

# Discretization of the Poisson Problem in $\mathbb{R}^1$ : Theory and Implementation

April 7 & 9, 2003

# Theory

## Goals

*A priori...*

*A priori* error estimates:

N1

bound various “measures”

of  $u$  [exact]  $- u_h$  [approximate];

in terms of  $C(\Omega, \text{problem parameters})$ ,

$h$  [mesh diameter], and  $u$ .

# Theory

## Goals

...A priori...

$$u: \quad -u_{xx} = f, \quad u(0) = u(1) = 0$$

$$a(u, v) = \ell(v), \quad \forall v \in X$$

$$a(w, v) = \int_0^1 w_x v_x dx, \quad \ell(v) = \int_0^1 f v dx$$

$$X = \{v \in H^1(\Omega) \mid v(0) = v(1) = 0\}$$

# Theory

## Goals

...A priori

$u_h$ :

$$a(u_h, v) = \ell(v), \quad \forall v \in X_h$$

$$a(w, v) = \int_0^1 w_x v_x dx, \quad \ell(v) = \text{“} \int_0^1 f v dx \text{”}$$

$$X_h = \{v \in X \mid v|_{T_h} \in \mathbb{P}_1(T_h), \quad \forall T_h \in \mathcal{T}_h\}$$

# Theory

## Goals

*A posteriori*

*A posteriori* error estimates:

N2

bound various “measures”

of  $u$  [exact]  $- u_h$  [approximate];

in terms of  $C(\Omega, \text{problem parameters})$ ,

$h$  [mesh diameter], and  $u_h$ .

## Projection

### Theory

### Definition

Given Hilbert spaces  $Y$  and  $Z \subset Y$ ,

$$\underbrace{(\Pi y, v)}_{\in Z} = \underbrace{(y, v)}_{\in Y}, \quad \forall v \in Z$$

defines the *projection* of  $y$  onto  $Z$ ,  $\Pi y$ ;

$$\Pi: Y \rightarrow Z .$$

## Projection

## Theory

## Property

The projection  $\Pi \mathbf{y}$  minimizes  $\|\mathbf{y} - \mathbf{z}\|_{\mathbf{Y}}^2$ ,  $\forall \mathbf{z} \in \mathbf{Z}$ .

Why?

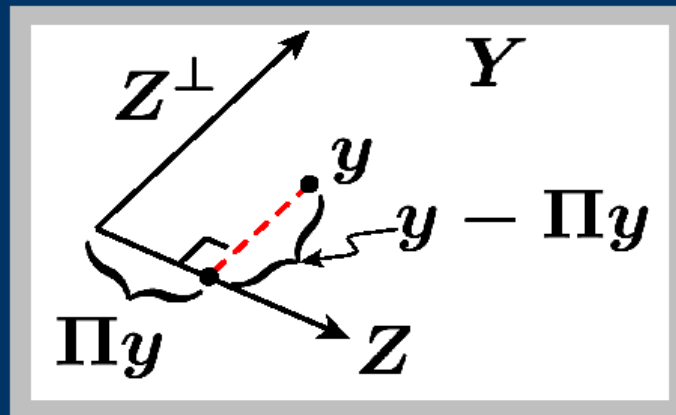
$$\begin{aligned} \|\mathbf{y} - \underbrace{(\Pi \mathbf{y} + \mathbf{v})}_{\text{any } \mathbf{z} \in \mathbf{Z}}\|_{\mathbf{Y}}^2 &= ((\mathbf{y} - \Pi \mathbf{y}) - \mathbf{v}, (\mathbf{y} - \Pi \mathbf{y}) - \mathbf{v})_{\mathbf{Y}} \\ &= \|\mathbf{y} - \Pi \mathbf{y}\|_{\mathbf{Y}}^2 - 2 \underbrace{(\mathbf{y} - \Pi \mathbf{y}, \mathbf{v})_{\mathbf{Y}}}_{0: \mathbf{v} \in \mathbf{Z}} + \|\mathbf{v}\|_{\mathbf{Y}}^2, \quad \forall \mathbf{v} \in \mathbf{Z}. \end{aligned}$$

# Projection

## Theory

## Geometry

Geometry of projection:



