

Introduction to Simulation - Lecture 10

Modified Newton Methods

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Thanks to Deepak Ramaswamy, Jaime Peraire, Michal Rewienski, and Karen Veroy

Outline

- Damped Newton Schemes
 - Globally Convergent if Jacobian is Nonsingular
 - Difficulty with Singular Jacobians
- Introduce Continuation Schemes
 - Problem with Source/Load stepping
 - More General Continuation Scheme
- Improving Continuation Efficiency
 - Better first guess for each continuation step
- Arc Length Continuation

Multidimensional Newton Method

Newton Algorithm

Newton Algorithm for Solving $F(x) = 0$

$x^0 =$ Initial Guess, $k = 0$

Repeat {

 Compute $F(x^k), J_F(x^k)$

 Solve $J_F(x^k)(x^{k+1} - x^k) = -F(x^k)$ for x^{k+1}

$k = k + 1$

} Until $\|x^{k+1} - x^k\|, \|F(x^{k+1})\|$ small enough

Multidimensional Newton Method

Multidimensional Convergence Theorem

Theorem Statement

Main Theorem

If

a) $\|J_F^{-1}(x^k)\| \leq \beta$ (Inverse is bounded)

b) $\|J_F(x) - J_F(y)\| \leq \ell \|x - y\|$ (Derivative is Lipschitz Cont)

**Then Newton's method converges given a sufficiently
close initial guess**

Multidimensional Newton Method

Multidimensional Convergence Theorem

Implications

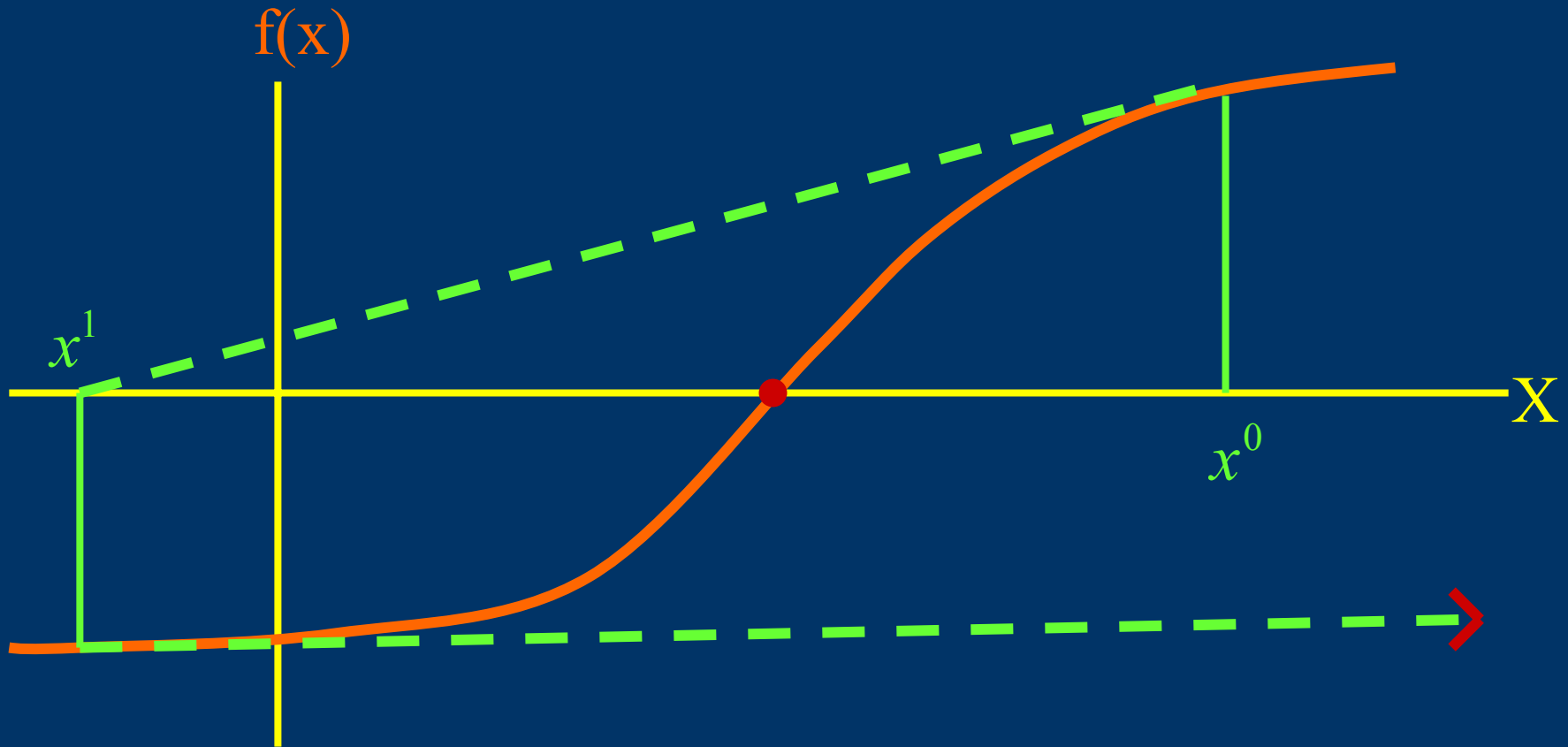
If a function's first derivative never goes to zero, and its second derivative is never too large...

Then Newton's method can be used to find the zero of the function *provided you all ready know the answer.*

Need a way to develop Newton methods which converge regardless of initial guess!

