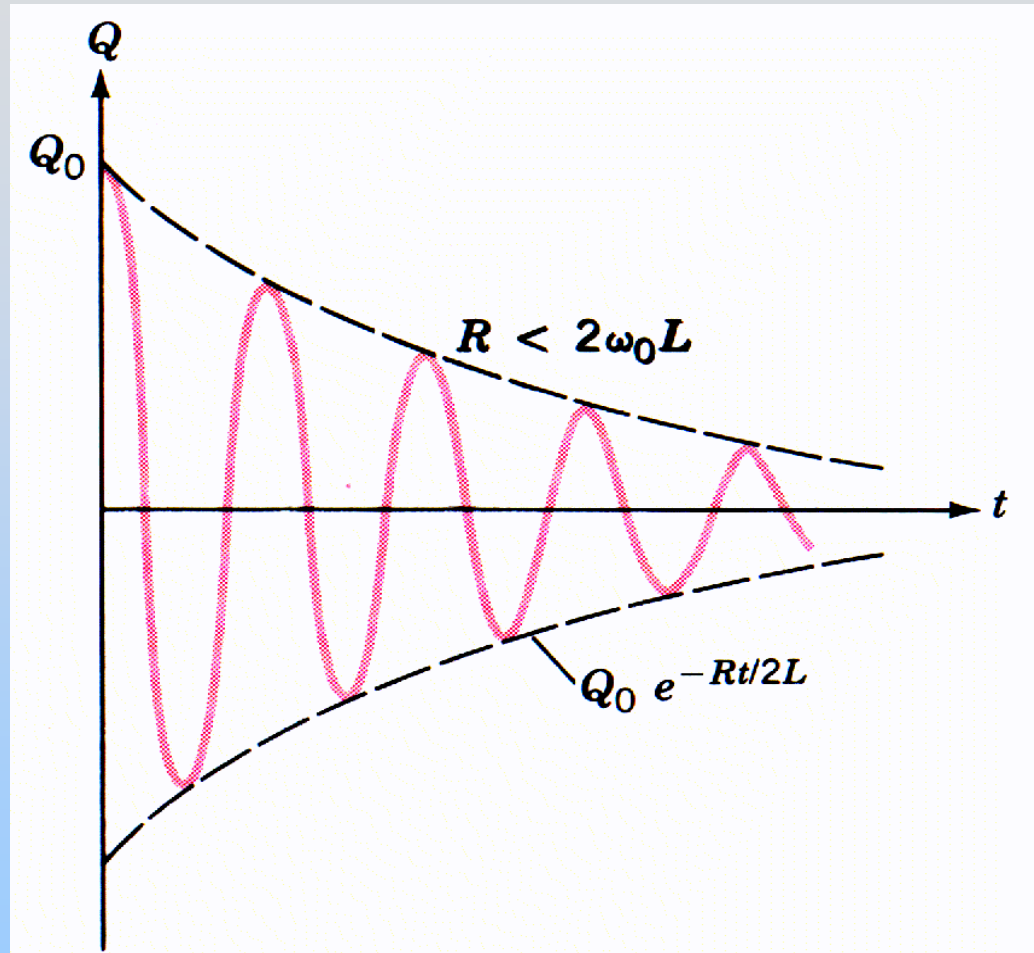
It undergoes simple harmonic motion, just like a mass on a spring, with trade-off between charge on capacitor (Spring) and current in inductor (Mass)



Damped LC Oscillations



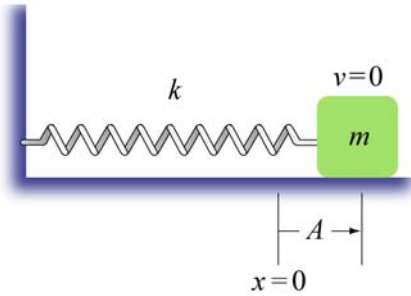
Resistor dissipates energy and system rings down over time



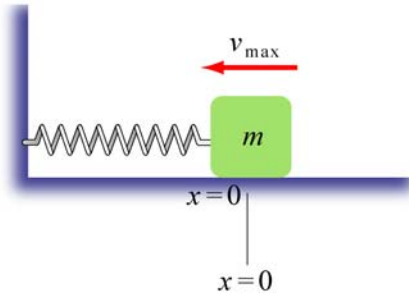
Mass on a Spring: Simple Harmonic Motion` A Second Look

Mass on a Spring

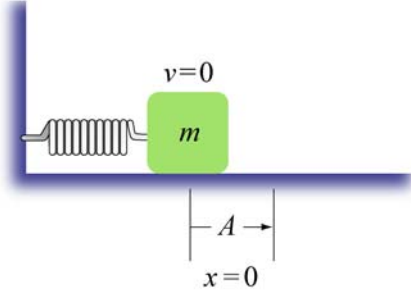
(1)



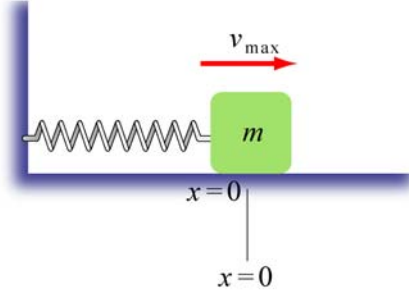
(2)



(3)



(4)



We solved this:

$$F = -kx = ma = m \frac{d^2 x}{dt^2}$$

$$m \frac{d^2 x}{dt^2} + kx = 0$$

Simple Harmonic Motion

$$x(t) = x_0 \cos(\omega_0 t + \phi)$$

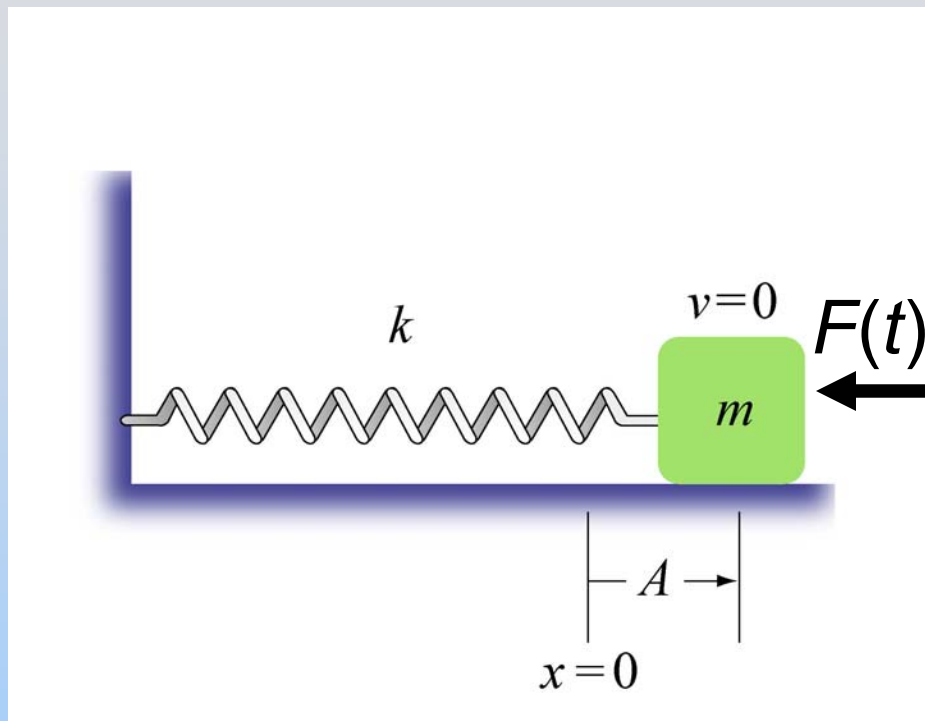
Moves at natural frequency

What if we now move the wall?

