

8.01L SUMMARY OF EQUATIONS

Note: Quantities shown in **bold** are vectors.

$$\mathbf{v} = d\mathbf{r}/dt \quad \mathbf{a} = d\mathbf{v}/dt$$

For *constant* acceleration \mathbf{a} , if at $t = 0$ $\mathbf{r} = \mathbf{r}_0$ and $\mathbf{v} = \mathbf{v}_0$:

$$\mathbf{v} = \mathbf{v}_0 + \mathbf{a}t$$

$$\mathbf{r} = \mathbf{r}_0 + \mathbf{v}_0t + \frac{1}{2}\mathbf{a}t^2$$

Circular motion at constant speed $a = v^2/r = \omega^2r$ (Centripetal acceleration, points towards center of circle, ω is angular speed in radians per second)

Adding relative velocities ("wrt" is short for "with respect to"): $\mathbf{v}_{B \text{ wrt } C} + \mathbf{v}_{C \text{ wrt } A} = \mathbf{v}_{B \text{ wrt } A}$

$$\sum \mathbf{F} = 0 \Leftrightarrow \mathbf{a} = 0 \quad (\text{Newton's first law})$$

$$\mathbf{F} = m\mathbf{a} \text{ or } \mathbf{F} = d\mathbf{p}/dt \quad (\text{Newton's second law}) \quad \mathbf{F}_{AB} = -\mathbf{F}_{BA} \quad (\text{Newton's third law})$$

$$\mathbf{p} = m\mathbf{v} \quad (\text{momentum})$$

$$\mathbf{J} = \int_{t_1}^{t_2} \mathbf{F} dt = \int_{t_1}^{t_2} \frac{d\mathbf{p}}{dt} dt = \mathbf{p}_2 - \mathbf{p}_1 \quad (\text{impulse})$$

$$\mathbf{r}_{\text{cm}} = \frac{\sum m_i \mathbf{r}_i}{\sum m_i} \quad (\text{position of center of mass})$$

$$\mathbf{F} = -k\mathbf{x} \quad (\text{spring force}) \quad f \leq \mu N \quad (\text{Friction force relative to Normal force})$$

$$\mathbf{F} = -\frac{GMm}{r^2} \hat{\mathbf{r}} \quad (\text{gravitational force between two particles})$$

$$W = \int \mathbf{F} \cdot d\mathbf{r} \quad (\text{work done by force } \mathbf{F})$$

$$W_{\text{other}} = \Delta E = E_f - E_i \quad E = KE + PE \quad (\text{work-energy theorem})$$

$$F_x = -\frac{dU}{dx} \quad (\text{force derived from potential energy})$$

$$\text{Potential Energies: } U = \frac{1}{2}kx^2 \quad (\text{spring force})$$

$$U = \frac{-GMm}{r} \quad (\text{gravitational, general}) \quad U = mgh \quad (\text{gravitational, near Earth})$$

$$\omega = \sqrt{k/m} \quad x = A\cos(\omega t + \phi) \quad (\text{Equations for Simple Harmonic Motion})$$

$$v = -A\omega \sin(\omega t + \phi) \quad T = 2\pi/\omega$$

$$P_2 + \rho gy_2 = P_1 + \rho gy_1 \quad (\text{Pascal's Law: pressure versus height in a liquid with velocity} = 0)$$

$$P + \frac{1}{2}\rho v^2 + \rho gy = \text{constant} \quad (\text{Bernoulli's equation})$$

$$A_2 v_2 = A_1 v_1 \quad (\text{continuity equation})$$

$$PV = NkT = nRT \quad (\text{ideal-gas law})$$

$$\left\langle \frac{1}{2} m \bar{v}^2 \right\rangle = \frac{3}{2} kT \quad (\text{definition of kinetic temperature})$$

$$F_B = \rho_f V_f g \quad (\text{buoyancy force, } f = \text{fluid displaced})$$