Non-converging Case

1-D Picture



Limiting the changes in X might improve convergence

Newton Method with Limiting

Newton Algorithm

Newton Algorithm for Solving $F(x) = 0$

$x^0 =$ Initial Guess, $k = 0$

Repeat {

 Compute $F(x^k), J_F(x^k)$

 Solve $J_F(x^k)\Delta x^{k+1} = -F(x^k)$ for Δx^{k+1}

$x^{k+1} = x^k + \text{limited}(\Delta x^{k+1})$

$k = k + 1$

} Until $\|\Delta x^{k+1}\|, \|F(x^{k+1})\|$ small enough

Newton Method with Limiting

Damped Newton Scheme

General Damping Scheme

Solve $J_F(x^k) \Delta x^{k+1} = -F(x^k)$ for Δx^{k+1}

$$x^{k+1} = x^k + \alpha^k \Delta x^{k+1}$$

Key Idea: Line Search

Pick α^k to minimize $\left\| F(x^k + \alpha^k \Delta x^{k+1}) \right\|_2^2$

$$\left\| F(x^k + \alpha^k \Delta x^{k+1}) \right\|_2^2 \equiv F(x^k + \alpha^k \Delta x^{k+1})^T F(x^k + \alpha^k \Delta x^{k+1})$$

Method Performs a one-dimensional search in
Newton Direction

Newton Method with Limiting

Damped Newton

Convergence Theorem

If

a) $\|J_F^{-1}(x^k)\| \leq \beta$ (Inverse is bounded)

b) $\|J_F(x) - J_F(y)\| \leq \ell \|x - y\|$ (Derivative is Lipschitz Cont)

Then

There exists a set of α^k 's $\in (0, 1]$ such that

$$\|F(x^{k+1})\| = \|F(x^k + \alpha^k \Delta x^{k+1})\| < \gamma \|F(x^k)\| \text{ with } \gamma < 1$$

Every Step reduces F-- Global Convergence!

Newton Method with Limiting

Damped Newton

Nested Iteration

$x^0 =$ Initial Guess, $k = 0$

Repeat {

Compute $F(x^k), J_F(x^k)$

Solve $J_F(x^k)\Delta x^{k+1} = -F(x^k)$ for Δx^{k+1}

Find $\alpha^k \in (0,1]$ such that $\|F(x^k + \alpha^k \Delta x^{k+1})\|$ is minimized