Push on the mass?

Demonstration: Driven Mass on a Spring Off Resonance

Driven Mass on a Spring



Now we get:

$$F = F(t) - kx = ma = m \frac{d^2 x}{dt^2}$$

$$m \frac{d^2 x}{dt^2} + kx = F(t)$$

Assume harmonic force:

$$F(t) = F_0 \cos(\omega t)$$

Simple Harmonic Motion

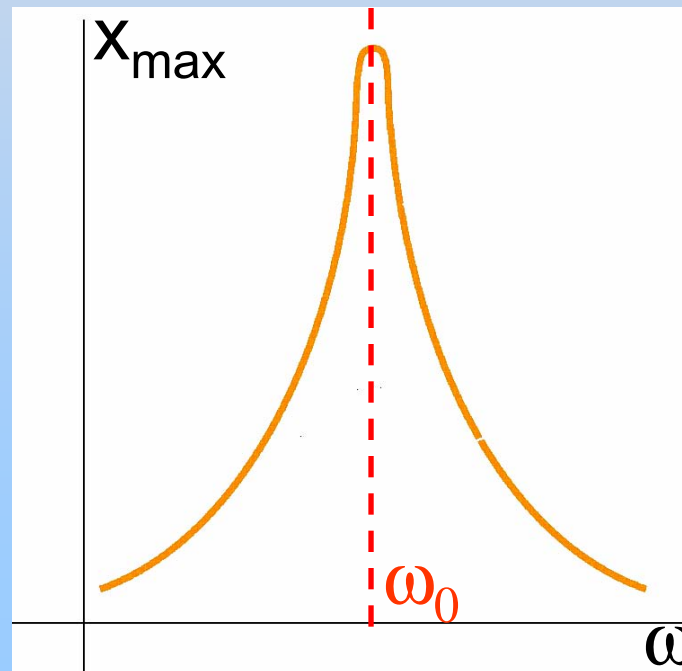
$$x(t) = x_{\max} \cos(\omega t + \phi)$$

Moves at driven frequency

Resonance

$$x(t) = x_{\max} \cos(\omega t + \phi)$$

Now the amplitude, x_{\max} , depends on how close the drive frequency is to the natural frequency



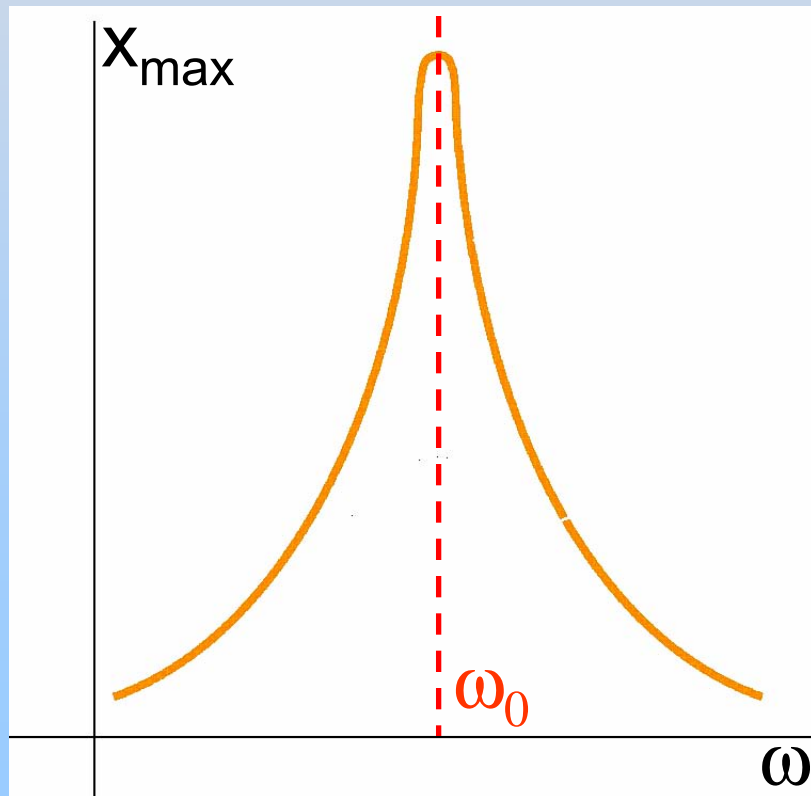
Let's
See...

Demonstration: Driven Mass on a Spring

Resonance

$$x(t) = x_{\max} \cos(\omega t + \phi)$$

x_{\max} depends on drive frequency



Many systems behave like this:

Swings

Some cars

Musical Instruments

...

Electronic Analog: RLC Circuits

Analog: RLC Circuit

Recall:

Inductors are like masses (have inertia)

Capacitors are like springs (store/release energy)

Batteries supply external force (EMF)

Charge on capacitor is like position,

Current is like velocity – watch them resonate

Now we move to “frequency dependent batteries:”

AC Power Supplies/AC Function Generators

Demonstration: RLC with Light Bulb

Start at Beginning: AC Circuits

Alternating-Current Circuit

- direct current (dc) – current flows one way (battery)
- alternating current (ac) – current oscillates

