

3.185 - Recitation Notes

September 04/05, 2003

Topics Covered:

- Dot Product
- Cross Product
- Outer Product
- Gradient of Scalar Field
- Divergence of a Vector Field
- Curl of a Vector Field
- Ordinary Differential Equation
- Error Function
- Substantial Derivative of Scalar Field

Dot Product

$$\begin{aligned}u &= (u_1 \quad u_2 \quad u_3) \\v &= (v_1 \quad v_2 \quad v_3) \\u \cdot v &= u_1 v_1 + u_2 v_2 + u_3 v_3\end{aligned}$$

Cross Product

$$\begin{aligned}u \times v &= \begin{vmatrix} i & j & k \\ u_1 & u_2 & u_3 \\ v_1 & v_2 & v_3 \end{vmatrix} \\u \times v &= (u_2 v_3 - u_3 v_2)i + (u_3 v_1 - u_1 v_3)j + (u_1 v_2 - u_2 v_1)k\end{aligned}$$

Outer Product

$$u \otimes v = \begin{pmatrix} u_1 v_1 & u_1 v_2 & u_1 v_3 \\ u_2 v_1 & u_2 v_2 & u_2 v_3 \\ u_3 v_1 & u_3 v_2 & u_3 v_3 \end{pmatrix}$$

Del Operator

$$\nabla = i \frac{\partial}{\partial x} + j \frac{\partial}{\partial y} + k \frac{\partial}{\partial z}$$

Gradient of Scalar Field

Suppose $\phi(x,y,z)$ is a scalar field

$$\text{Grad } \phi(x,y,z) = \nabla \phi(x,y,z) = \frac{\partial \phi}{\partial x} i + \frac{\partial \phi}{\partial y} j + \frac{\partial \phi}{\partial z} k$$

Divergence of a Vector Field

Suppose $\mathbf{F}(x,y,z)$ is a vector field: $\mathbf{F} = F_1(x,y,z)\mathbf{i} + F_2(x,y,z)\mathbf{j} + F_3(x,y,z)\mathbf{k}$

$$\text{Div. } \mathbf{F}(x,y,z) = \nabla \cdot \vec{F}(x,y,z) = \frac{\partial F_1}{\partial x} + \frac{\partial F_2}{\partial y} + \frac{\partial F_3}{\partial z} = \text{A scalar}$$

Interpretation of the *divergence*: "... a measure of the rate at which the field 'diverges' or 'spread away' from a point".

Curl of a Vector Field

Suppose $\mathbf{F}(x,y,z)$ is a vector field: $\mathbf{F} = F_1(x,y,z)\mathbf{i} + F_2(x,y,z)\mathbf{j} + F_3(x,y,z)\mathbf{k}$

$$\text{Curl } \mathbf{F}(x,y,z) = \nabla \times \vec{F}(x,y,z) = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ F_1 & F_2 & F_3 \end{vmatrix}$$

$$\nabla \times \vec{F}(x,y,z) = \left(\frac{\partial F_3}{\partial y} - \frac{\partial F_2}{\partial z} \right) \mathbf{i} + \left(\frac{\partial F_1}{\partial z} - \frac{\partial F_3}{\partial x} \right) \mathbf{j} + \left(\frac{\partial F_2}{\partial x} - \frac{\partial F_1}{\partial y} \right) \mathbf{k} = \text{A vector}$$

Interpretation of the *curl*: "... measures the extent to which the vector field \mathbf{F} 'swirls' around a point".

Ordinary Differential Equation

- 1st order

Ex.: $\frac{dy}{dx} = ky \dots$ the solution is $y = ce^{kx}$

- 2nd order

Ex.: $\frac{d^2y}{dx^2} - y = 0$

By inspection, one of the solutions is $y = ce^x$, but wait... $y = ce^{-x}$ is also a solution. In fact, the linear combination of any individual solution is also a solution; therefore, $y = c_1e^{kx} + c_2e^{-kx}$ is also a solution. Boundary conditions are required to identify the particular solution from the family of solutions.

For more general 2nd order ODE, we can write $ay'' + by' + cy = g(x)$.