Orthogonality:  $(y - \Pi y, v)_Y = 0, \quad \forall v \in Z.$

E1



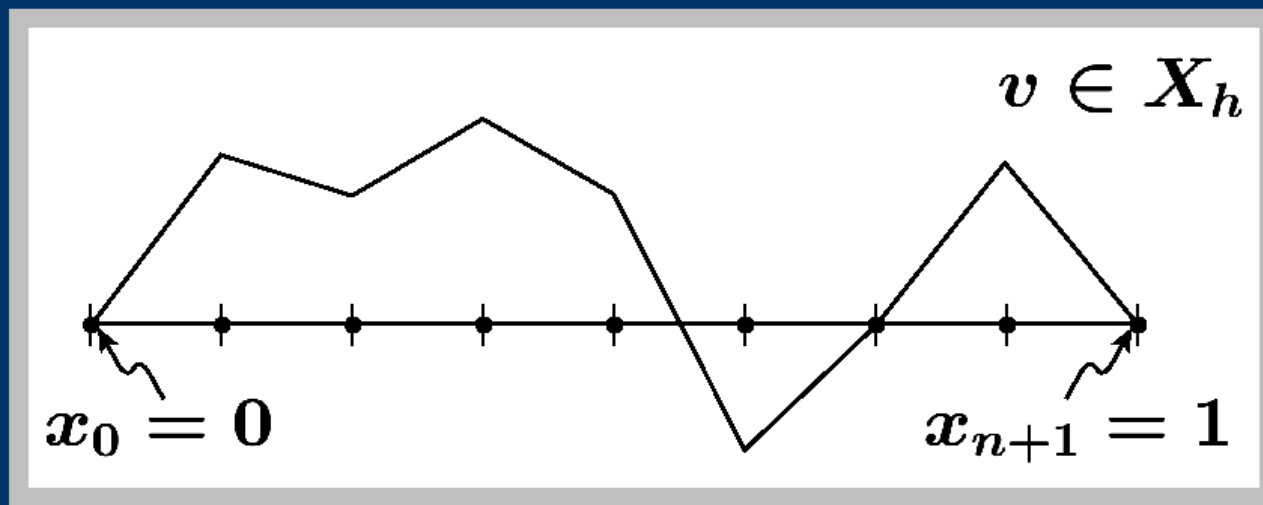
## The Interpolant

# Theory

Definition...

*Recall*

$$\mathbf{X}_h = \{v \in \mathbf{X} \mid v|_{T_h} \in \mathbb{P}_1(T_h), \quad \forall T_h \in \mathcal{T}_h\}$$



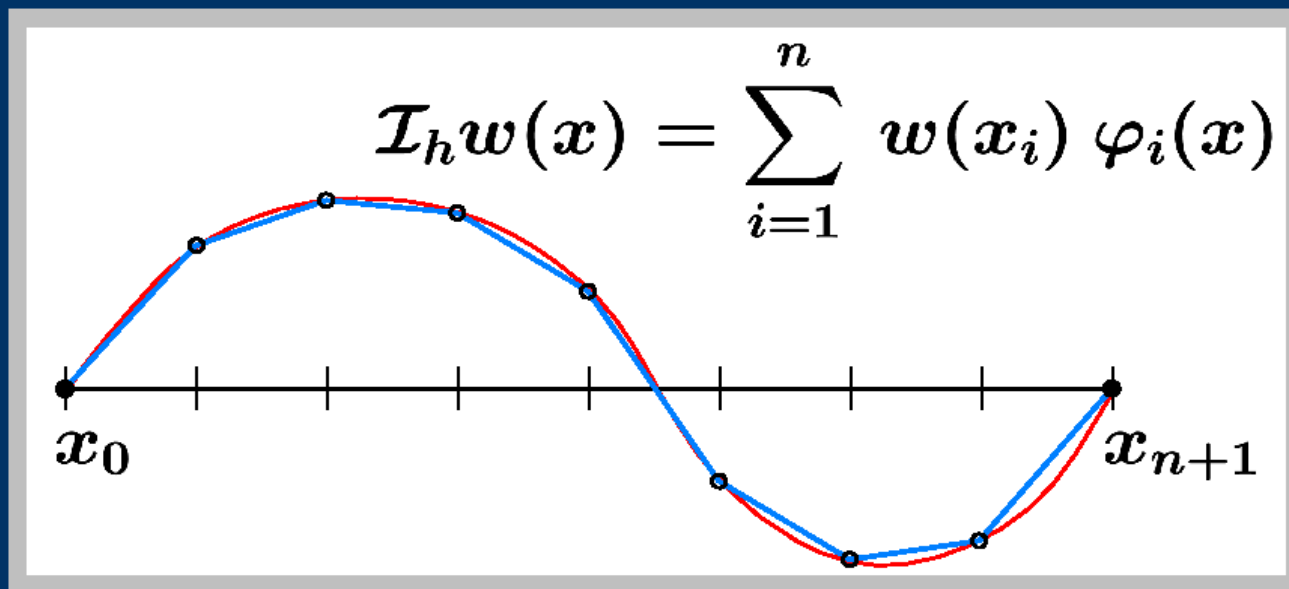
# The Interpolant

## Theory

### ...Definition

Given  $w \in X$ , the *interpolant*  $\mathcal{I}_h w$  satisfies:

$\mathcal{I}_h w \in X_h$ ; and  $\mathcal{I}_h w(x_i) = w(x_i)$ ,  $i = 0, \dots, n + 1$ .



## The Interpolant

### Approximation Theory...

## Theory

If  $w \in X$ , and  $w|_{T_h} \in C^2(T_h)$ ,  $\forall T_h \in \mathcal{T}_h$ , then

$$\|w - \mathcal{I}_h w\|_{H^1(\Omega)} \leq h \max_{T_h \in \mathcal{T}_h} \left( \max_{x \in T_h} |w''| \right)$$