$x^{k+1} = x^k + \alpha^k \Delta x^{k+1}$

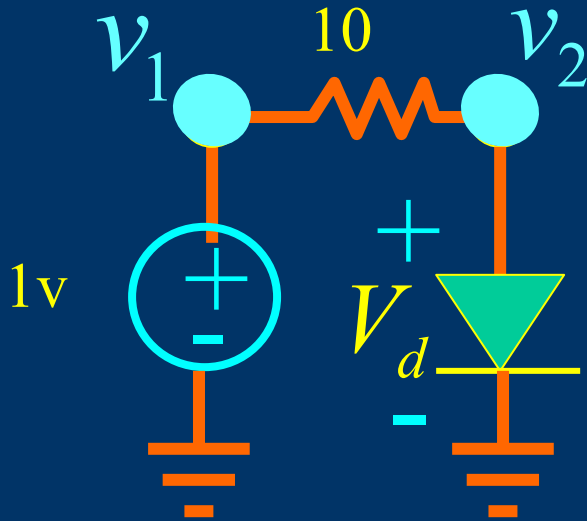
$k = k + 1$

} Until $\|\Delta x^{k+1}\|, \|F(x^{k+1})\|$ small enough

Newton Method with Limiting

Damped Newton

Example



$$I_r - \frac{1}{10} V_r = 0$$

$$I_d - I_s (e^{V_d/V_t} - 1) = 0$$

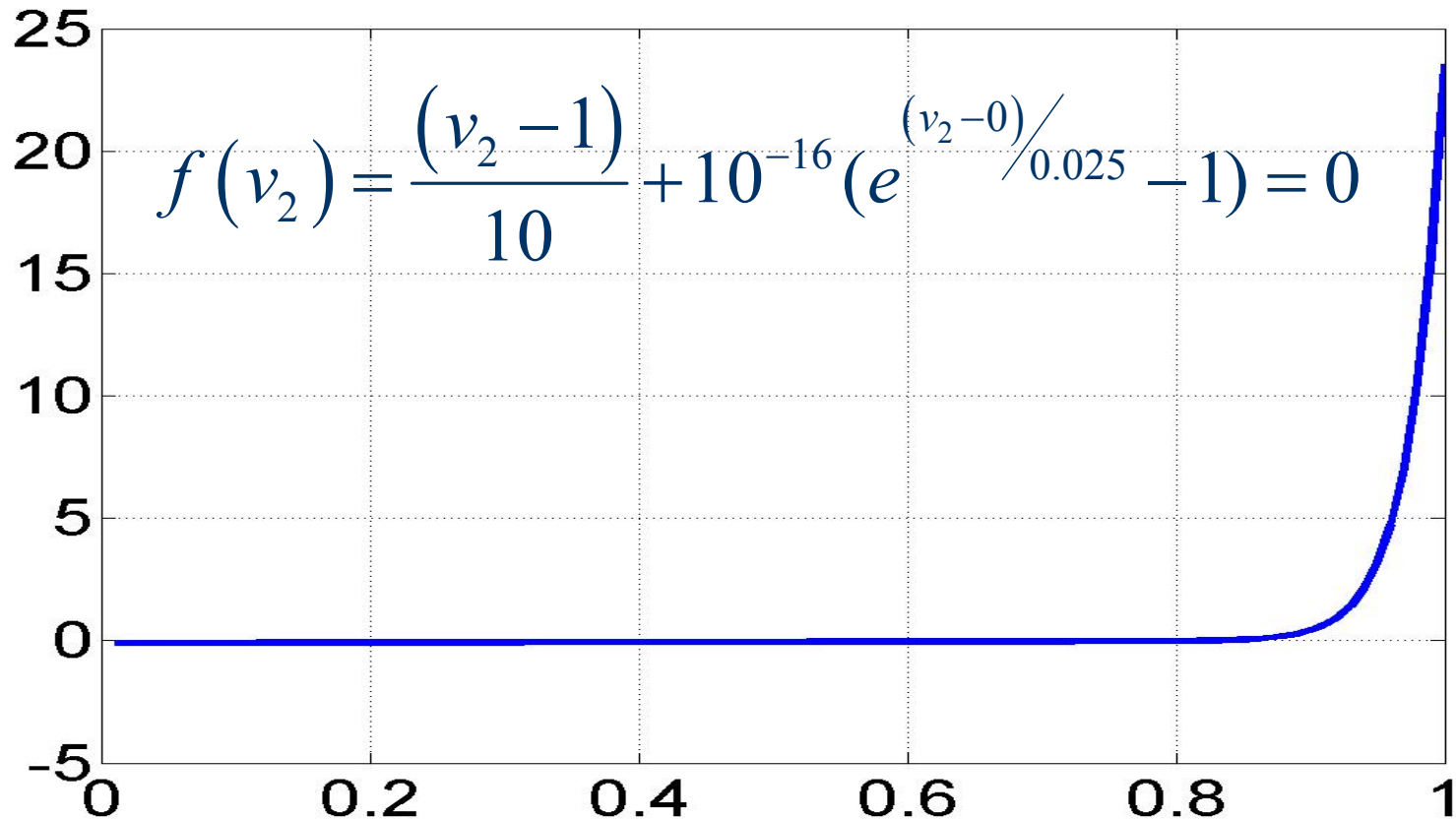
Nodal Equations with Numerical Values

$$f(v_2) = \frac{(v_2 - 1)}{10} + 10^{-16} (e^{(v_2 - 0)/0.025} - 1) = 0$$

Newton Method with Limiting

Damped Newton

Example cont.



Newton Method with Limiting

Damped Newton

Nested Iteration

$x^0 =$ Initial Guess, $k = 0$

Repeat {

 Compute $F(x^k), J_F(x^k)$

 Solve $J_F(x^k)\Delta x^{k+1} = -F(x^k)$ for Δx^{k+1}

 Find $\alpha^k \in (0,1]$ such that $\|F(x^k + \alpha^k \Delta x^{k+1})\|$ is minimized

$x^{k+1} = x^k + \alpha^k \Delta x^{k+1}$

$k = k + 1$

} Until $\|\Delta x^{k+1}\|, \|F(x^{k+1})\|$ small enough

How can one find the damping coefficients?

Newton Method with Limiting

Damped Newton

Theorem Proof

By definition of the Newton Iteration

$$x^{k+1} = x^k - \alpha^k \underbrace{J_F(x^k)^{-1} F(x^k)}_{\text{Newton Direction}}$$

Multidimensional Mean Value Lemma

$$\|F(x) - F(y) - J_F(y)(x - y)\| \leq \frac{\ell}{2} \|x - y\|^2$$

Combining

$$\left\| F(x^{k+1}) - F(x^k) + J_F(x^k) \left[\alpha^k J_F(x^k)^{-1} F(x^k) \right] \right\| \leq \frac{\ell}{2} \left\| \alpha^k J_F(x^k)^{-1} F(x^k) \right\|^2$$

Newton Method with Limiting

Damped Newton

Theorem Proof-Cont

From the previous slide

$$\left\| F(x^{k+1}) - F(x^k) + J_F(x^k) \left[\alpha^k J_F(x^k)^{-1} F(x^k) \right] \right\| \leq \frac{\ell}{2} \left\| \alpha^k J_F(x^k)^{-1} F(x^k) \right\|^2$$

Combining terms and moving scalars out of norms

$$\left\| F(x^{k+1}) - (1 - \alpha^k) F(x^k) \right\| \leq (\alpha^k)^2 \frac{\ell}{2} \left\| J_F(x^k)^{-1} F(x^k) \right\|^2$$

Using the Jacobian Bound and splitting the norm

$$\left\| F(x^{k+1}) \right\| \leq \left[(1 - \alpha^k) \left\| F(x^k) \right\| + (\alpha^k)^2 \frac{\beta^2 \ell}{2} \left\| F(x^k) \right\|^2 \right]$$

Yields a quadratic in the damping coefficient

Newton Method with Limiting

Damped Newton

Theorem Proof-Cont-II

Simplifying quadratic from previous slide

$$\|F(x^{k+1})\| \leq \left[1 - \alpha^k + (\alpha^k)^2 \frac{\beta^2 \ell}{2} \|F(x^k)\| \right] \|F(x^k)\|$$

Two Cases:

$$1) \frac{\beta^2 \ell}{2} \|F(x^k)\| < \frac{1}{2} \quad \text{Pick } \alpha^k = 1 \text{ (Standard Newton)}$$

$$\Rightarrow \left(1 - \alpha^k + (\alpha^k)^2 \frac{\beta^2 \ell}{2} \|F(x^k)\| \right) < \frac{1}{2}$$

$$2) \frac{\beta^2 \ell}{2} \|F(x^k)\| > \frac{1}{2} \quad \text{Pick } \alpha^k = \frac{1}{\beta^2 \ell \|F(x^k)\|}$$

$$\Rightarrow \left(1 - \alpha^k + (\alpha^k)^2 \frac{\beta^2 \ell}{2} \|F(x^k)\| \right) < 1 - \frac{1}{2\beta^2 \ell \|F(x^k)\|}$$

Newton Method with Limiting

Damped Newton

Theorem Proof-Cont-III

Combining the results from the previous slide

$$\|F(x^{k+1})\| \leq \gamma^k \|F(x^k)\| \quad \text{not good enough, need } \gamma \text{ independent from } k$$

The above result does imply

$$\|F(x^{k+1})\| \leq \|F(x^0)\| \quad \text{not yet a convergence theorem}$$

For the case where $\frac{\beta^2 \ell}{2} \|F(x^k)\| > \frac{1}{2}$

$$1 - \frac{1}{2\beta^2 \ell \|F(x^k)\|} \leq 1 - \frac{1}{2\beta^2 \ell \|F(x^0)\|} \leq \gamma^0$$

Note the proof technique

First – Show that the iterates do not increase

Second – Use the non-increasing fact to prove convergence

Newton Method with Limiting

Damped Newton

Nested Iteration

$x^0 =$ Initial Guess, $k = 0$

Repeat {

 Compute $F(x^k), J_F(x^k)$

 Solve $J_F(x^k)\Delta x^{k+1} = -F(x^k)$ for Δx^{k+1}

 Find $\alpha^k \in (0,1]$ such that $\|F(x^k + \alpha^k \Delta x^{k+1})\|$ is minimized