When $g(x) = 0$, the ODE is said to be homogeneous - $ay'' + by' + cy = 0$

Let's suppose the solution to the homogeneous 2nd order ODE is: $y = e^{rx}$

$$y' = re^{rx}$$

$$y'' = r^2e^{rx}$$

$$ay'' + by' + cy = 0$$

$$(ar^2 + br + c)e^{rx} = 0$$

$$\text{since } e^{rx} \neq 0$$

$$ar^2 + br + c = 0$$

(this is called the characteristic equation)

Note: The quadratic equation has two roots, which can be real, complex or repeated.
The complete solution to $ay'' + by' + cy = 0$ is

$$y = c_1 e^{r_1 x} + c_2 e^{r_2 x}$$

(This can be verified easily by back substitution)

Error Function

Definition:

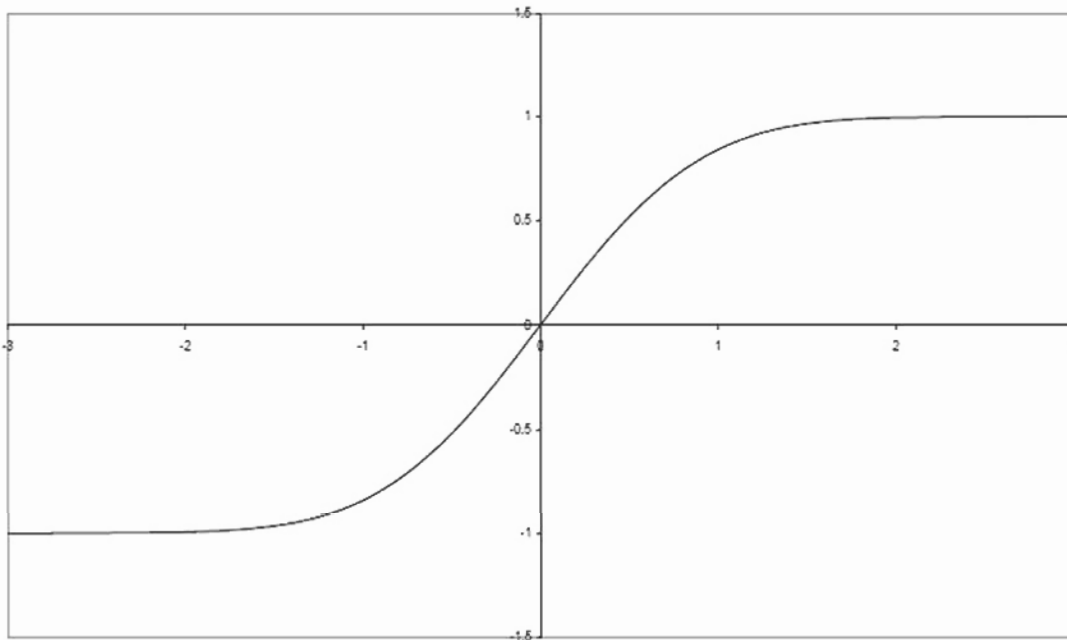
$$\operatorname{erf}(x) = \frac{2}{\sqrt{\pi}} \int_0^x e^{-\zeta^2} d\zeta$$

Some properties:

$$\operatorname{erf}(0) = 0$$

$$\operatorname{erf}(\infty) = 1$$

$$\operatorname{erf}(-x) = -\operatorname{erf}(x)$$



Substantial Derivative

Definition:

$$\frac{D}{Dt} = \frac{\partial}{\partial t} + v_x \frac{\partial}{\partial x} + v_y \frac{\partial}{\partial y} + v_z \frac{\partial}{\partial z}$$

$$v_x = \frac{dx}{dt}$$

$$\text{where } v_y = \frac{dy}{dt}$$

$$v_z = \frac{dz}{dt}$$

$$\frac{D}{Dt} = \underbrace{\frac{\partial}{\partial t}}_{\substack{\text{local} \\ \text{rate} \\ \text{of} \\ \text{change}}} + \underbrace{v_x \frac{\partial}{\partial x} + v_y \frac{\partial}{\partial y} + v_z \frac{\partial}{\partial z}}_{\text{rate of change due to motion}}$$

Also read *WR* p.111

Reminder: Thursday recitation time change: 1:00am – 1:00pm?