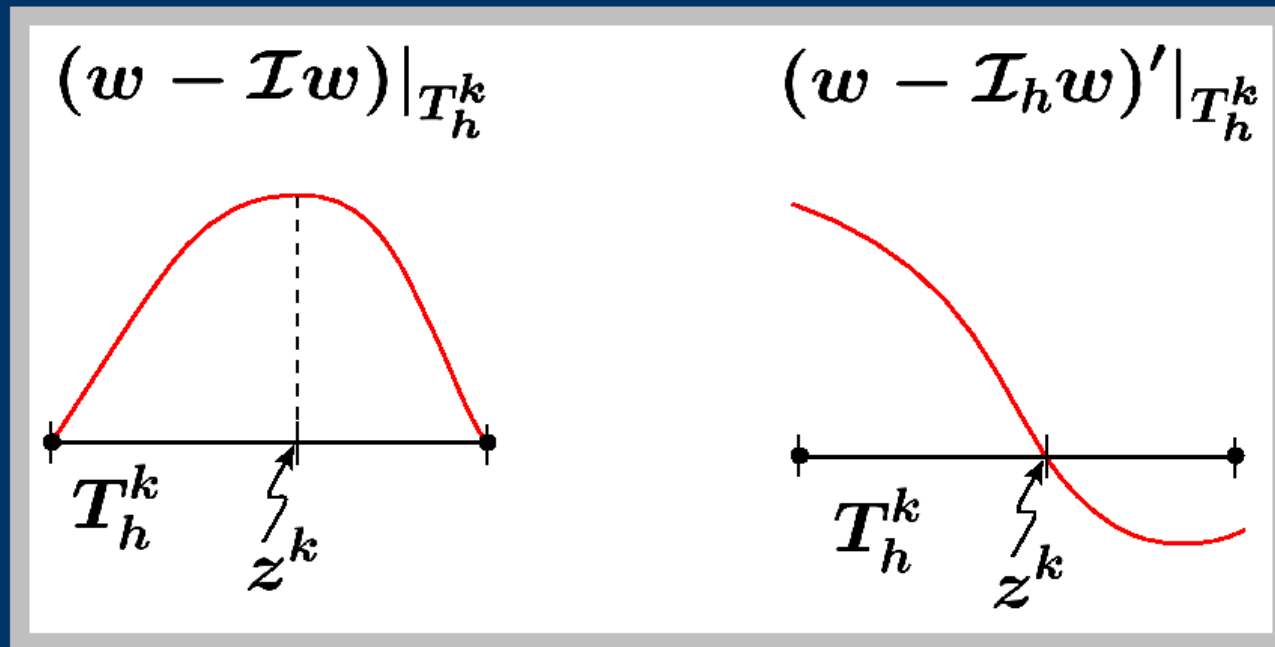
$$\|w - \mathcal{I}_h w\|_{L^2(\Omega)} \leq h^2 \max_{T_h \in \mathcal{T}_h} \left( \max_{x \in T_h} |w''| \right) .$$

# The Interpolant

...Approximation Theory...

## Theory

Sketch of proof:



## The Interpolant

...Approximation Theory...

## Theory

$$\begin{aligned} \left| (w - \mathcal{I}_h w)' \Big|_{T_h^k}(\boldsymbol{x}) \right| &= \left| \int_{z^k}^{\boldsymbol{x}} (w - \mathcal{I}_h w)'' \Big|_{T_h^k} d\boldsymbol{x} \right| = \left| \int_{z^k}^{\boldsymbol{x}} w'' d\boldsymbol{x} \right| \\ &\leq h \max_{\boldsymbol{x} \in T_h^k} |w''| \end{aligned}$$

$$\sum_{k=1}^K \int_{T_h^k} (w - \mathcal{I}_h w)' \Big|_{T_h^k}^2 d\boldsymbol{x} \leq \frac{1}{h} h \left( h \max_{k=1, \dots, K} \max_{\boldsymbol{x} \in T_h^k} |w''| \right)^2$$

E2

## The Interpolant

### ...Approximation Theory

## Theory

If  $w \in X$ , and  $w \in H^2(\Omega, \mathcal{T}_h)$ ,

$$|w - \mathcal{I}_h w|_{H^1(\Omega)} \leq \frac{h}{\pi} \|w\|_{H^2(\Omega, \mathcal{T}_h)}$$

$$\|w - \mathcal{I}_h w\|_{L^2(\Omega)} \leq \frac{h^2}{\pi^2} \|w\|_{H^2(\Omega, \mathcal{T}_h)},$$

where

$$\|w\|_{H^2(\Omega, \mathcal{T}_h)}^2 \equiv \sum_{k=1}^K \|w\|_{H^2(T_h^k)}^2 = \sum_{k=1}^K \int_{T_h^k} w_{xx}^2 + w_x^2 + w^2 dx.$$

# Theory

## Error: Energy Norm

### Definition...

Define the energy, or “ $a$ ”, norm  $|||v|||$  as

$$|||v|||^2 = a(v, v) \quad (\text{generally})$$

$$= \int_0^1 v_x^2 dx = |v|_{H^1(\Omega)}^2 \quad (\text{here}) .$$

Note:  $||| \cdot |||$  is *problem-dependent*.

# Theory

## Error: Energy Norm

...Definition

Of interest: for

$u(\mathbf{x})$  (exact solution)

$u_h(\mathbf{x})$  (finite element approximation)

$\Rightarrow e(\mathbf{x}) = (u - u_h)(\mathbf{x})$  (discretization error)

find bound for  $\|e\|$  in terms of  $h, u$ .



# Theory

## Error: Energy Norm

### Orthogonality

Since  $a(u, v) = \ell(v), \forall v \in X$

then  $a(u, v) = \ell(v), \forall v \in X_h \quad (X_h \subset X),$

but  $- [a(u_h, v) = \ell(v)], \forall v \in X_h$

so  $a(u - u_h, v) = 0, \forall v \in X_h$  (bilinearity).

# Theory

## Error: Energy Norm

### General Bound...

For any  $w_h = u_h + v_h \in X_h$ ,  $v_h \in X_h$

$$\underbrace{a(u - w_h, u - w_h)}_{\|u - w_h\|^2} = a((u - u_h) - v_h, (u - u_h) - v_h)$$

$$= \underbrace{a(u - u_h, u - u_h)}_{\|e\|^2} - \underbrace{2a(u - u_h, v_h)}_{0: \text{orthogonality}} + \underbrace{a(v_h, v_h)}_{>0 \text{ if } v_h \neq 0}$$

$\Rightarrow$

$$\|e\| = \inf_{w_h \in X_h} \|u - w_h\|.$$

# Theory

## Error: Energy Norm

...General Bound...