- sinusoidal voltage source

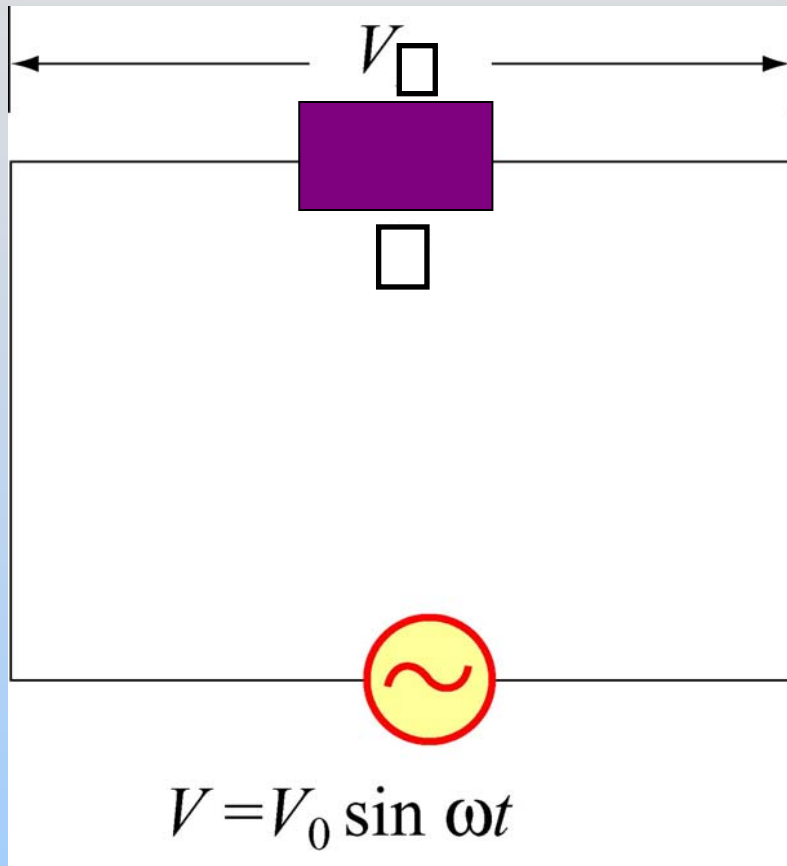
$$V(t) = V_0 \sin \omega t$$



$\omega = 2\pi f$: angular frequency

V_0 : voltage amplitude

AC Circuit: Single Element



$$V_{\square} = V$$

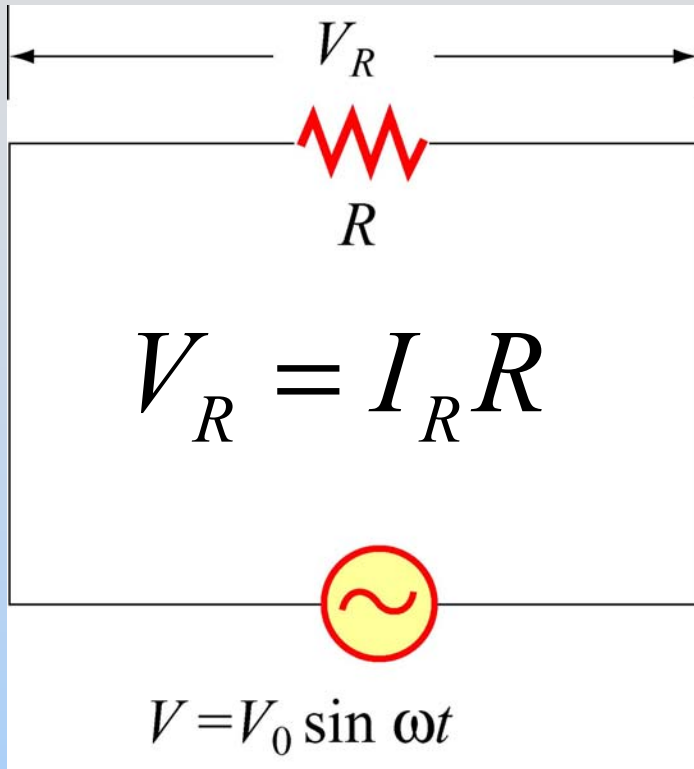
$$= V_0 \sin \omega t$$

$$I(t) = I_0 \sin(\omega t - \phi)$$

Questions:

1. What is I_0 ?
2. What is ϕ ?

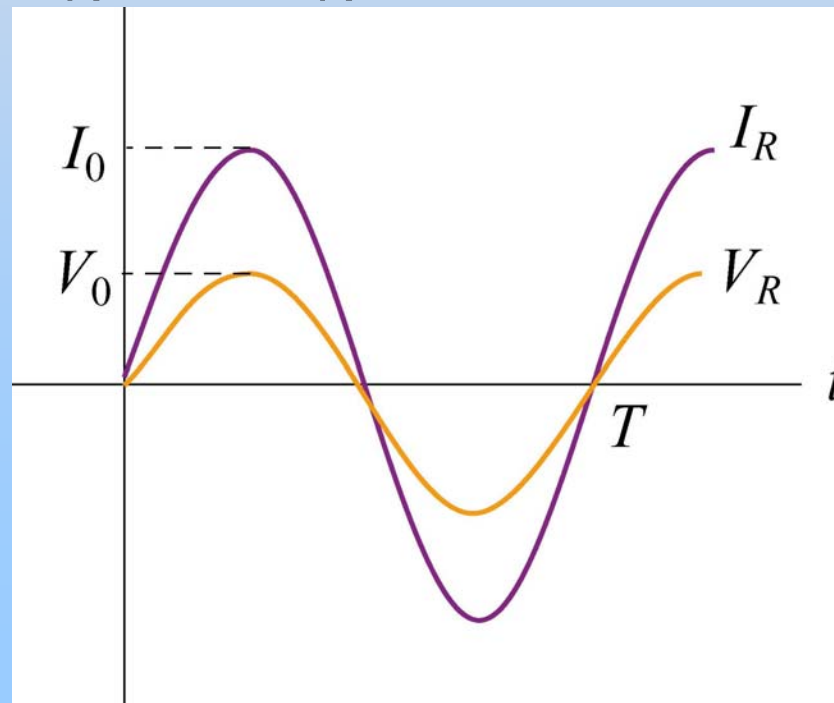
AC Circuit: Resistors



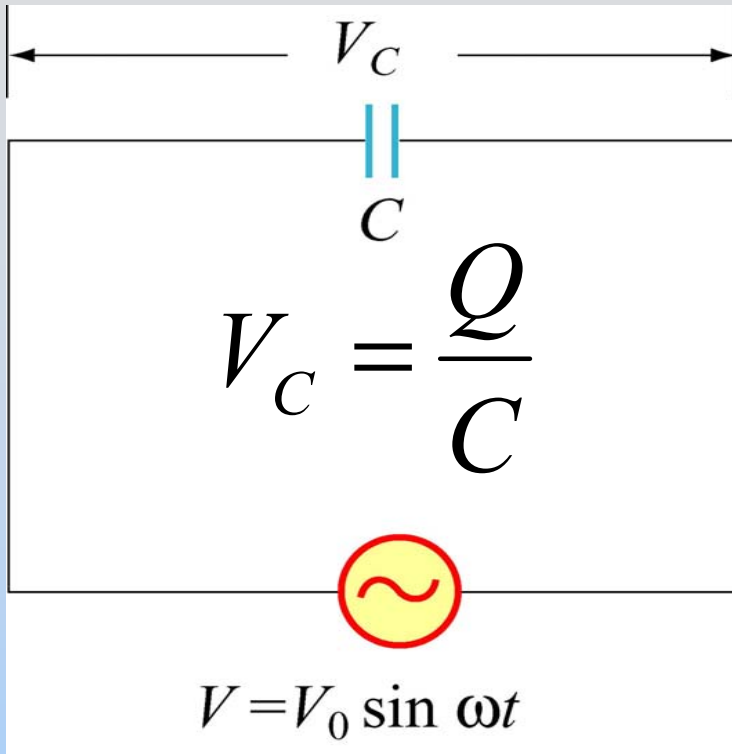
$$I_R = \frac{V_R}{R} = \frac{V_0}{R} \sin \omega t$$
$$= I_0 \sin (\omega t - 0)$$

$$I_0 = \frac{V_0}{R}$$
$$\varphi = 0$$

I_R and V_R are in phase



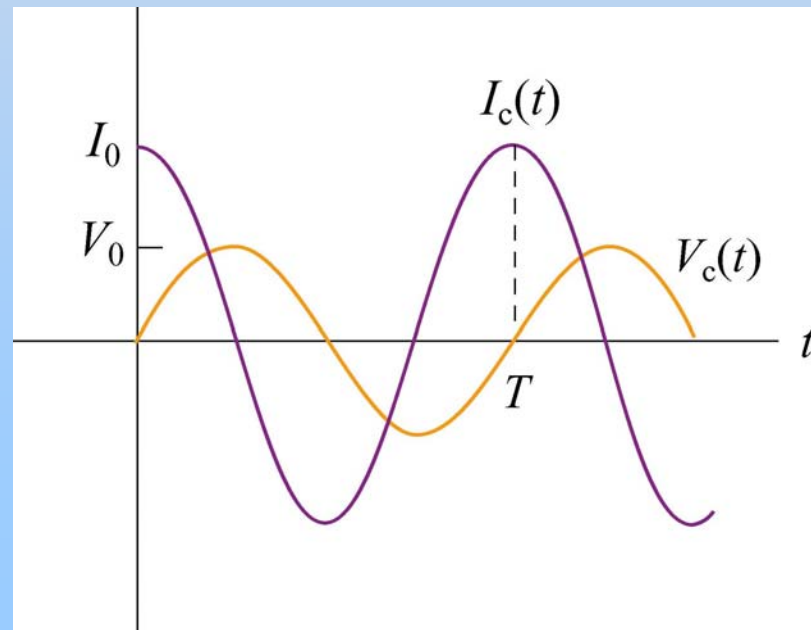
AC Circuit: Capacitors



$$\begin{aligned}
 I_C(t) &= \frac{dQ}{dt} \\
 &= \omega C V_0 \cos \omega t \\
 &= I_0 \sin(\omega t - \pi/2)
 \end{aligned}$$

