22.615, MHD Theory of Fusion Systems Prof. Freidberg **Lecture 9: The High Beta Tokamak**

Summary of the Properties of an Ohmic Tokamak

- 1. Advantages:
	- a. good equilibrium (small shift)
	- b. good stability (*q* ∼ 1)
	- c. good confinement $(\tau \sim naR^2)$
	- d. good ohmic heating $(T_e \sim T_i \sim 2 \text{keV})$
- 2. Disadvantages:

a. low
$$
\beta : \beta \sim \epsilon^2
$$
, $\beta_t = \frac{\epsilon^2 \beta_p}{q_g^2} \sim \frac{0.3^2 \times 0.5}{3^2} = 1/2\%$

- b. external heating is required: joule heating is not adequate. External heating is expensive, but also raises β
- c. tight aspect ratio is required to raise β : this is technologically difficult
- d. pulsed operation is required unless current drive works efficiently
- 3. The high β tokamak resolves the problem of low β
	- a. It allows a tokamak to operate at higher $\beta \sim 5-10\%$. This leads to more economic devices
	- b. How do we achieve higher β ? We apply additional auxiliary heating, keeping $B_{\!\phi}$ fixed. This raises ρ relative to $B_{\!\phi}^2 \big/ 2 \mu_{0}^2$.

High β **Tokamak Expansion**

- 1. We again assume large aspect ratio: $a/R_0 \ll 1 \epsilon \equiv a/R_0$
- 2. Stability is produced by a large toroidal field: *q* ∼ 1
- 3. Thus, as in the ohmic tokamak $q \sim rB_{\phi}/RB_{\theta}$, implying that $B_{\theta}/B_{\phi} \sim \epsilon$

4. Radial pressure balance, however is produced by the *toroidal* field

 $|$
neglect, confines only $β \sim ∈^2$

5. To improve β over that achievable in the ohmic tokamak we need

$$
p \sim \frac{B_0 \delta B_{\phi}}{\mu_0} \gg \frac{B_{\theta}^2}{\mu_0}
$$

6. Or in terms of β

$$
\beta \sim \frac{\delta B_{\phi}}{B_{0}} \gg \frac{B_{\theta}^{2}}{B_{\phi}^{2}} \sim \epsilon^{2}
$$

- 7. How large can β and $\delta B_{\phi}/B_0$ get?
- 8. The limiting condition is determined by toroidal force balance which is still accomplished by a combination of *I* and *Bv*
- 9. Increasing β increases the toroidal shift. The largest possible β occurs when the shift becomes of order unity $Δ/a ~ 1$. Recall that in an ohmic tokamak $Δ/a ~ a/R_0$.

10. Let us estimate the shift using the small shift relation

$$
\Psi_1 = -B_\theta \int_r^b \frac{dr}{r B_\theta^2} \int_0^r \left(y B_\theta^2 - 2 \mu_0 y^2 \frac{dp}{dy} \right) dy
$$

neglect since $\mu_0 p \gg B_\theta^2$

$$
\Psi_1 \sim \frac{\mu_0 a^2 p}{B_\theta}
$$

11. Therefore

$$
\frac{\Delta}{a} \sim -\frac{\Psi_1}{a\psi_0} \sim \frac{1}{aRB_\theta} \left(\frac{\mu_0 a^2 p}{B_\theta}\right) \sim \frac{a}{R} \left(\frac{\mu_0 p}{B_\theta^2}\right) \sim \epsilon \beta_p \sim \frac{\beta_t q^2}{\epsilon}
$$

12. For *q* ∼ 1, then Δ/a ∼ 1 when β_t /∈ ∼ 1

13. This suggests the following ordering for the high β tokamak

$$
\beta\sim\in, \frac{\delta B_{\phi}}{B_{\phi}}\sim\in, \quad \Delta/a\sim 1
$$

Comparison of Expansions

Expansion of Grad-Shafranov Equation

- 1. Since Δ/a ~ 1, toroidal force balance and radial pressure balance enter together in zeroth order.
- 2. Good news: we need only the zeroth order equations. No first order corrections are required.
- 3. Bad news: The zero other equations are still nonlinear partial differential equations.
- 4. Expansion:
	- a. $\psi = \psi_0 (r, \theta) + ..., \psi \sim r R B_\theta \sim a^2 B_0$
	- b. $p(\psi) = p(\psi_0) + ..., \mu_0 p \sim \in B_0^2$
	- c. $F = RB_{\phi} = F(\psi)$ new free function $F^2 = R_0^2 \left[B_0^2 - 2 \mu_0 p(\psi) + 2 B_0 \overline{B_2} (\psi) \right]$ $~\sim 1$ $~\sim \epsilon$ $~\sim \epsilon^2$ $B_2/B_0 \sim \epsilon^2$
	- d. This automatically produces a θ pinch pressure balance

$$
p + \frac{B_{\phi}^2}{2\mu_0} \approx \text{const}
$$

5. Substitute the expansion into the Grad-Shafranov equation

$$
\nabla^2 \psi = -\mu_0 \left(R_0 + r \cos \theta \right)^2 \frac{dp}{d\psi} - \frac{d}{d\psi} \frac{F^2}{2} + \frac{1}{R} \left(\frac{\partial \psi}{\partial r} \cos \theta - \frac{1}{r} \frac{\partial \psi}{\partial \theta} \sin \theta \right)
$$