*In words:* even if you *knew*  $u$ ,

you could not find a  $w_h$  in  $X_h$

more accurate than  $u_h$

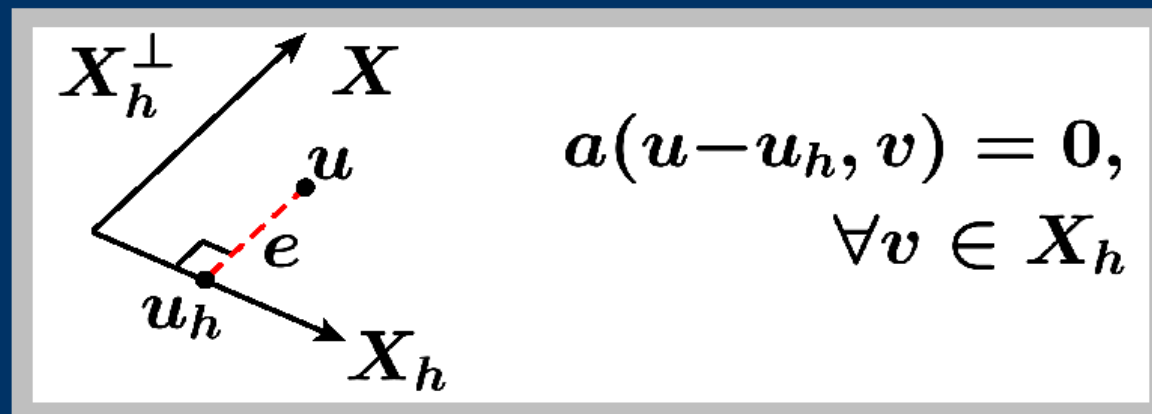
*in the energy norm.*

# Theory

## Error: Energy Norm

...General Bound...

### Geometry



$\Rightarrow u_h = \Pi_h^a u$ : the projection of (closest point to)  
 $u$  on  $X_h$  in the  $a$  norm.

# Theory

## Error: Energy Norm

...General Bound

Miracle?:  $a(\underbrace{\Pi_h^a u}_{u_h}, v) = a(u, v), \forall v \in X_h;$

but we do not know  $u \dots$

NO:

$$a(u, v) = \underbrace{\ell(v)}_{\text{can evaluate}} \Rightarrow a(\underbrace{\Pi_h^a u}_{u_h}, v) = \ell(v), \forall v \in X_h.$$

Only in the energy inner product can we

compute  $\Pi_h u$  without knowing  $u$ . **N3**

# Theory

## Error: Energy Norm

### Particular Bound

We know  $\|u - \mathcal{I}_h u\|_{H^1(\Omega)} \leq \frac{h}{\pi} \|u\|_{H^2(\Omega, \mathcal{T}_h)}$ .

Thus

$$\begin{aligned} \|e\| &= \inf_{w_h \in X_h} \|u - w_h\| \leq \|u - \mathcal{I}_h u\| \\ &= \|u - \mathcal{I}_h u\|_{H^1(\Omega)} \leq \frac{h}{\pi} \|u\|_{H^2(\Omega, \mathcal{T}_h)} \end{aligned}$$

E3 N4

(assuming  $\|u\|_{H^2(\Omega, \mathcal{T}_h)}$  finite).

The  $H^1$  norm:

$$\begin{aligned}\|v\|_{H^1(\Omega)}^2 &= |v|_{H^1(\Omega)}^2 + \|v\|_{L^2(\Omega)}^2 \\ &= \int_0^1 v_x^2 dx + \int_0^1 v^2 dx ;\end{aligned}$$

$\|e\|_{H^1(\Omega)}$  measures  $e$  and  $e_x$ .

## Theory

...Reminders

Coercivity of  $a(\cdot, \cdot)$ :

$\exists \alpha > 0$  such that  $a(v, v) \geq \alpha \|v\|_{H^1(\Omega)}^2, \quad \forall v \in X$

$$\left( \int_0^1 v_x^2 dx \geq \alpha \left( \int_0^1 v_x^2 dx + \int_0^1 v^2 dx \right) \right).$$

Continuity of  $a(\cdot, \cdot)$ :

$\exists \beta (= 1) > 0$  such that  $a(w, v) \leq \beta \|w\|_{H^1(\Omega)} \|v\|_{H^1(\Omega)}.$



## Error: $H^1$ Norm

### General Result

# Theory

The error  $e = u - u_h$  satisfies

$$\|e\|_{H^1(\Omega)} \leq \underbrace{\left(1 + \frac{\beta}{\alpha}\right)}_{\text{degradation}} \underbrace{\inf_{w \in X_h} \|u - w_h\|_{H^1(\Omega)}}_{\text{error in } H^1 \text{ projection of } u \text{ on } X_h} ;$$

in general  $u_h$  is *not* the  $H^1$  projection of  $u$  on  $X_h$ .

E4

N5

## Error: $H^1$ Norm

### Theory

### Particular Result

We know  $\|\mathbf{u} - \mathcal{I}_h \mathbf{u}\|_{H^1(\Omega)} \leq \sqrt{2} \frac{h}{\pi} \|\mathbf{u}\|_{H^2(\Omega, \mathcal{T}_h)}$ . Thus

$$\begin{aligned} \|\mathbf{e}\|_{H^1(\Omega)} &= \left(1 + \frac{\beta}{\alpha}\right) \inf_{\mathbf{w}_h \in X_h} \|\mathbf{u} - \mathbf{w}_h\|_{H^1(\Omega)} \\ &\leq \left(1 + \frac{\beta}{\alpha}\right) \|\mathbf{u} - \mathcal{I}_h \mathbf{u}\|_{H^1(\Omega)} \\ &\leq \sqrt{2} \left(1 + \frac{\beta}{\alpha}\right) \frac{h}{\pi} \|\mathbf{u}\|_{H^2(\Omega, \mathcal{T}_h)}. \end{aligned}$$

The  $L^2$  norm:

$$\|v\|_{L^2(\Omega)} = \left( \int_0^1 v^2 dx \right)^{1/2} ;$$

$\|e\|_{L^2(\Omega)}$  measures  $e$ .