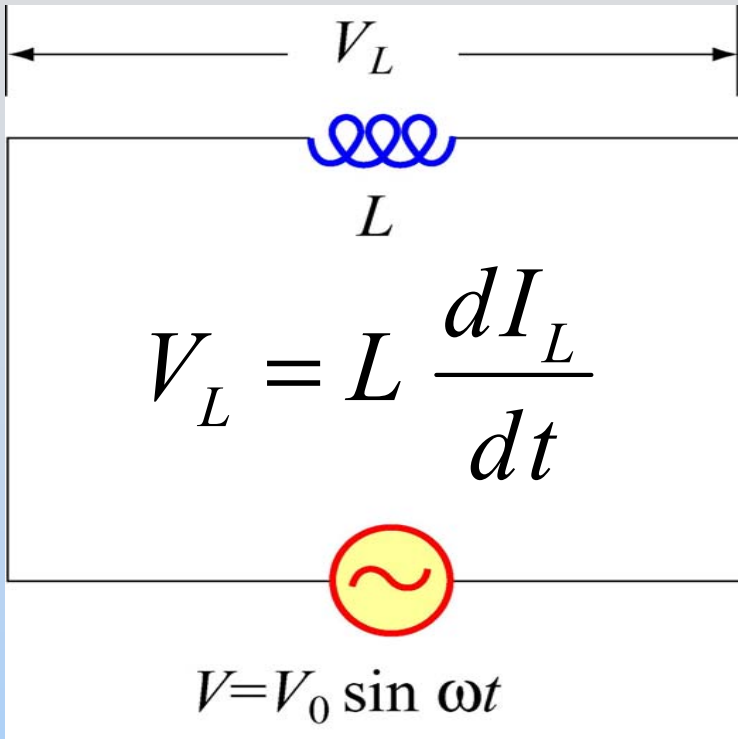
$$\begin{aligned}
 I_0 &= \omega C V_0 \\
 \varphi &= -\pi/2
 \end{aligned}$$

I_C leads V_C by $\pi/2$



$$Q(t) = CV_C = CV_0 \sin \omega t$$

AC Circuit: Inductors



$$I_L(t) = \frac{V_0}{L} \int \sin \omega t \, dt$$

$$= -\frac{V_0}{\omega L} \cos \omega t$$

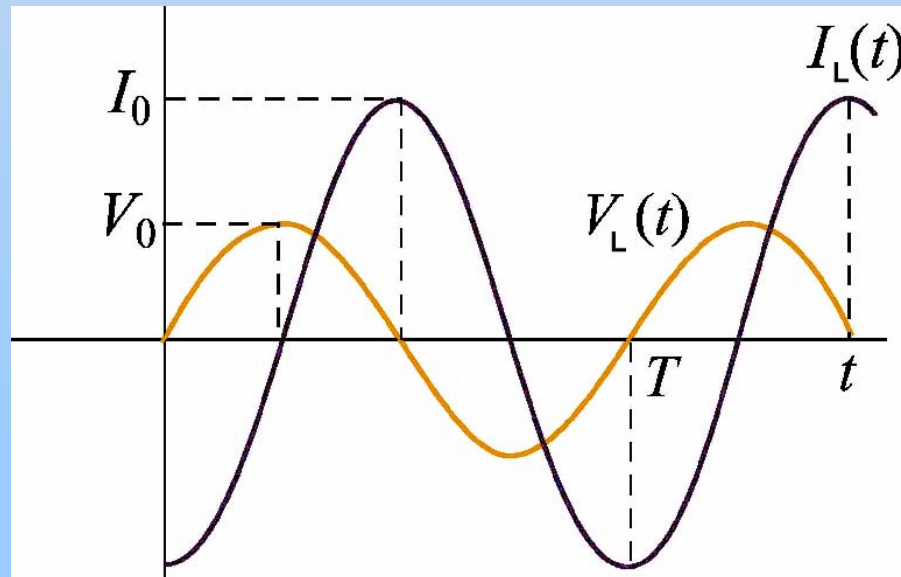
$$= I_0 \sin \left(\omega t - \frac{\pi}{2} \right)$$

$$I_0 = \frac{V_0}{\omega L}$$

$$\varphi = \frac{\pi}{2}$$

I_L lags V_L by $\pi/2$

$$\frac{dI_L}{dt} = \frac{V_L}{L} = \frac{V_0}{L} \sin \omega t$$



AC Circuits: Summary

Element	I_0	Current vs. Voltage	Resistance Reactance Impedance
Resistor	$\frac{V_{0R}}{R}$	In Phase	$R = R$
Capacitor	$\omega C V_{0C}$	Leads	$X_C = \frac{1}{\omega C}$
Inductor	$\frac{V_{0L}}{\omega L}$	Lags	$X_L = \omega L$

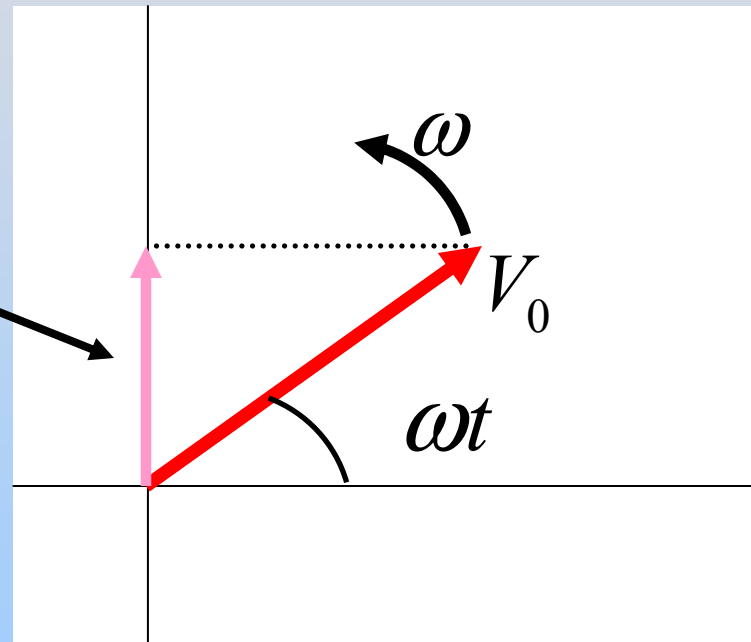
Although derived from single element circuits, these relationships hold generally!

PRS Question: Leading or Lagging?