$x^{k+1} = x^k + \alpha^k \Delta x^{k+1}$

$k = k + 1$

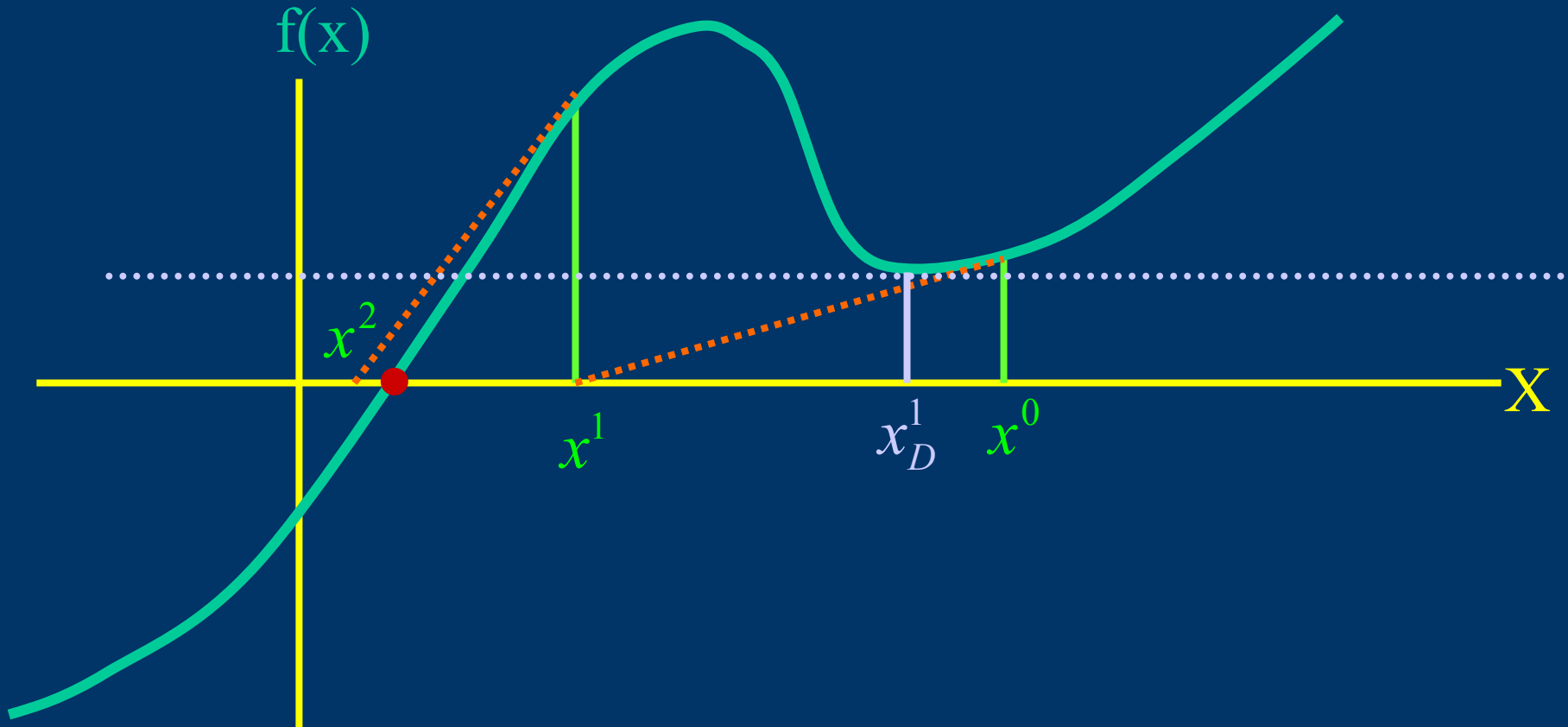
} Until $\|\Delta x^{k+1}\|, \|F(x^{k+1})\|$ small enough

Many approaches to finding α^k

Newton Method with Limiting

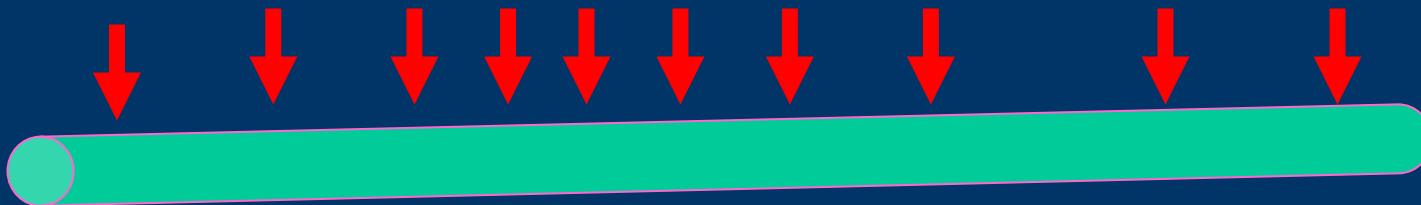
Damped Newton

Singular Jacobian Problem



Damped Newton Methods “push” iterates to local minimums
Finds the points where Jacobian is Singular

- Newton converges given a close initial guess
 - Generate a sequence of problems
 - Make sure previous problem generates guess for next problem
- Heat-conducting bar example

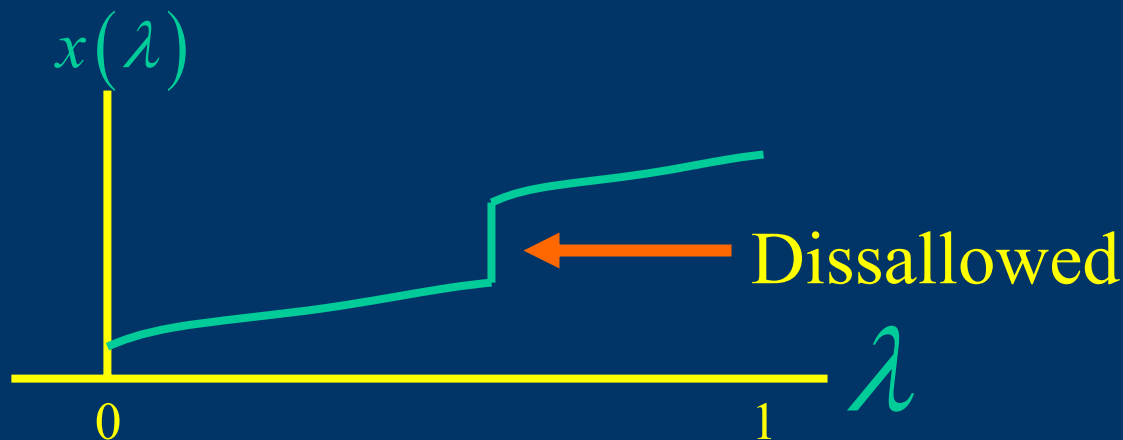


1. Start with heat off, $T=0$ is a very close initial guess
2. Increase the heat slightly, $T=0$ is a good initial guess
3. Increase heat again