## Error: $L^2$ Norm

### Particular Result

# Theory

The  $L^2$  error satisfies

$$\begin{aligned}\|e\|_{L^2(\Omega)} &\leq C h \|e\|_{H^1(\Omega)} \\ &\leq C h^2 \|u\|_{H^2(\Omega, \mathcal{T}_h)},\end{aligned}$$

for  $C$  independent of  $h$  and  $u$ .

N6

A linear-functional “output”  $s$  is defined by

$$s = \ell^O(u) + c^O ;$$

where

$$\ell^O: H_0^1(\Omega) \rightarrow \mathbb{R}$$

is a bounded linear functional

$$|\ell^O(v)| \leq C \|v\|_{H^1(\Omega)} , \quad \forall v \in H_0^1(\Omega) .$$

## Theory

...Motivation...

*Very relevant:* engineering quantities of interest.

For example:

**s:** average over  $\mathcal{D} \subset \Omega$ , with

$$\ell^O(v) = \int_{\mathcal{D}} v \, dx ;$$

**s:** flux at boundary,  $u_x(0)$ , with

$$\ell^O(v) = - \int_0^1 (1-x)_x v_x, \quad c^O = \int_0^1 f(1-x) \, dx .$$

N7

Of interest:  $s = \ell^O(u) + c^O$ ,

$$s_h = \underbrace{\ell^O(u_h)} + c^O;$$

finite element prediction of output

error in output is thus

$$\begin{aligned} |s - s_h| &= |\ell^O(u) - \ell^O(u_h)| = |\ell^O(u - u_h)| \\ &= |\ell^O(e)|. \end{aligned}$$

If  $\ell^0 \in H^{-1}(\Omega)$ , then

$$|\ell^0(e)| \leq C \|e\|_{H^1(\Omega)} \text{ (boundedness).}$$

If  $\ell^0 \in L^2(\Omega)$ , then

$$|\ell^0(e)| \leq C \|e\|_{L^2(\Omega)} \text{ (boundedness).}$$



## Linear Functionals

### Theory

#### ...General Result

In fact: for any  $\ell^0 \in H^{-1}(\Omega)$ ,

$$|\ell^0(e)| \leq C \|e\|_{H^1(\Omega)} \|\psi - \psi_h\|_{H^1(\Omega)}$$

where  $a(v, \psi) = -\ell^0(v), \quad \forall v \in X$

N8

$$a(v, \psi_h) = -\ell^0(v), \quad \forall v \in X_h,$$

and  $\psi$  is an adjoint, or dual, variable.

## Linear Functionals

### Theory

### Particular Result

From our earlier bounds for  $\|e\|_{H^1(\Omega)}$  and  $\|e\|_{L^2(\Omega)}$  for linear finite elements:

$$\text{for } \ell^0 \in H^{-1}(\Omega): \quad |\ell^0(e)| \leq C h \|u\|_{H^2(\Omega, \mathcal{T}_h)}$$

$$\text{for } \ell^0 \in L^2(\Omega): \quad |\ell^0(e)| \leq C h^2 \|u\|_{H^2(\Omega, \mathcal{T}_h)} \cdot$$

*Better yet:* for  $\ell^0 \in H^{-1}(\Omega)$

$$|\ell^0(e)| \leq C \boxed{h^2} \|u\|_{H^2(\Omega, \mathcal{T}_h)} \|\psi\|_{H^2(\Omega, \mathcal{T}_h)} \cdot$$

# Implementation

Four steps:

A Proto-Problem,

Elemental Quantities;

Assembly;

Boundary Conditions;

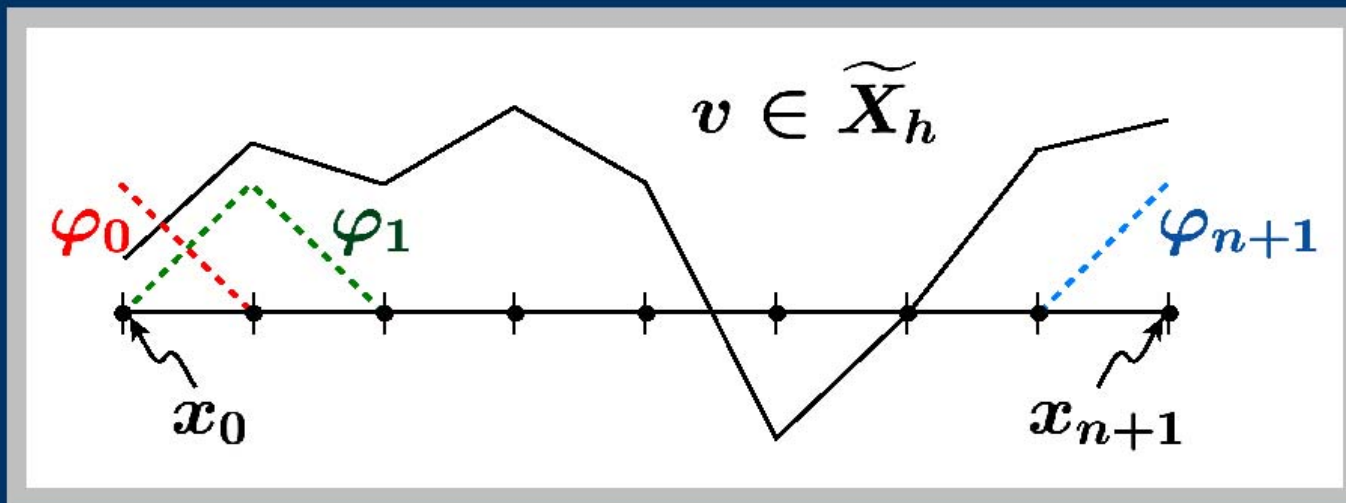
and Quadrature.

