

13.42 HW#2 SOLUTIONS

1 a. GIVEN: $y(t) = \int_0^{t+\alpha} u(s) ds$

$$\begin{aligned} \bullet \int_0^{t+\alpha} [a_1 u_1(s) + a_2 u_2(s)] ds &= a_1 \int_0^{t+\alpha} u_1(s) ds + a_2 \int_0^{t+\alpha} u_2(s) ds \\ &= a_1 y_1(t) + a_2 y_2(t) \end{aligned}$$

\therefore LINEAR

1.) RHS: $\int_0^{t+\alpha} u(s+\tau) ds$

$$\left[\begin{array}{ll} \text{LET } \xi = s + \tau & s = t + \alpha \longrightarrow \xi = t + \alpha + \tau \\ d\xi = ds & s = 0 \longrightarrow \xi = \tau \end{array} \right.$$

$$= \int_{\tau}^{t+\alpha+\tau} u(\xi) d\xi$$

2.) LHS: $y(t+\tau) = \int_0^{t+\tau+\alpha} u(s) ds$

RHS \neq LHS, \therefore NOT T.I.

b. GIVEN: $y(t) = \int_{t-\alpha}^{t+\alpha} [u(s)]^2 ds$

$$\begin{aligned} \bullet \int_{t-\alpha}^{t+\alpha} [a_1 u_1(s) + a_2 u_2(s)]^2 ds &\neq a_1 \int_{t-\alpha}^{t+\alpha} [u_1(s)]^2 ds + \\ &+ a_2 \int_{t-\alpha}^{t+\alpha} [u_2(s)]^2 ds \end{aligned}$$

\therefore NONLINEAR

$$\bullet \int_{t-\alpha}^{t+\alpha} [u(s+\tau)]^2 ds = \int_{t-\alpha+\tau}^{t+\alpha+\tau} [u(\xi)]^2 d\xi = y(t+\tau)$$

\therefore TIME INVARIANT.

c. GIVEN: $y(\tau) = \alpha \frac{du}{dt}(\tau) \left| \frac{du}{dt}(\tau) \right|$

• $\alpha \left(a_1 \frac{du_1}{dt} + a_2 \frac{du_2}{dt} \right) \left| a_1 \frac{du_1}{dt} + a_2 \frac{du_2}{dt} \right| \neq$

$a_1 \alpha \frac{du_1}{dt} \left| \frac{du_1}{dt} \right| + a_2 \alpha \frac{du_2}{dt} \left| \frac{du_2}{dt} \right|$

∴ NONLINEAR

• $\alpha \frac{du}{dt}(\tau + \tau) \left| \frac{du}{dt}(\tau + \tau) \right| = \alpha \frac{du}{dt}(\tau + \tau) \left| \frac{du}{dt}(\tau + \tau) \right|$
(RHS) (LHS)

∴ TIME INVARIANT

d. GIVEN: $\alpha \ddot{y}(t) + \beta \dot{y}(t) + \gamma y(t) = u(t)$

• $a_1 u_1 + a_2 u_2 = a_1 (\alpha \ddot{y}_1 + \beta \dot{y}_1 + \gamma y_1) + a_2 (\alpha \ddot{y}_2 + \beta \dot{y}_2 + \gamma y_2)$

∴ LINEAR

• $u(\tau + \tau) = \alpha \ddot{y}(\tau + \tau) + \beta \dot{y}(\tau + \tau) + \gamma y(\tau + \tau)$
(RHS) (LHS)

∴ TIME INVARIANT

2 a. $a_1 \cos \omega t \rightarrow$ LTI $\rightarrow a_2 \cos(\omega t + \phi)$

b. $\sin 5t \rightarrow$ NOT LTI $\rightarrow 2 \cos(10t + \pi)$

$$\begin{aligned} 3a. \quad \tilde{f}(\omega) &= \int_{-\infty}^{\infty} f(t) e^{-i\omega t} dt \\ &= \int_{-\infty}^{\infty} u_0(t-\tau) e^{-i\omega t} dt \\ &= \underline{e^{-i\omega\tau}} \end{aligned}$$

$$b. \quad \int_{-\infty}^{\infty} \frac{df}{dx} e^{-i\alpha x} dx \quad \left[\begin{array}{l} \text{LET } u = e^{-i\alpha x}, \quad du = \frac{df}{dx} dx \\ du = -i\alpha e^{-i\alpha x} dx, \quad v = f \end{array} \right]$$

$$= \left[f e^{-i\alpha x} \right]_{-\infty}^{\infty} - \int_{-\infty}^{\infty} f (-i\alpha) e^{-i\alpha x} dx$$

$$= 0 + i\alpha \int_{-\infty}^{\infty} f e^{-i\alpha x} dx$$

$$= \underline{i\alpha \tilde{f}(\alpha)}$$

$$c. \quad \int_{-\infty}^{\infty} \frac{d^2 f}{dx^2} e^{-i\alpha x} dx \quad \left[\begin{array}{l} \text{LET } u = e^{-i\alpha x}, \quad du = \frac{d^2 f}{dx^2} dx \\ du = -i\alpha e^{-i\alpha x} dx, \quad v = \frac{df}{dx} \end{array} \right]$$

$$= \left[\frac{df}{dx} e^{-i\alpha x} \right]_{-\infty}^{\infty} - \int_{-\infty}^{\infty} \frac{df}{dx} (-i\alpha e^{-i\alpha x}) dx$$

$$= 0 + i\alpha \underbrace{\int_{-\infty}^{\infty} \frac{df}{dx} e^{-i\alpha x} dx}_{= i\alpha \tilde{f}(\alpha)}$$