Solve $\tilde{F}(x(\lambda), \lambda) = 0$ where:

- a) $\tilde{F}(x(0), 0) = 0$ is easy to solve Starts the continuation
- b) $\tilde{F}(x(1), 1) = F(x)$ Ends the continuation
- c) $x(\lambda)$ is sufficiently smooth Hard to insure!



Continuation Schemes

Basic Concepts

Template Algorithm

Solve $\tilde{F}(x(0), 0)$, $x(\lambda_{prev}) = x(0)$

$\delta\lambda = 0.01$, $\lambda = \delta\lambda$

While $\lambda < 1$ {

$x^0(\lambda) = x(\lambda_{prev})$

Try to Solve $\tilde{F}(x(\lambda), \lambda) = 0$ with Newton

If Newton Converged

$x(\lambda_{prev}) = x(\lambda)$, $\lambda = \lambda + \delta\lambda$, $\delta\lambda = 2\delta\lambda$

Else

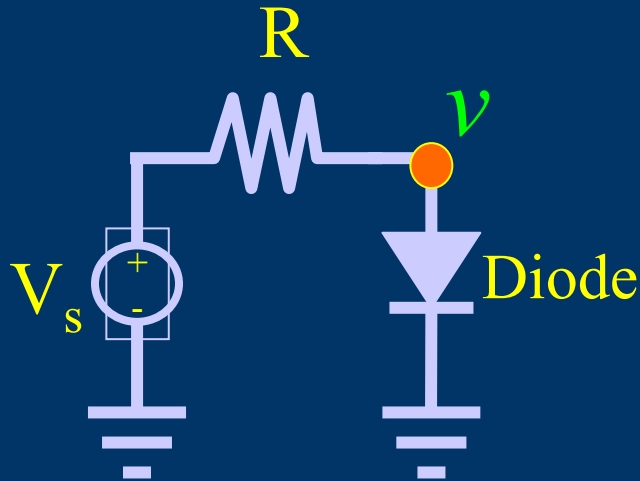
$\delta\lambda = \frac{1}{2}\delta\lambda$, $\lambda = \lambda_{prev} + \delta\lambda$

}

Continuation Schemes

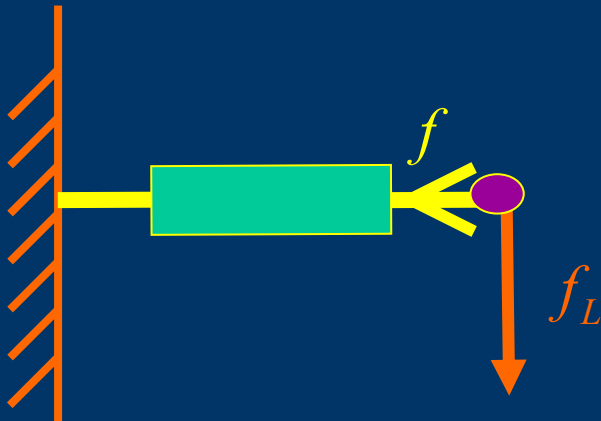
Basic Concepts

Source/Load Stepping Examples



$$\tilde{f}(v(\lambda), \lambda) = i_{diode}(v) + \frac{1}{R}(v - \lambda V_s) = 0$$

$$\frac{\partial \tilde{f}(v, \lambda)}{\partial v} = \frac{\partial i_{diode}(v)}{\partial v} + \frac{1}{R} \leftarrow \text{Not } \lambda \text{ dependent!}$$



$$\tilde{F}(\vec{x}, \lambda) = \begin{cases} f_x(x, y) = 0 \\ f_y(x, y) + \lambda f_l = 0 \end{cases}$$

Source/Load Stepping Does Not Alter Jacobian

Continuation Schemes

Jacobian Altering Scheme

Description

$$\tilde{F}(x(\lambda), \lambda) = \lambda F(x(\lambda)) + (1 - \lambda)x(\lambda)$$

Observations

$$\begin{aligned} \underline{\lambda=0} \quad \tilde{F}(x(0), 0) &= x(0) = 0 \\ \frac{\partial \tilde{F}(x(0), 0)}{\partial x} &= I \end{aligned}$$

Problem is easy to solve and Jacobian definitely nonsingular.

$$\begin{aligned} \underline{\lambda=1} \quad \tilde{F}(x(1), 1) &= F(x(1)) \\ \frac{\partial \tilde{F}(x(1), 1)}{\partial x} &= \frac{\partial F(x(1))}{\partial x} \end{aligned}$$

Back to the original problem and original Jacobian

Solve $\tilde{F}(x(0), 0)$, $x(\lambda_{prev}) = x(0)$
 $\delta\lambda = 0.01$, $\lambda = \delta\lambda$

While $\lambda < 1$ {

$$x^0(\lambda) = x(\lambda_{prev}) + ?$$

Try to Solve $\tilde{F}(x(\lambda), \lambda) = 0$ with Newton

If Newton Converged

$$x(\lambda_{prev}) = x(\lambda), \quad \lambda = \lambda + \delta\lambda, \quad \delta\lambda = 2\delta\lambda$$