## A Proto-Problem

### Space and Basis

## Implementation

Let  $\widetilde{X}_h = \{v \in H^1(\Omega) \mid v|_{T_h} \in \mathbb{P}_1(T_h), \forall T_h \in \mathcal{T}_h\}$   
 $= \text{span} \{\varphi_0, \dots, \varphi_{n+1}\}.$



## A Proto-Problem

## Implementation

### Definition

“Find”  $\tilde{u}_h \in \tilde{X}_h$  such that

$$a(\tilde{u}_h, v) = \ell(v), \quad \forall v \in \tilde{X}_h.$$

We never actually solve this problem:

it serves only as a convenient pre-processing step.

## A Proto-Problem

Discrete Equations...

## Implementation

$$\underline{\tilde{A}}_h \underline{\tilde{u}}_h = \underline{\tilde{F}}_h \quad \tilde{u}_h(x) = \sum_{i=0}^{n+1} \tilde{u}_{h i} \varphi_i(x)$$

$$\tilde{A}_{h i j} = a(\varphi_i, \varphi_j) = \int_0^1 \frac{d\varphi_i}{dx} \frac{d\varphi_j}{dx} dx, \quad 0 \leq i, j \leq n+1$$

$$\tilde{F}_{h i} = \ell(\varphi_i) \left( = \int_0^1 f \varphi_i dx \right), \quad 0 \leq i \leq n+1$$

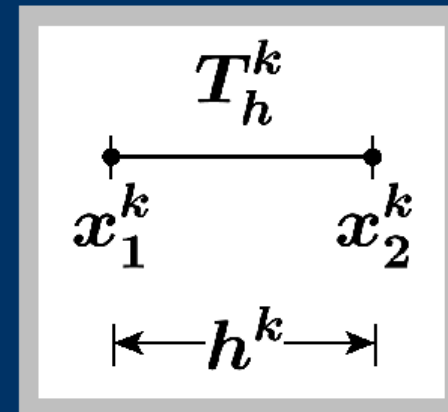


# Implementation

## Elemental Quantities

### Local Definitions

Element  $T_h^k$ :  $\mapsto \mathbf{x}$



$x_1^k$ : local node **1** of element  $T_h^k$ ;

$x_2^k$ : local node **2** of element  $T_h^k$ ;

$h^k$ : length of element  $T_h^k$ .

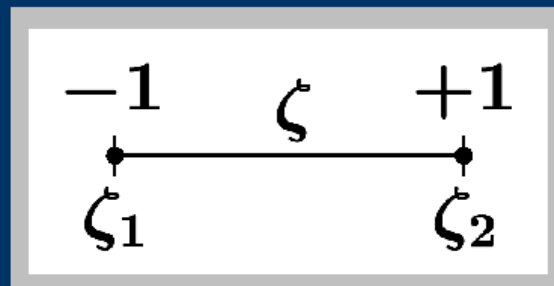


# Implementation

## Elemental Quantities

Reference Element...

*Definition:*  $\hat{T} = (-1, 1)$



$\zeta_1$ : reference element node **1**;

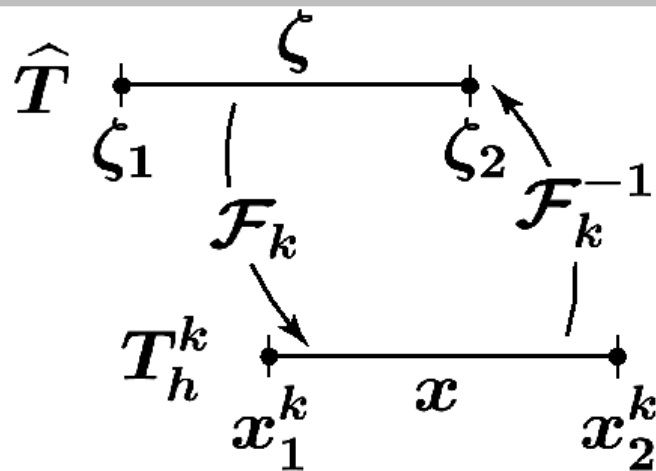
$\zeta_2$ : reference element node **2**.

# Implementation

## Elemental Quantities

...Reference Element

Relation of  $\hat{T}$  to each  $T_h^k$ : Affine Mappings



$$\mathcal{F}_k(\zeta) = x_1^k + \frac{1}{2} (1 + \zeta) h^k$$

$$\mathcal{F}_k^{-1}(x) = 2 \frac{x - x_1^k}{h^k} - 1$$

# Implementation

## Elemental Quantities

Reference Element Space, Basis

Define *space*  $\widehat{X} = \mathbb{P}_1(\widehat{T})$ : all linear polynomials over  $\widehat{T}$ ;  $\dim(\widehat{X}) = 2$ .