$$= \underline{(i\alpha)^2 \tilde{f}(\alpha)}$$

4 a. GIVEN: $m\ddot{x}(t) + c\dot{x}(t) + kx(t) = f(t)$

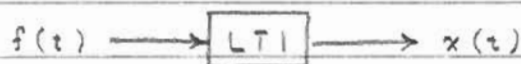
$$f(t) = \text{Re} \{ F e^{i\omega t} \}$$

$$x(t) = \text{Re} \{ X e^{i\omega t} \}$$

$$\rightarrow m(-\omega^2) X e^{i\omega t} + c i \omega X e^{i\omega t} + k X e^{i\omega t} = F e^{i\omega t}$$

$$(-\omega^2 m + i\omega c + k) X = F$$

FROM READING 3, WE KNOW THAT, GIVEN



$$X(\omega) = H(\omega) F(\omega)$$

$$\therefore H(\omega) = \frac{1}{-\omega^2 m + i\omega c + k}$$

b. LET $f_1(t) = \text{Re} \{ F_1 e^{i\omega t} \}$ & $f_2(t) = \text{Re} \{ F_2 e^{i\omega t} \}$

$$\text{THEN } f(t) = \alpha \text{Re} \{ F_1 e^{i\omega t} \} + \beta \text{Re} \{ F_2 e^{i\omega t} \}$$

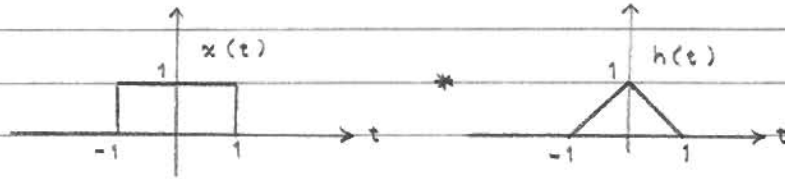
$$= \text{Re} \left\{ \underbrace{(\alpha F_1 + \beta F_2)}_F e^{i\omega t} \right\}$$

• $X = H(\omega) F$

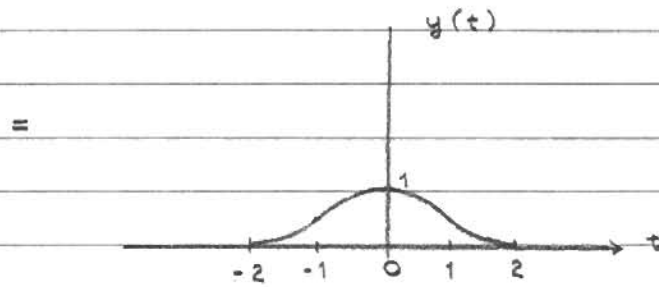
$$= \frac{\alpha F_1 + \beta F_2}{-\omega^2 m + i\omega c + k}$$

AND $x(t) = \text{Re} \left\{ \frac{(\alpha F_1 + \beta F_2)}{-\omega^2 m + i\omega c + k} e^{i\omega t} \right\}$

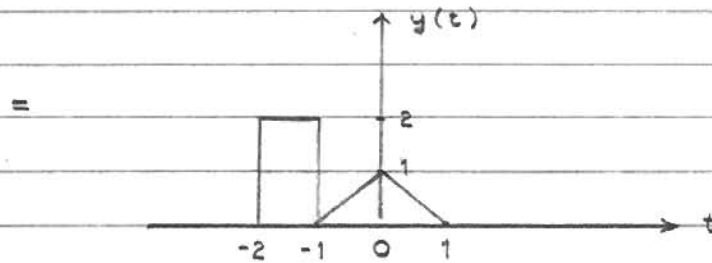
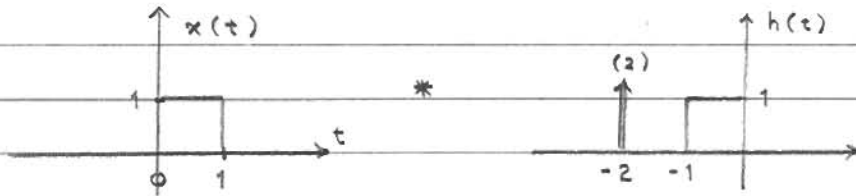
5a.



$$y(t) = x(t) * h(t)$$
$$= \int_{-\infty}^{\infty} x(\tau) h(t-\tau) d\tau$$



b.



6a. LET $f(t) = f_0 \cos(\omega_0 t + \psi)$

$$= \text{Re} \{ f_0 e^{i(\omega_0 t + \psi)} \}$$

$$= \text{Re} \{ F_0 e^{i\omega_0 t} \} \quad \text{WHERE } F_0 = f_0 e^{i\psi}$$

AND $y(t) = h(t) * f(t) :$

$$\bullet y(t) = \int_{-\infty}^{\infty} h(\tau) f(t-\tau) d\tau$$

$$= \int_{-\infty}^{\infty} h(\tau) \text{Re} \{ F_0 e^{i\omega_0(t-\tau)} \} d\tau$$

$$= \text{Re} \left\{ \int_{-\infty}^{\infty} h(\tau) e^{-i\omega_0 \tau} F_0 e^{i\omega_0 t} d\tau \right\}$$

$$= \text{Re} \{ H(\omega_0) F_0 e^{i\omega_0 t} \}$$

$$\text{LET } H(\omega_0) = |H(\omega_0)| e^{i\varphi}$$

$$= \text{Re} \{ |H(\omega_0)| f_0 e^{i(\omega_0 t + \psi + \varphi)} \}$$

$$= |H(\omega_0)| f_0 \cos(\omega_0 t + \psi + \varphi)$$