Phasor Diagram

Nice way of tracking magnitude & phase:

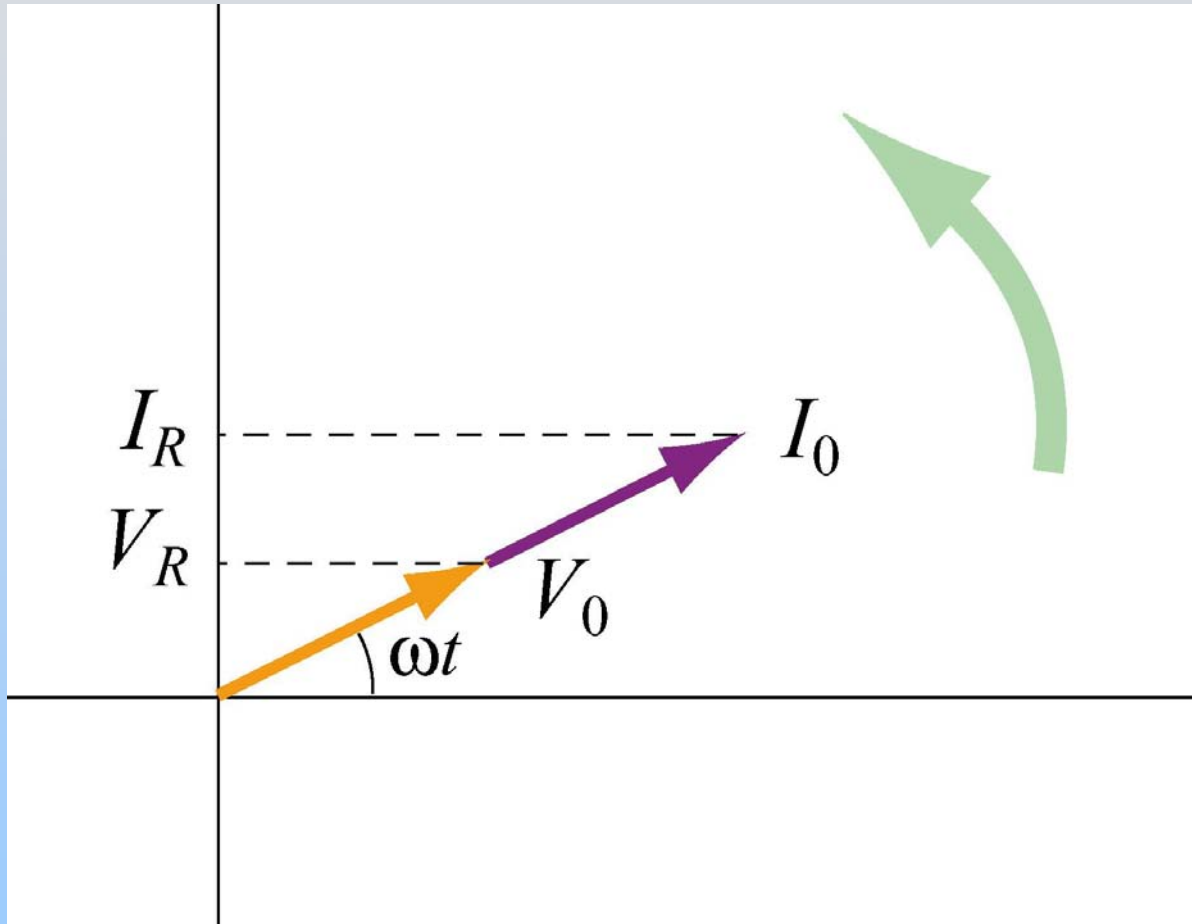
$$V(t) = V_0 \sin(\omega t)$$



- Notes: (1) As the phasor (red vector) rotates, the projection (pink vector) oscillates
(2) Do both for the current and the voltage