Quantity	Translational	Rotational (about axis)
Velocity, acceleration	\mathbf{v}, \mathbf{a}	$\boldsymbol{\omega}, \boldsymbol{\alpha} (v=R\omega, a = R\alpha)$
Mass	$M = \sum_i m_i$	$I = \sum_i m_i R_i^2$
Kinetic energy	$\frac{1}{2} Mv^2$	$\frac{1}{2} I\omega^2$
Net force	$\sum_i \mathbf{F}^{\text{ext}} = M\mathbf{a}_{\text{cm}}$	$\sum_i \boldsymbol{\tau}^{\text{ext}} = I\boldsymbol{\alpha}$
Momentum	$\mathbf{p} = m\mathbf{v}$	$\mathbf{L} = \mathbf{r} \times \mathbf{p}$ or $\mathbf{L} = I\boldsymbol{\omega}$

$$\boldsymbol{\tau} = \mathbf{r} \times \mathbf{F} = \frac{d\mathbf{L}}{dt} = I\boldsymbol{\alpha} \quad |\tau| = rF \sin(\phi) = Fr_{\perp} \quad (\text{torque equations})$$

$$\mathbf{L} = \mathbf{r} \times \mathbf{p} \quad |\mathbf{L}| = mvr \sin(\phi) \quad (\text{angular momentum of point particle})$$

$$\mathbf{L} = I\boldsymbol{\omega} \quad (\text{angular momentum for solid object})$$

$$I_1 = I_{\text{c.m.}} + Md^2 \quad (\text{parallel axis theorem})$$

$$I = \frac{1}{2} MR^2 \quad (\text{cylinder around center}) \quad I = \frac{2}{5} MR^2 \quad (\text{solid sphere around center})$$

$$I = \frac{1}{12} ML^2 \quad (\text{rod around center}) \quad I = \frac{1}{3} ML^2 \quad (\text{rod around end})$$

$$KE = \frac{1}{2} M_{\text{Tot}} v_{\text{CM}}^2 + \frac{1}{2} I_{\text{CM}} \omega^2 \quad (\text{kinetic energy for object moving and rolling})$$

$$KE = \frac{1}{2} I_{\text{pivot}} \omega^2 \quad (\text{kinetic energy for object rotating around a fixed pivot})$$

Physical Constants:

$$g = 9.8 \text{ m/s}^2 \quad \text{Use the approximate value } g = 10 \text{ m/s}^2 \text{ where told to do so.}$$

$$G = 6.67 \times 10^{-11} \text{ N m}^2/\text{kg}^2$$

$$k = 1.38 \times 10^{-23} \text{ J/K} \quad R = 8.31 \text{ J/(mol. K)}$$

$$0^\circ \text{ C} = 273^\circ \text{ K}$$

$$\text{Density of water} = 1,000 \text{ kg/m}^3$$

$$\text{Atmospheric pressure} = 1.0 \times 10^5 \text{ Pa}$$

Conversion reminder:

$$\pi \text{ radians} = 180^\circ$$

Lazy Physicist 's Favorite Angle: (to be used when calculators are not allowed):

36.9° and 53.1° are the angles of a 3-4-5 right triangle so:

$$\sin(36.9^\circ) = \cos(53.1^\circ) = 0.60 \quad \cos(36.9^\circ) = \sin(53.1^\circ) = 0.80$$

$$\tan(36.9^\circ) = 0.75 \quad \tan(53.1^\circ) = 1.33$$

Other (possibly) Useful Trig Functions:

$$\cos(30^\circ) = \sin(60^\circ) = \frac{\sqrt{3}}{2} \quad \sin(30^\circ) = \cos(60^\circ) = \frac{1}{2}$$

$$\cos(45^\circ) = \sin(45^\circ) = \frac{1}{\sqrt{2}}$$

$$\text{Solution to a Quadratic Equation: If } ax^2 + bx + c = 0 \text{ then } x = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$$