Else

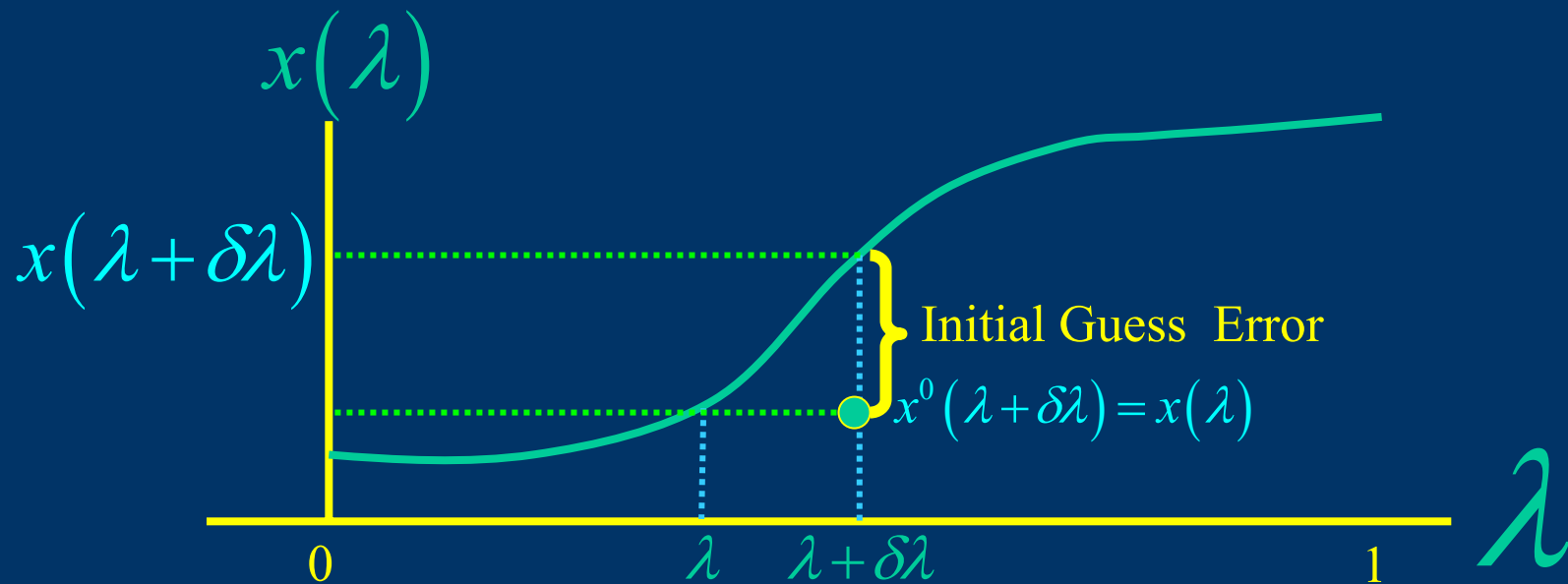
$$\delta\lambda = \frac{1}{2}\delta\lambda, \quad \lambda = \lambda_{prev} + \delta\lambda$$

}

Continuation Schemes

Jacobian Altering Scheme

Initial Guess for each step.



Continuation Schemes

Update Improvement

$$\tilde{F}(x(\lambda + \delta\lambda), \lambda + \delta\lambda) \approx \tilde{F}(x(\lambda), \lambda) + \frac{\partial \tilde{F}(x(\lambda), \lambda)}{\partial x} (x(\lambda + \delta\lambda) - x(\lambda)) + \frac{\partial \tilde{F}(x(\lambda), \lambda)}{\partial \lambda} \delta\lambda$$

$$\Rightarrow \underbrace{\frac{\partial \tilde{F}(x(\lambda), \lambda)}{\partial x}}_{\text{Have From last step's Newton}} \underbrace{(x^0(\lambda + \delta\lambda) - x(\lambda))}_{\text{Better Guess for next step's Newton}} = - \frac{\partial \tilde{F}(x(\lambda), \lambda)}{\partial \lambda} \delta\lambda$$

Continuation Schemes

Jacobian Altering Scheme

Update Improvement Cont.

If

$$\tilde{F}(x(\lambda), \lambda) = \lambda F(x(\lambda)) + (1 - \lambda)x(\lambda)$$

Then

$$\frac{\partial \tilde{F}(x, \lambda)}{\partial \lambda} = \underbrace{F(x) - x(\lambda)}$$