\n
$$
T_1 = \nabla^2 \psi \sim \frac{\psi}{d^2} \sim B_0
$$

\n
$$
T_2 = \frac{1}{R} \left(\frac{\partial \psi}{\partial r} \cos \theta - \frac{1}{r} \frac{\partial \psi}{\partial \theta} \sin \theta \right) \sim \frac{\psi}{dR} \sim \epsilon B_0 \text{ neglect}
$$

\n
$$
T_2 = -\mu_0 \left(R_0 + r \cos \theta \right)^2 \frac{dp}{d\psi} - \frac{d}{d\psi} \frac{F^2}{2}
$$

\n
$$
\approx -\frac{d}{d\psi} \left(\frac{F^2}{2} + \mu_0 R_0^2 \rho \right) - 2\mu_0 R_0 r \cos \theta \frac{dp}{d\psi} + ...
$$

\n
$$
= -R_0^2 \frac{d}{d\psi} \left[\left(\frac{B_0^2}{2} - \mu_0 p + B_0 B_2 \right) + \mu_0 p \right] - 2\mu_0 R_0 r \cos \theta \frac{dp}{d\psi}
$$

\n
$$
= -R_0^2 \frac{d}{d\psi} \left(B_0 B_2 \right) \sim \frac{R_0^2 B_0 B_2}{\psi} \sim B_0
$$

\n
$$
-2\mu_0 R_0 r \cos \theta \frac{dp}{d\psi} \sim \frac{\mu_0 p B_0 a}{\psi} \sim B_0
$$

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6. Therefore, to leading order the Grad-Shafranov equation reduces to

$$
\nabla^2 \psi_0 = -R_0^2 \frac{d}{d\psi_0} B_0 B_2 (\psi_0) - 2\mu_0 R_0 r \cos \theta \frac{d\rho(\psi_0)}{d\psi_0}
$$

7. Note that $\mu_0 R J_\phi \approx -\nabla^2 \psi$, so that on a circular plasma flux surface

$$
\langle \mu_0 R J_\phi \rangle = R_0^2 \frac{d}{d\psi} B_0 B_2
$$

average over θ

We see that $dB_2/d\psi$ is proportional to the average toroidal current within a given flux surface.

- 8. Even though the equation is simpler, it is still a nonlinear PDE.
- 9. In general, it must be solved numerically.
- 10. The difficulty arises because the shifts are finite and cannot be treated perturbatively.
- 11. We shall determine general features of high β tokamak by examining a special case.

Special Case

1. Choose

$$
2\mu_0 R_0 \frac{dp}{d\psi_0} = -C \quad C = \text{const}
$$

$$
R_0^2 B_0 \frac{dB_2}{d\psi_0} = -A \qquad A = \text{const}
$$

2. This implies $p \sim -C\psi$ (assume ψ (boundary)=0) and $\langle J_{\phi} \rangle \sim -A$

3. Solution: with these choices the Grad-Shafranov equation becomes

$$
\frac{1}{r}\frac{\partial}{\partial r}r\frac{\partial \psi_0}{\partial r} + \frac{1}{r^2}\frac{\partial^2 \psi_0}{\partial \theta^2} = A + Cr\cos\theta
$$

4. Boundary conditions: We assume a *circular* plasma of radius $r = a$

 $\psi(a, \theta)$ = 0 (normalization of flux function is arbitrary)

 $\psi(r, \theta)$ regular for $r \le a$

The circular assumption is made for simplicity and can be generalized to other cross sections.