Demonstration: Phasors

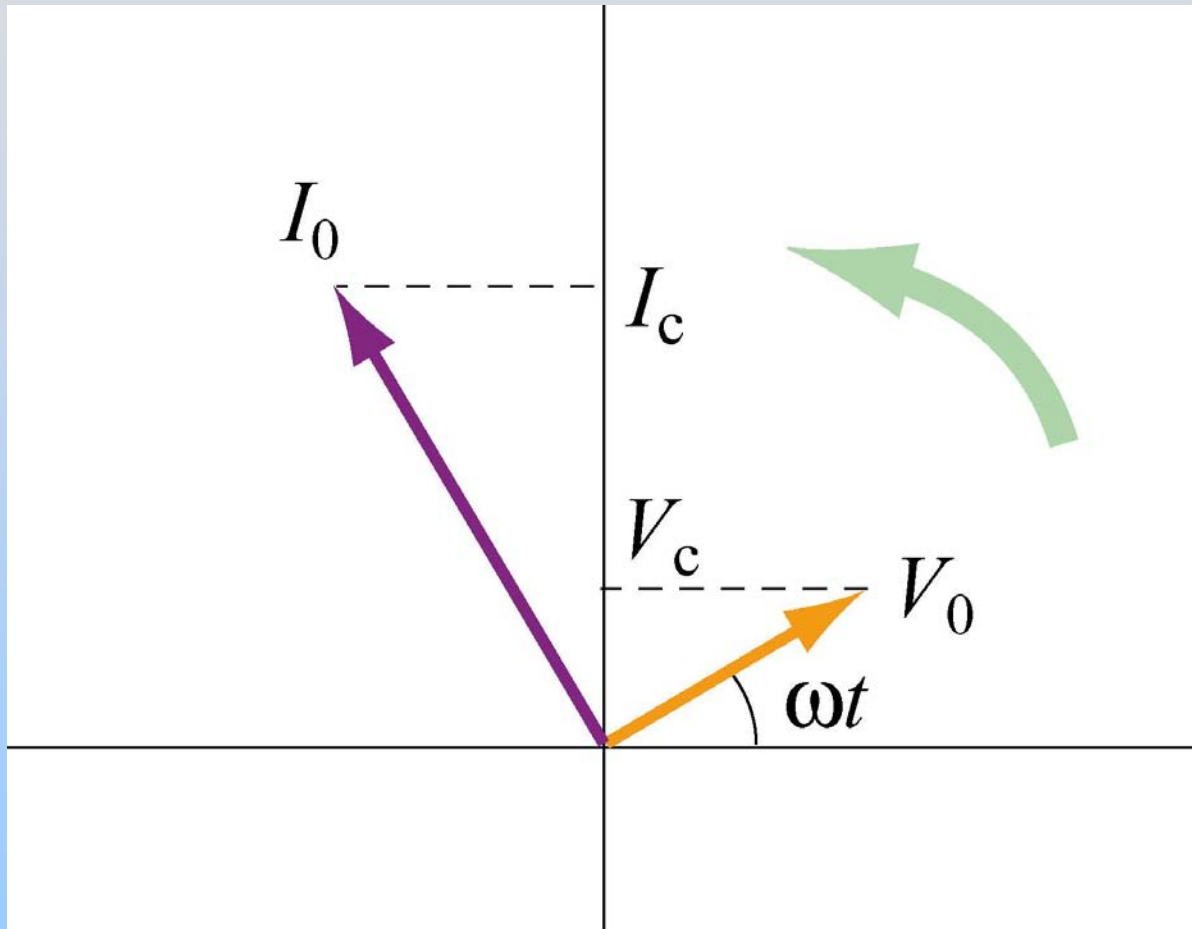
Phasor Diagram: Resistor



$$V_0 = I_0 R$$
$$\varphi = 0$$

I_R and V_R are in phase

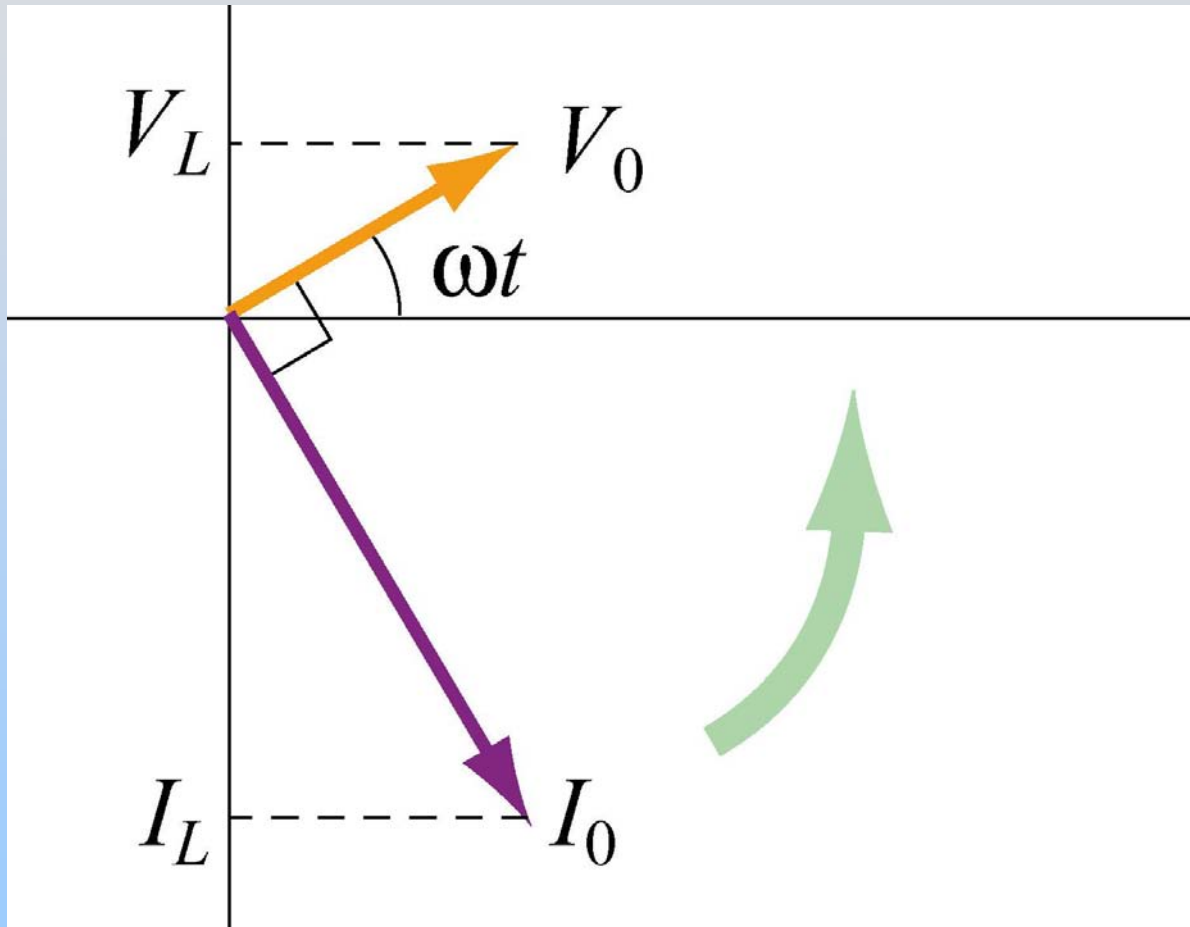
Phasor Diagram: Capacitor



$$\begin{aligned} V_0 &= I_0 X_C \\ &= I_0 \frac{1}{\omega C} \\ \varphi &= -\frac{\pi}{2} \end{aligned}$$

I_C leads V_C by $\pi/2$

Phasor Diagram: Inductor



$$\begin{aligned} V_0 &= I_0 X_L \\ &= I_0 \omega L \\ \varphi &= \frac{\pi}{2} \end{aligned}$$

I_L lags V_L by $\pi/2$

PRS Questions: Phase

Put it all together: Driven RLC Circuits

Question of Phase

We had fixed phase of voltage:

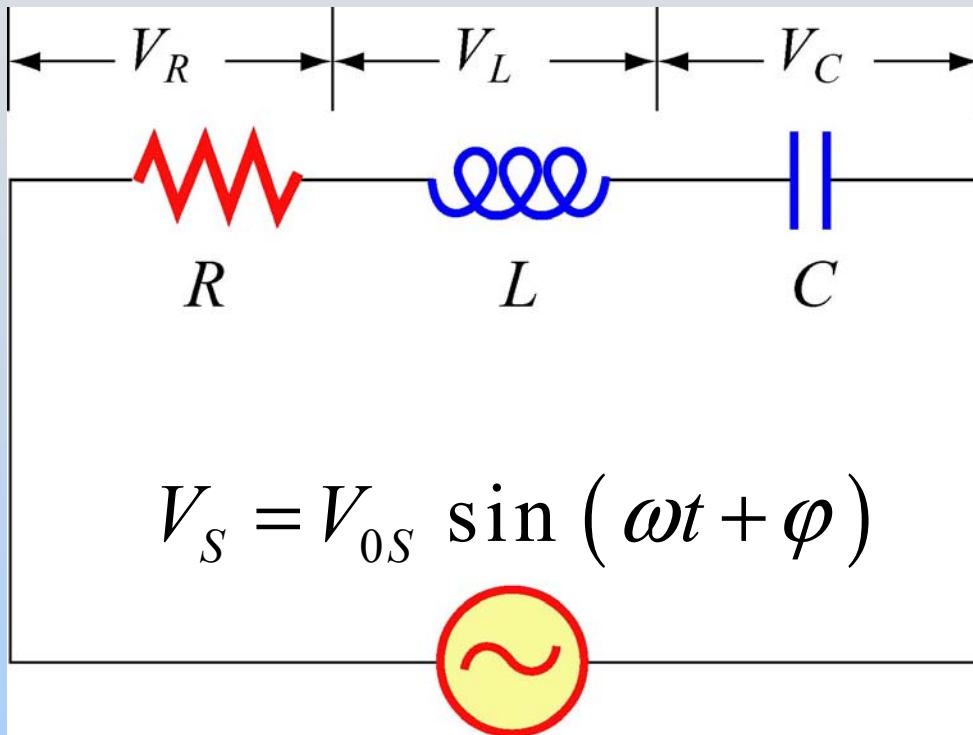
$$V = V_0 \sin \omega t \quad I(t) = I_0 \sin(\omega t - \phi)$$

It's the same to write:

$$V = V_0 \sin(\omega t + \phi) \quad I(t) = I_0 \sin \omega t$$

(Just shifting zero of time)