Introduce *basis* for  $\widehat{X}$ ,  $\mathcal{H}_1(\zeta), \mathcal{H}_2(\zeta)$ :

$$\left. \begin{array}{l} \mathcal{H}_1(\zeta) = \frac{(1 - \zeta)}{2} \\ \mathcal{H}_2(\zeta) = \frac{(1 + \zeta)}{2} \end{array} \right\} \text{Lagrangian interpolants}$$

$\zeta_1 = -1$        $\zeta_2 = 1$

# Implementation

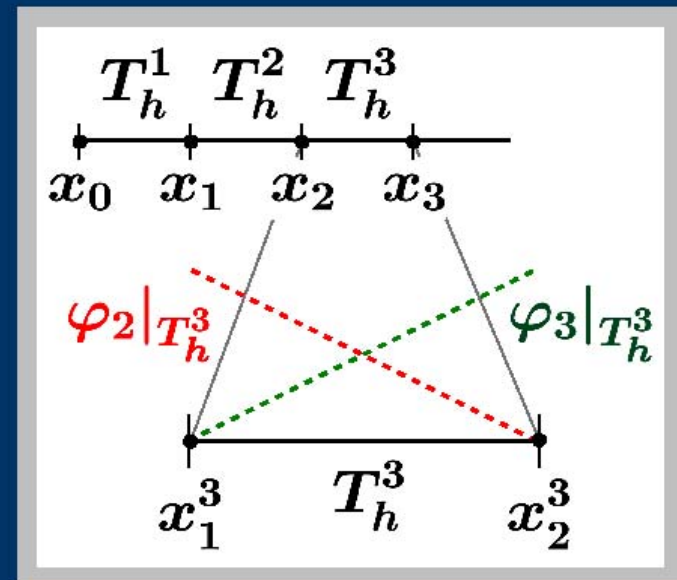
## Elemental Quantities

### Elemental Matrices...

$$\tilde{A}_{hij} = a(\varphi_i, \varphi_j) = \int_0^1 \frac{d\varphi_i}{dx} \frac{d\varphi_j}{dx} dx$$

Element  $T_h^3$  (say) contributes

$$\int_{T_h^3} \frac{d\varphi_{2 \text{ or } 3}}{dx} \Big|_{T_h^3} \frac{d\varphi_{2 \text{ or } 3}}{dx} \Big|_{T_h^3} dx$$



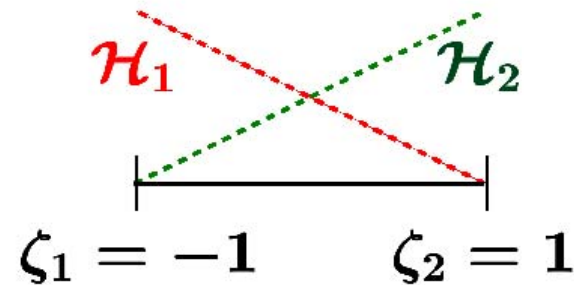
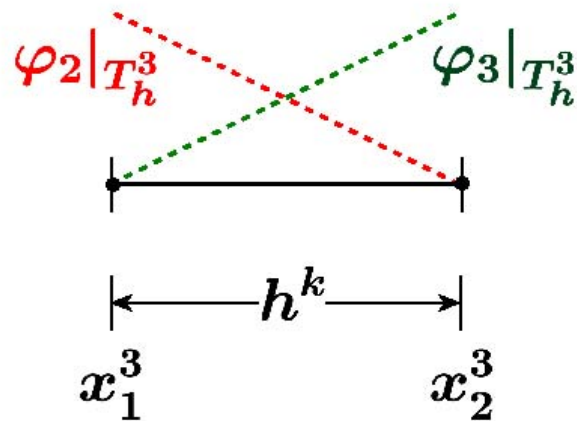
# Implementation

## Elemental Quantities

...Elemental Matrices...

Change variables  $T_h^3 \rightarrow \hat{T}$ :

N9



$$\int_{T_h^3} \frac{d\varphi_{2 \text{ or } 3}}{dx} \frac{d\varphi_{2 \text{ or } 3}}{dx} dx \quad \int_{-1}^1 \left( \frac{d\mathcal{H}_{1 \text{ or } 2}}{d\zeta} \frac{2}{h^k} \right) \left( \frac{d\mathcal{H}_{1 \text{ or } 2}}{d\zeta} \frac{2}{h^k} \right) \left( d\zeta \frac{h^k}{2} \right)$$

## Elemental Quantities

### ...Elemental Matrices

## Implementation

Define  $\underline{\mathbf{A}}^k \in \mathbb{R}^{2 \times 2}$  (e.g.,  $k = 3$ ):

E5

E6

N10

$$\frac{2}{h^k} \int_{-1}^1 \frac{d\mathcal{H}_{\alpha(1 \text{ or } 2)}}{d\zeta} \frac{d\mathcal{H}_{\beta(1 \text{ or } 2)}}{d\zeta} d\zeta =$$

$$\frac{2}{h^k} \int_{-1}^1 \frac{d}{d\zeta} \underline{\mathcal{H}} \frac{d}{d\zeta} \underline{\mathcal{H}}^T d\zeta = \quad \underline{\mathcal{H}} = \begin{pmatrix} \mathcal{H}_1 \\ \mathcal{H}_2 \end{pmatrix}$$

$$\frac{1}{h^k} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} \equiv \underline{\mathbf{A}}^k$$