5. Solution: (We need only cos *n*θ terms because of up-down symmetry.)

$$
\Psi_{part} = A\frac{r^2}{4} + C\frac{r^3}{8}\cos\theta
$$

$$
\psi_{\text{hom}} = k_1 + k_2 \ln r + k_3 r \cos \theta + \frac{k_4 \cos \theta}{r} + \sum_{n=2}^{\infty} \left(a_n r^n + b_n r^{-n} \right) \cos n\theta
$$
\n
$$
\begin{vmatrix}\n\cdot & \cdot & \cdot \\
\cdot & \cdot & \cdot \\
\cdot & \cdot & \cdot\n\end{vmatrix} \quad \text{not regular} \quad \text{not regular} \quad \text{not regular}
$$

$$
= k_3 r \cos \theta + k_1
$$

 only terms which are regular and required to balance ψ_{part} on the boundary $r = a$

For all $n \ge 2$, it follows that $a_n = 0$

6. Choose k_1 and k_3 to make $\psi(a, \theta) = 0$

$$
\psi(r,\theta) = \frac{A}{4}(r^2 - a^2) + \frac{C}{8}(r^3 - a^2r)\cos\theta
$$

7. Then

$$
B_0 = \frac{1}{R_0} \frac{\partial \psi_0}{\partial r} = \frac{1}{2R_0} \left[Ar + \frac{C}{4} \left(3r^2 - a^2 \right) \cos \theta \right]
$$

$$
\mu_0 p = -\frac{C}{2R_0} \psi_0 = \frac{C}{8R_0} \left[A \left(a^2 - r^2 \right) + \frac{C}{2} \left(a^2 r - r^3 \right) \cos \theta \right]
$$

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Physical Interpretation

Let us express *A* and *C* in terms of more physical quantities: β_t , *I* or equivalently β_t , $q_* \propto 1/I$

1. q_* is a parameter related to kink stability and the surface MHD safety factor q_a

$$
q_{\ast} = \frac{2A_{p}B_{0}}{\mu_{0}R_{0}I}
$$

$$
= \frac{2\pi a^{2}B_{0}}{\mu_{0}R_{0}I}
$$

2.
$$
\mu_0 I = \int B_\rho \cdot dl = \int B_\theta (a, \theta) a d\theta
$$

ON A CIRCLE

$$
\begin{array}{c}\n\text{SININGLE} \\
\text{SININGLE}\n\end{array}
$$

$$
= \frac{a}{2R_0} \int_0^{2\pi} \left[Aa + \frac{Ca^2}{2} \zeta \right]_0^{2\pi} d\theta = \frac{Aa^2}{2R_0} \cdot 2\pi = \frac{\pi A a^2}{R_0}
$$

3.
$$
\frac{1}{q_*} = \frac{\mu_0 R_0}{2\pi a^2 R_0} \frac{\pi A a^2}{R_0 \mu_0} = \frac{A}{2R_0}
$$

4.
$$
\beta_t = \frac{2\mu_0}{B_0^2} \langle p \rangle = \frac{2\mu_0}{B_0^2} \frac{1}{\pi a^2} \int pr dr d\theta
$$

$$
= \frac{2\mu_0}{\pi a^2 B_0} \frac{C}{8\mu_0 R_0} \int_0^a \int_0^{2\pi} r dr d\theta \left[A\left(a^2 - r^2\right) + \frac{C}{2} \left(a^2 r - r^3\right) \zeta \phi' s \theta \right]
$$

$$
\frac{2\pi a^4}{4}
$$

$$
=\frac{a^2}{8R_0B_0^2}AC=\frac{a^2}{4R_0B_0}\frac{C}{q_\star}
$$

5. Thus

$$
\frac{A}{2B_0} = \frac{1}{q_*}
$$

$$
\frac{a^2C}{4R_0B_0} = q_*\beta_t
$$

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6. General equilibrium relation for a high β circular tokamak (minor degression)

a.
$$
\beta_p = \frac{\int pr \, dr \, d\theta}{\mu_0 l^2 / 8\pi}
$$

$$
= \frac{8\pi}{\mu_0 l^2} \frac{\pi a^2 B_0^2}{2\mu_0} \beta_t
$$

$$
= \left(\frac{2\pi a B_0}{\mu_0 l}\right)^2 \beta_t
$$

$$
= \frac{q_\star^2 \beta_t}{\epsilon^2}, \epsilon = a/R_0
$$

b. The general equilibrium relation is given by

$$
\beta_t = \frac{\epsilon^2 \ \beta_p}{q_*^2}
$$

7. Substitute *A* and *C* back into the solutions. Define $=\frac{\beta_t q^2}{q} = \epsilon \beta_p \sim 1,$ $v = \frac{\beta_t q^2}{\epsilon} = \epsilon \beta_p \sim 1, \rho = r/a$

$$
\frac{\Psi_0}{a^2 B_0} = \frac{1}{2q_*} \Big[\rho^2 - 1 + v \Big(\rho^3 - \rho \Big) \cos \theta \Big]
$$

$$
\frac{B_\theta}{\epsilon B_0} = \frac{1}{q_*} \Big[\rho + \frac{v}{2} \Big(3\rho^2 - 1 \Big) \cos \theta \Big]
$$