Easily Computed

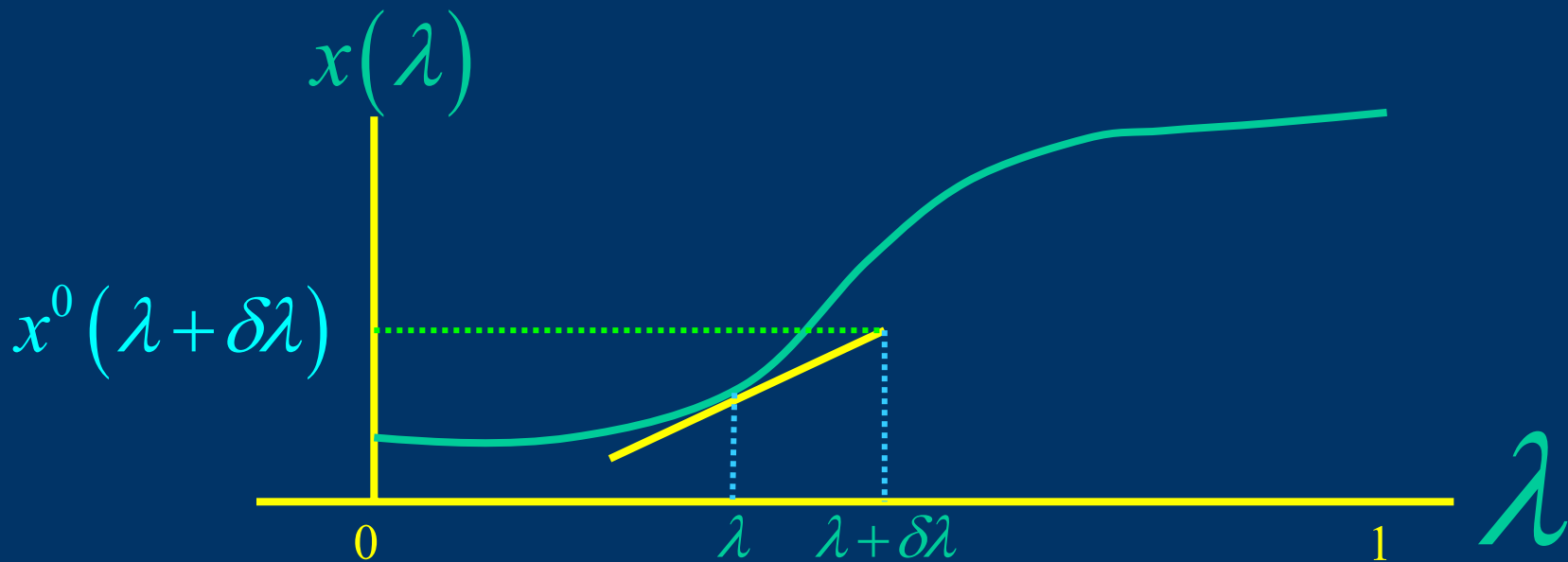
Continuation Schemes

Jacobian Altering Scheme

Update Improvement Cont. II.

$$x^0(\lambda + \delta\lambda) = x(\lambda) - \left(\frac{\partial \tilde{F}(x(\lambda), \lambda)}{\partial x} \right)^{-1} \frac{\partial \tilde{F}(x(\lambda), \lambda)}{\partial \lambda} \delta\lambda$$