Driven RLC Series Circuit



$$I(t) = I_0 \sin(\omega t)$$

$$V_R = V_{R0} \sin(\omega t)$$

$$V_L = V_{L0} \sin\left(\omega t + \frac{\pi}{2}\right)$$

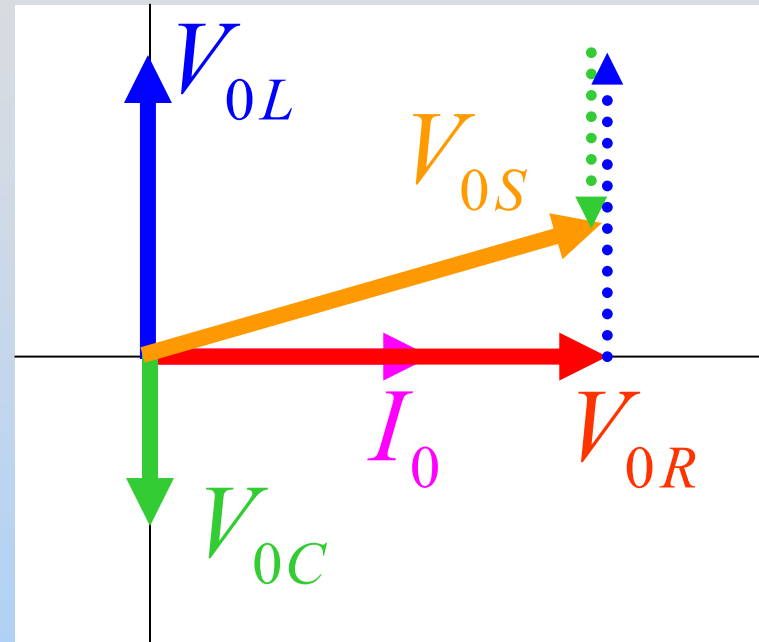
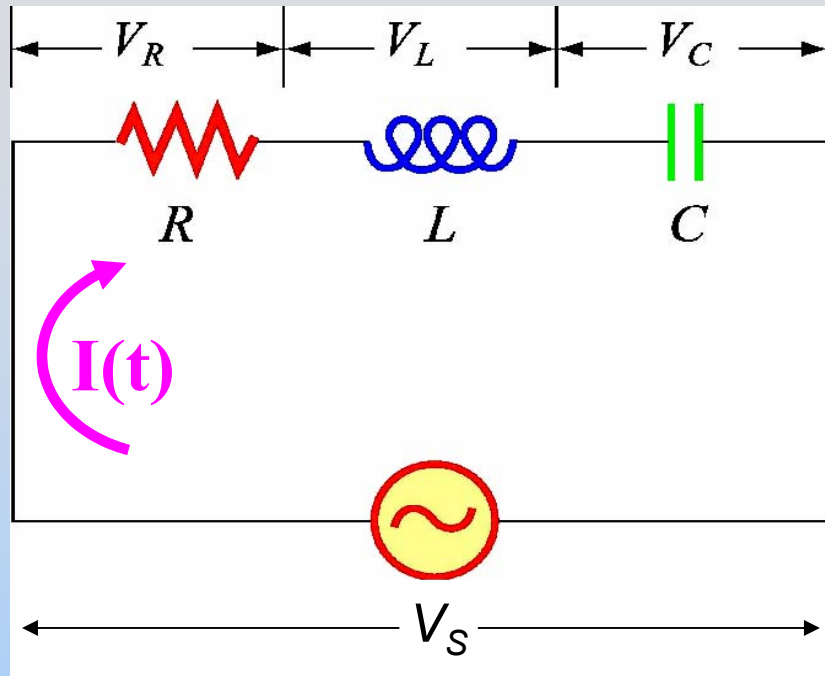
$$V_C = V_{C0} \sin\left(\omega t + \frac{-\pi}{2}\right)$$

What is I_0 (and $V_{R0} = I_0 R$, $V_{L0} = I_0 X_L$, $V_{C0} = I_0 X_C$)?

What is φ ? Does the current lead or lag V_s ?

$$\text{Must Solve: } V_S = V_R + V_L + V_C$$

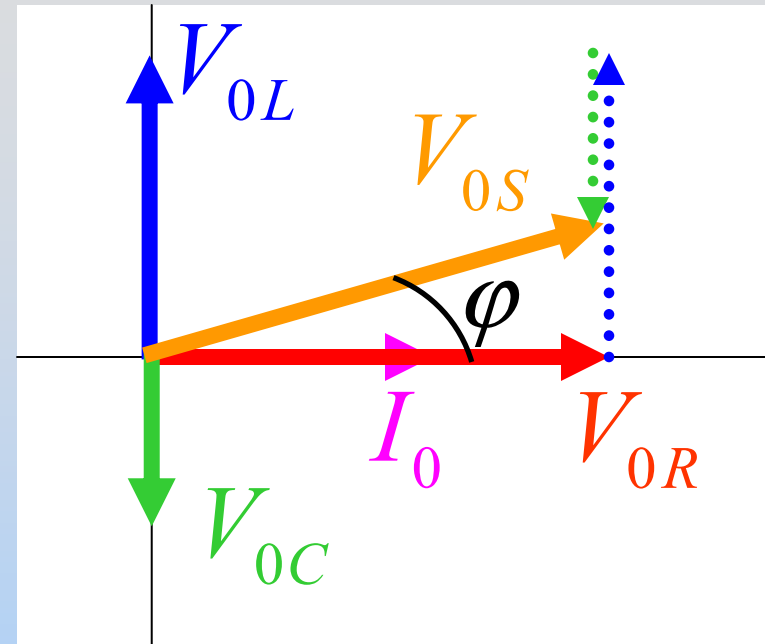
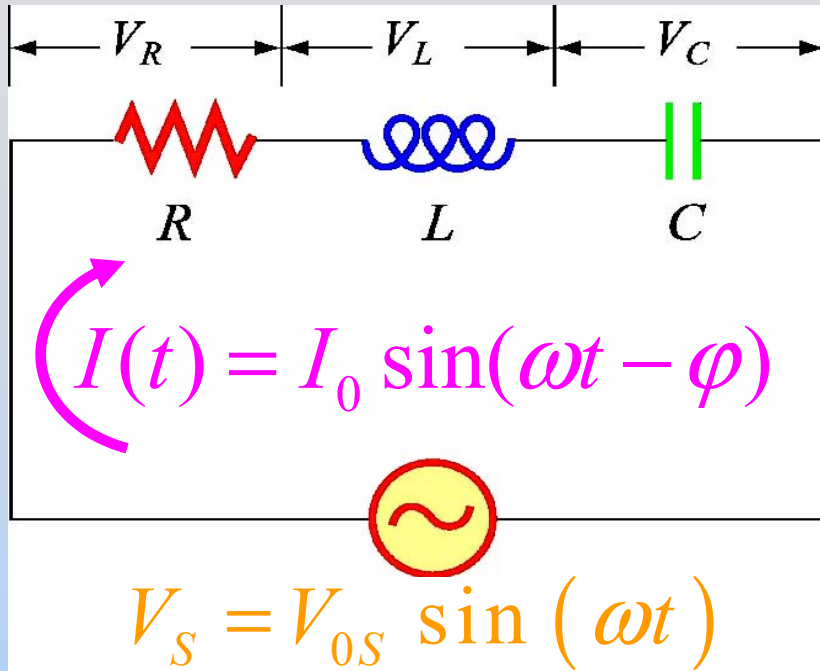
Driven RLC Series Circuit



Now Solve: $V_S = V_R + V_L + V_C$

Now we just need to read the phasor diagram!