$$
\frac{B_r}{\epsilon B_0} = -\frac{v}{2q_*} \Big(\rho^2 - 1 \Big) \sin \theta
$$

$$
\frac{2\mu_0 p}{B_0^2} = 2\beta_t \Big(1 - \rho^2 \Big) \Big(1 + v \rho \cos \theta \Big)
$$

$$
\frac{\mu_0 R_0 J_\phi}{B_0} = -\frac{2}{q_*} \Big(1 + 2v \rho \cos \theta \Big)
$$

$$
\frac{B_\phi}{B_0} = 1 - \epsilon \rho \cos \theta - \beta_t \Big(1 - \rho^2 \Big) \Big(1 + v \rho \cos \theta \Big)
$$

Properties of High Beta Tokamak Equilibria

- B_{ϕ} P $\stackrel{B}{\searrow}$ R R_0 R_0 -a $R_0 + a$
- 1. Sketched below are typical midplane profiles (*Z*=0) showing radial pressure balance.

2. Shown here are p and J_{ϕ} profiles along the midplane for different v . Increasing ν implies higher $β$.

- a. Observe the increased shift of the magnetic axis as β increases.
- b. Observe the buildup of current on the outside of the torus to produce toroidal force balance at higher β .
- c. Observe J_{ϕ} reversing on the inside of the torus when $v > 1/2$.
- 3. The flux surfaces are "round", but are not circles except for the boundary

$$
\rho = 1 \text{ CIRCLE}
$$

- 4. Let us calculate the magnetic axis shift Δ_0 by finding the value of *r* where $\frac{\partial \psi}{\partial r} \propto \frac{\partial p}{\partial r} = 0$. By symmetry this occurs when $\theta = O($ or $\pi)$.
	- a. At $\theta = 0$

 $\rho^2 - 1 + v(\rho^3 - \rho)\cos\theta = \text{const}$

$$
\psi \propto \rho^2 - 1 + v \left(\rho^3 - \rho \right)
$$

b. Set

$$
\frac{\partial \psi}{\partial \rho} \bigg(\rho = \frac{\Delta_0}{a}, \theta = 0 \bigg) = 0
$$

c. This yields

$$
\frac{2\Delta_0}{a} + v \left(3\frac{\Delta_0^2}{a^2} - 1\right) = 0
$$

d. The value of Δ_0 is given by

$$
\frac{\Delta_0}{a} = \frac{v}{1 + \left(1 + 3v^2\right)^{1/2}} \sim 1
$$

e. For the HBT
$$
v \sim 1 \rightarrow \frac{\Delta_0}{a} \sim 1
$$

Ohmic $Tv \sim \epsilon \rightarrow \frac{\Delta_0}{a} \sim \frac{v}{2} \sim \epsilon \ll 1$

- 5. Find the shape of the flux surfaces near the magnetic axis.
	- a. Let $x = \rho \cos \theta$ $y = \rho \sin \theta$
	- b. Then $\psi \propto (x^2 + y^2 1) [1 + \nu x]$
	- c. Expand $x = \frac{\Delta_0}{a} + \delta x$ $y = \delta y$ $\delta x, \delta y \ll 1$

and define $x_0 = \Delta_0 / a$

d. Substitute

$$
\psi \propto \left[x_0^2 + 2x_0 \delta x + (\delta x)^2 + (\delta y)^2 - 1 \right] \left[1 + v x_0 + v \delta x \right] = \text{const}
$$

$$
= \left(x_0^2 - 1 \right) \left(1 + v x_0 \right) + \delta x \left[2x_0 + 2v x_0^2 + v x_0^2 - v \right]
$$

0 definition of *x*⁰

$$
+\left(\delta y\right)^{2}\left(1+\nu x_{0}\right)+\left(\delta x\right)^{2}\left[1+\nu x_{0}+2\nu x_{0}\right]
$$

$$
(1+3\nu x_0)(\delta x)^2 + (1+\nu x_0)(\delta y)^2 = \text{const}
$$

e. This is the equation of an ellipse

elongated flux surfaces, squashed near the outside

f. The elongation κ_0 is defined by

$$
\kappa_0^2 = \frac{b^2}{a^2} = \frac{1 + 3v x_0}{1 + v x_0}
$$

$$
= \left(1 + 3v^2\right)^{1/2} \frac{\left[1 + \left(1 + 3v^2\right)^{1/2}\right]}{\left[1 + v^2 + \left(1 + 3v^2\right)^{1/2}\right]}
$$

 $\kappa_0^2 \approx 1$ for $\nu \ll 1$ and $\kappa_0^2 = 3/2$ for $\nu = 1$.