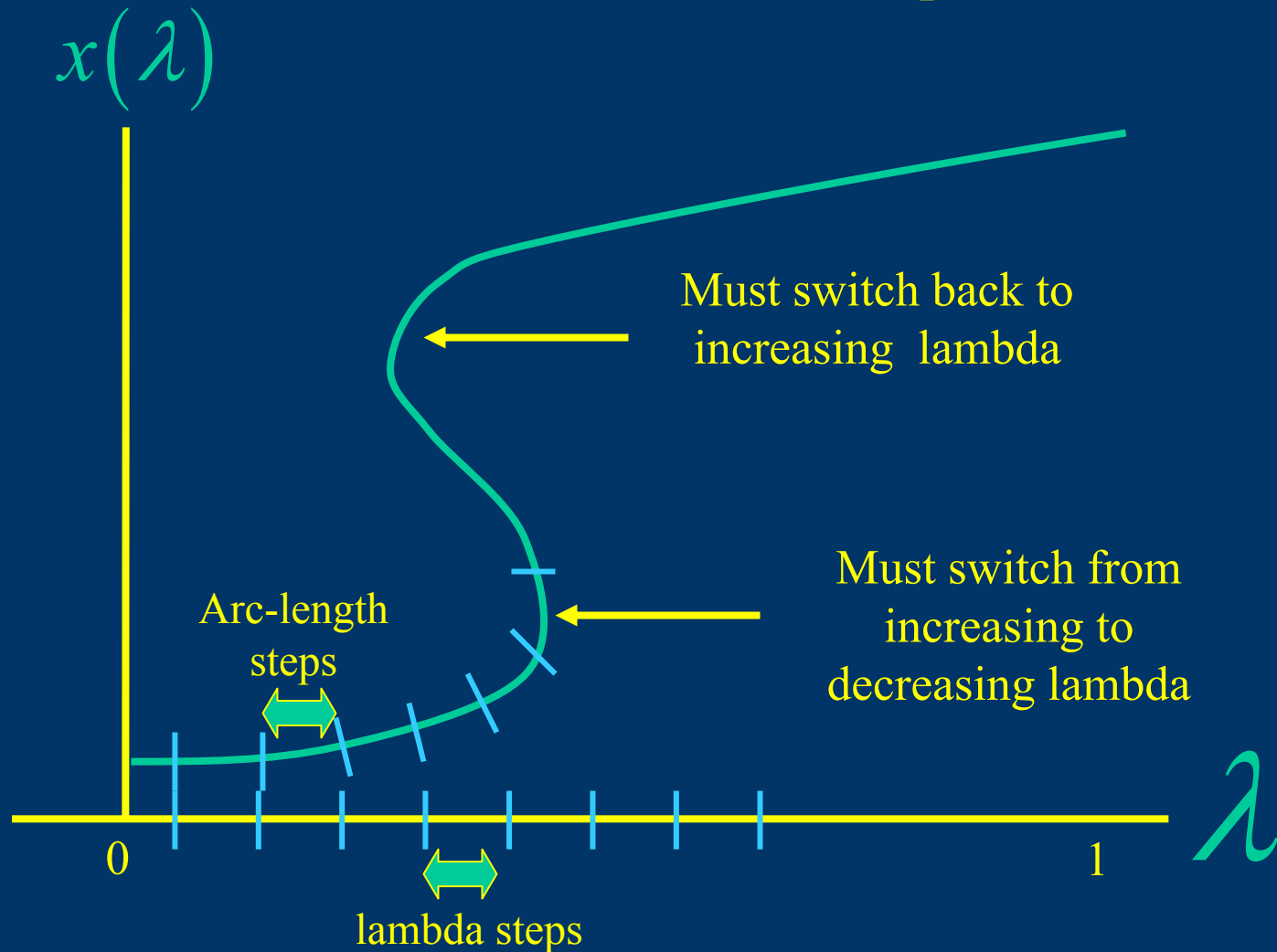
Graphically



Continuation Schemes

Jacobian Altering Scheme

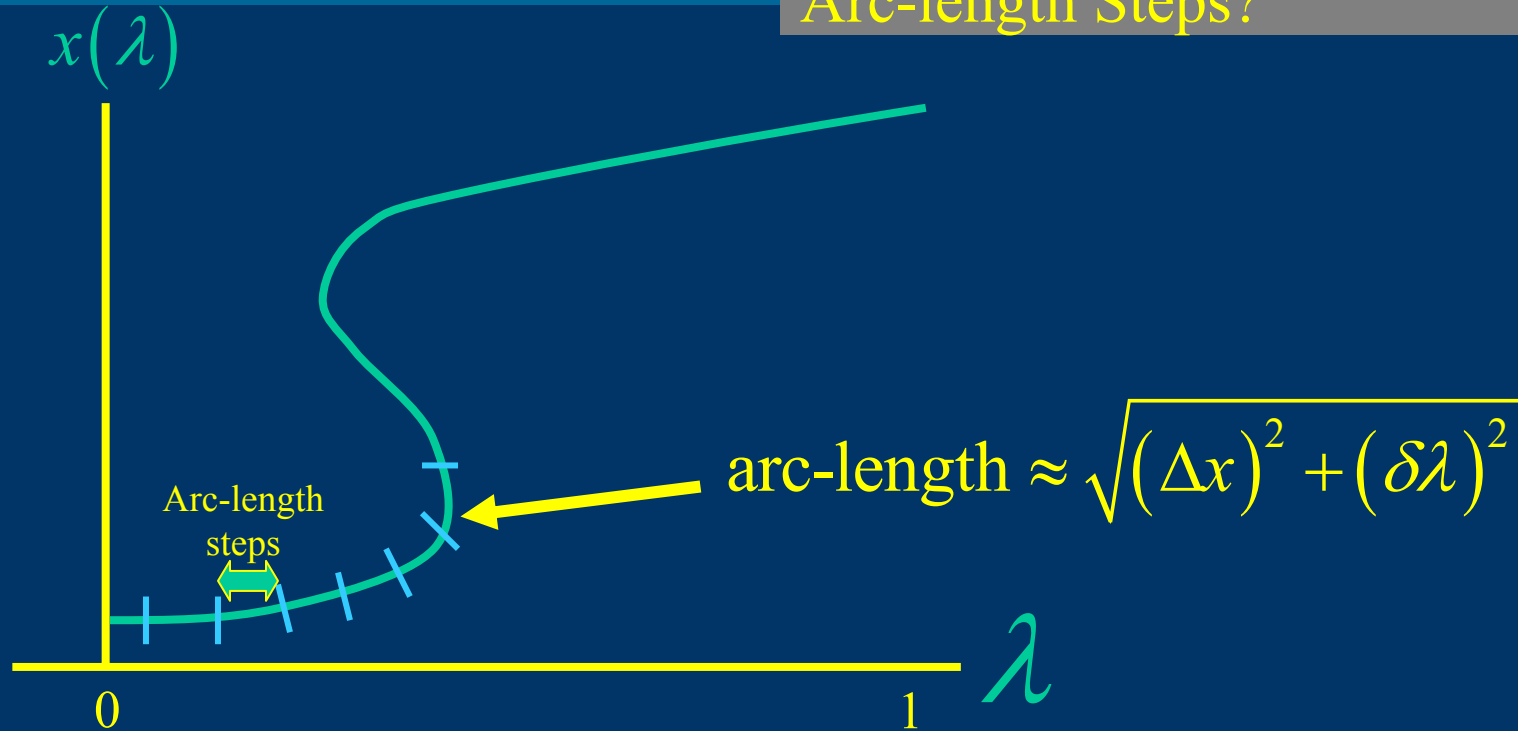
Still can have problems



Continuation Schemes

Jacobian Altering Scheme

Arc-length Steps?



Must Solve For Lambda

$$\tilde{F}(x, \lambda) = 0$$

$$(\lambda - \lambda_{prev})^2 + \|x - x(\lambda_{prev})\|_2^2 - arc^2 = 0$$

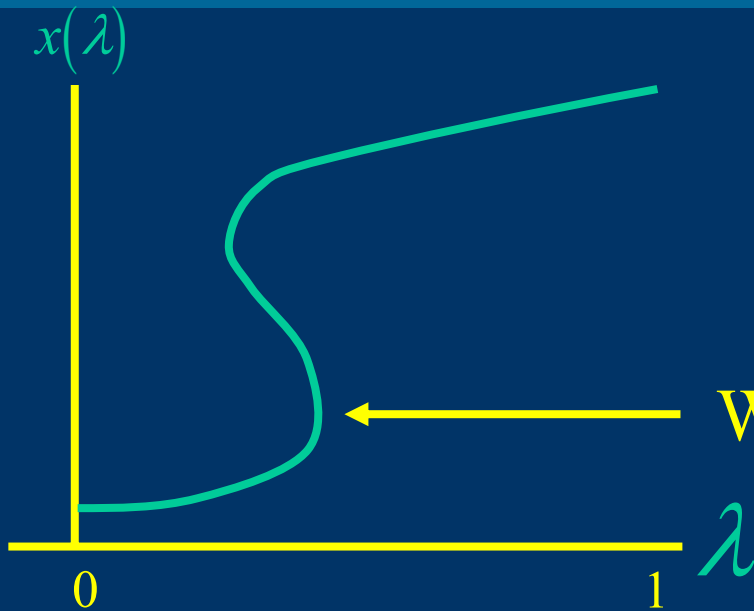
$$\begin{bmatrix} \frac{\partial \tilde{F}(x^k, \lambda^k)}{\partial x} & \frac{\partial \tilde{F}(x^k, \lambda^k)}{\partial \lambda} \\ 2(x^k - x(\lambda_{prev}))^T & 2(\lambda^k - \lambda_{prev}) \end{bmatrix} \begin{bmatrix} x^{k+1} - x^k \\ \lambda^{k+1} - \lambda^k \end{bmatrix} =$$

$$-\begin{bmatrix} \tilde{F}(x^k, \lambda^k) \\ (\lambda^k - \lambda_{prev})^2 + \|x^k - x(\lambda_{prev})\|_2^2 - arc^2 \end{bmatrix}$$

Continuation Schemes

Jacobian Altering Scheme

Arc-length Turning point



What happens here?

Upper left-hand
Block is singular

$$\begin{bmatrix} \frac{\partial \tilde{F}(x^k, \lambda^k)}{\partial x} & \frac{\partial \tilde{F}(x^k, \lambda^k)}{\partial \lambda} \\ 2(x^k - x(\lambda_{prev}))^T & 2(\lambda^k - \lambda_{prev}) \end{bmatrix}$$

Summary

- Damped Newton Schemes
 - Globally Convergent if Jacobian is Nonsingular
 - Difficulty with Singular Jacobians
- Introduce Continuation Schemes
 - Problem with Source/Load stepping
 - More General Continuation Scheme
- Improving Efficiency
 - Better first guess for each continuation step
- Arc-length Continuation