Driven RLC Series Circuit



$$V_{0S} = \sqrt{V_{R0}^2 + (V_{L0} - V_{C0})^2} = I_0 \sqrt{R^2 + (X_L - X_C)^2} \equiv I_0 Z$$

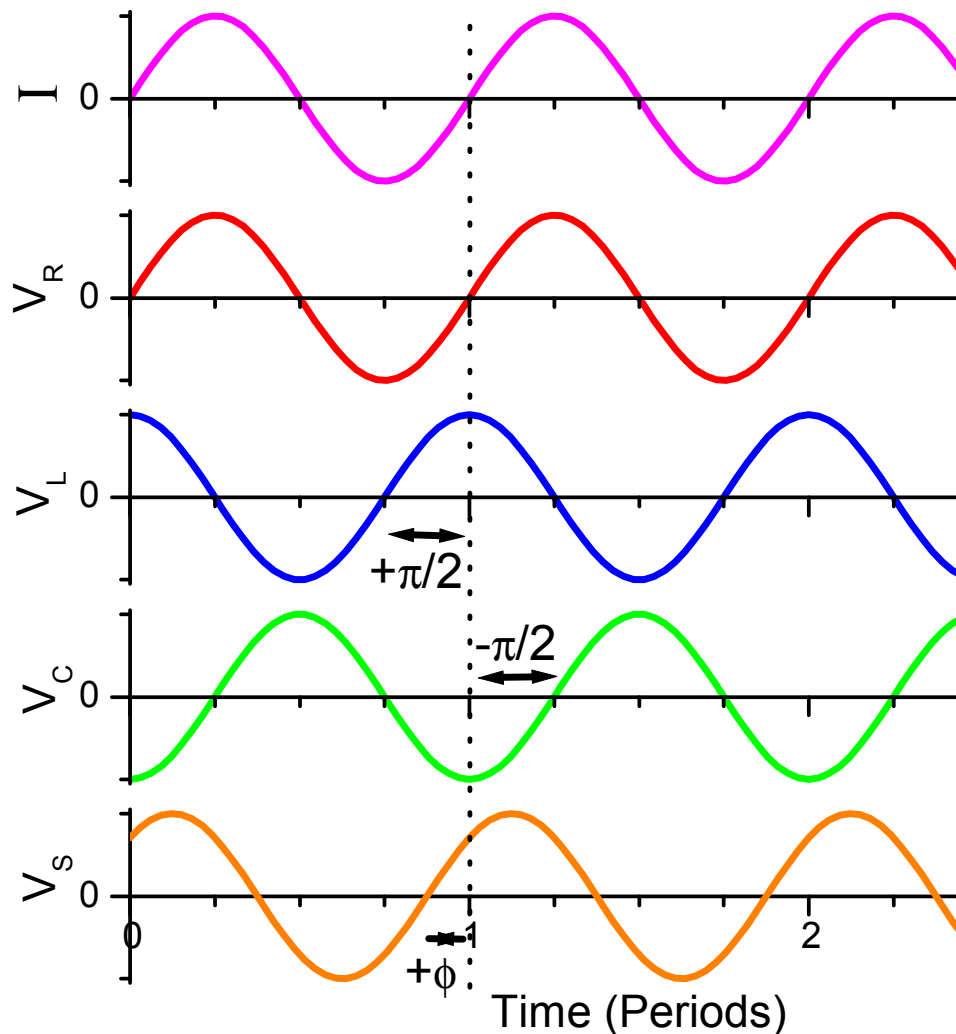
$$I_0 = \frac{V_{0S}}{Z}$$

$$Z = \sqrt{R^2 + (X_L - X_C)^2}$$

Impedance

$$\phi = \tan^{-1} \left(\frac{X_L - X_C}{R} \right)$$

Plot I, V's vs. Time



$$I(t) = I_0 \sin(\omega t)$$

$$V_R(t) = I_0 R \sin(\omega t)$$

$$V_L(t) = I_0 X_L \sin\left(\omega t + \frac{\pi}{2}\right)$$

$$V_C(t) = I_0 X_C \sin\left(\omega t - \frac{\pi}{2}\right)$$

$$V_S(t) = V_{S0} \sin(\omega t + \phi)$$

PRS Question: Who Dominates?

RLC Circuits: Resonances

Resonance

$$I_0 = \frac{V_0}{Z} = \frac{V_0}{\sqrt{R^2 + (X_L - X_C)^2}}; \quad X_L = \omega L, \quad X_C = \frac{1}{\omega C}$$

At very low frequencies, C dominates ($X_C \gg X_L$):
it fills up and keeps the current low

At very high frequencies, L dominates ($X_L \gg X_C$):
the current tries to change but it won't let it

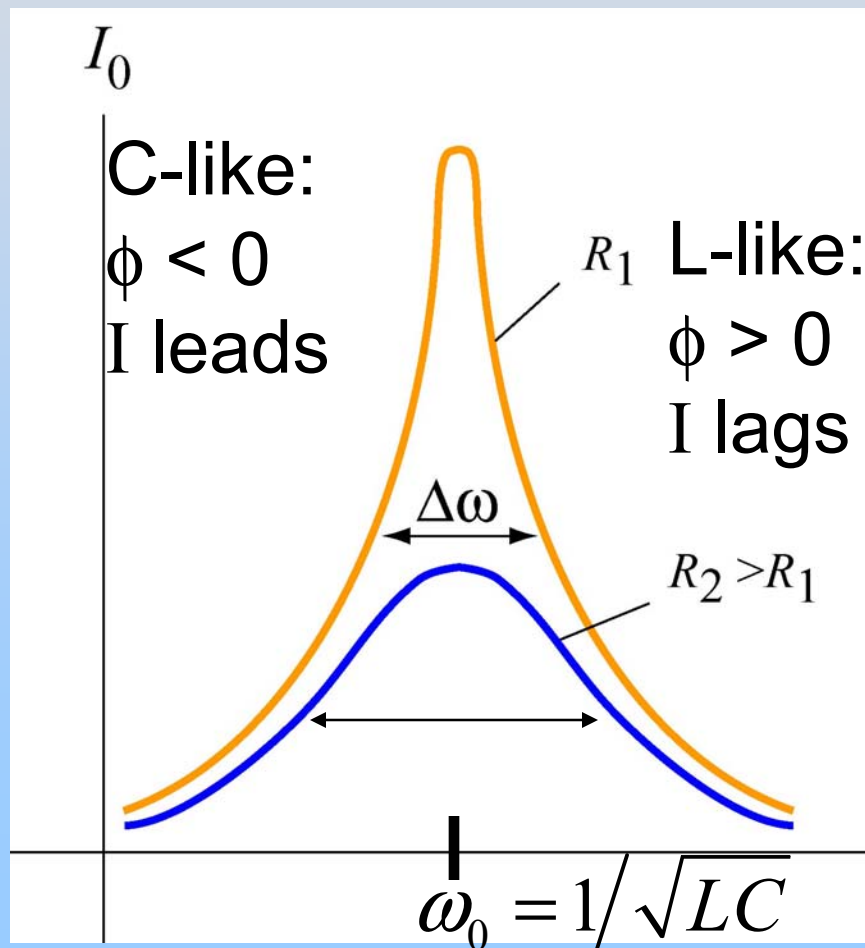
At intermediate frequencies we have **resonance**

I_0 reaches maximum when $X_L = X_C$

$$\omega_0 = \frac{1}{\sqrt{LC}}$$

Resonance

$$I_0 = \frac{V_0}{Z} = \frac{V_0}{\sqrt{R^2 + (X_L - X_C)^2}}; \quad X_L = \omega L, \quad X_C = \frac{1}{\omega C}$$



$$\phi = \tan^{-1} \left(\frac{X_L - X_C}{R} \right)$$

Demonstration: RLC with Light Bulb

PRS Questions: Resonance

Experiment 11: Driven RLC Circuit

Experiment 11: How To

Part I

- Use exp11a.ds
- Change frequency, look at I & V. Try to find resonance – place where I is maximum

Part II

- Use exp11b.ds
- Run the program at each of the listed frequencies to make a plot of I_0 vs. ω