*Elemental Stiffness Matrix*

# Implementation

## Elemental Quantities

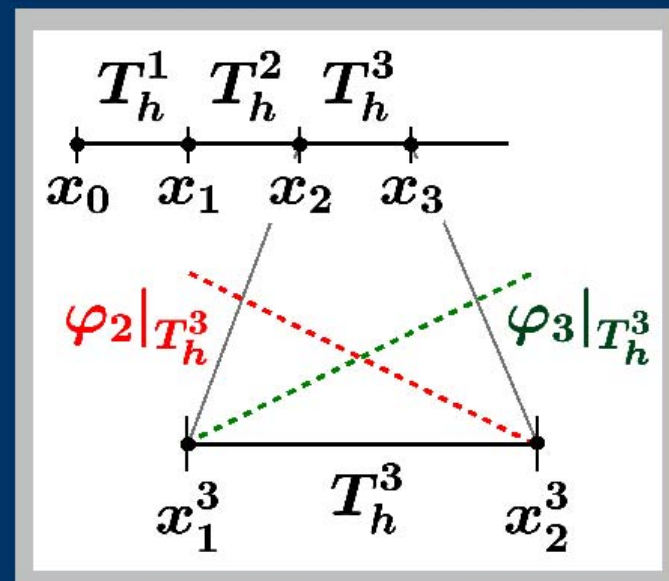
Elemental "Loads"...

$$\tilde{F}_{hi} = \ell(\varphi_i) = \int_0^1 f \varphi_i dx$$

(say)

Element  $T_h^3$  (say) contributes

$$\int_{T_h^3} f \varphi_2 \text{ or } 3 dx$$

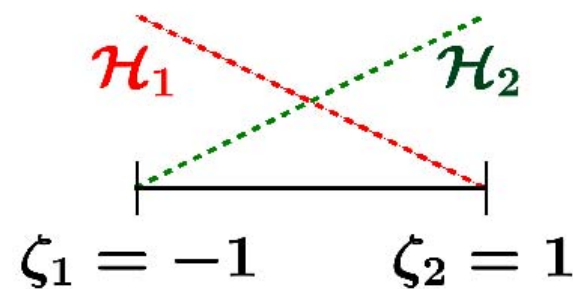
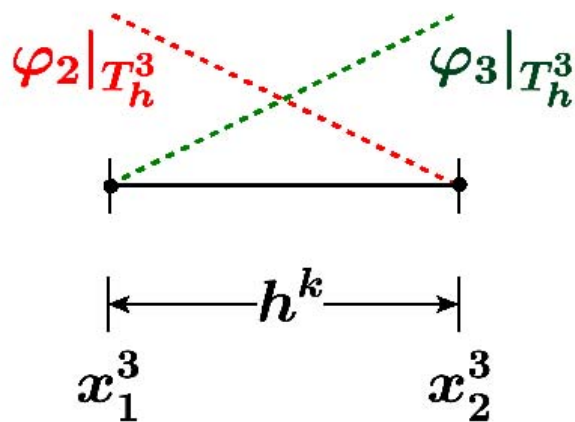


# Implementation

## Elemental Quantities

...Elemental "Loads"...

Change variables  $T_h^3 \rightarrow \hat{T}$ :



$$\int_{T_h^3} f \varphi_{2 \text{ or } 3} dx$$

$$\frac{h^k}{2} \int_{-1}^1 f \mathcal{H}_{1 \text{ or } 2} d\zeta$$



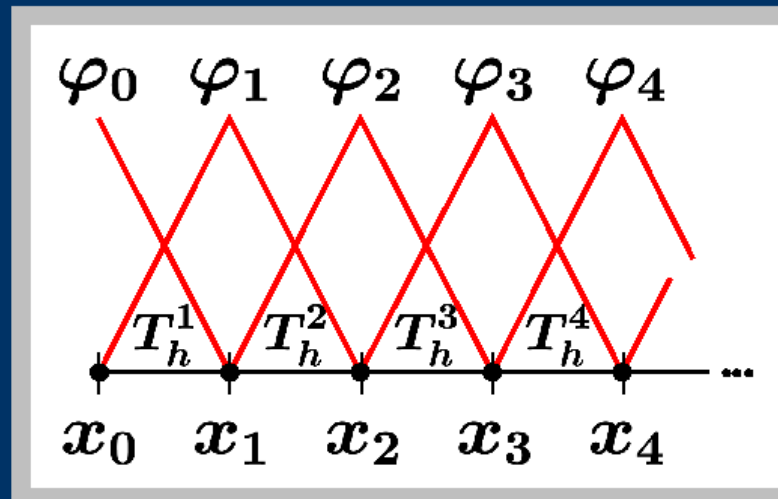
## Implementation

Define  $\underline{F}^k \in \mathbb{R}^2$  (e.g.,  $k = 3$ ):

$$\begin{aligned} F_{\alpha}^k &= \frac{h^k}{2} \int_{-1}^1 f \mathcal{H}_{\alpha(1 \text{ or } 2)} d\zeta && \text{Elemental Load Vector} \\ &= \frac{h^k}{2} \int_{-1}^1 f \underline{\mathcal{H}} d\zeta && \underline{\mathcal{H}} = \begin{pmatrix} \mathcal{H}_1 \\ \mathcal{H}_2 \end{pmatrix}. \end{aligned}$$

Evaluation (usually) by numerical quadrature.

Recall triangulation and basis functions:



## Assembly

## Implementation

...The Idea...

$$T_h^3 \text{ contribution to } \tilde{A}_{hij} = a(\varphi_i, \varphi_j) = \int_0^1 \frac{d\varphi_i}{dx} \frac{d\varphi_j}{dx} dx$$

$$\int_{T_h^3} \frac{d\varphi_{2 \text{ or } 3}}{dx} \frac{d\varphi_{2 \text{ or } 3}}{dx} dx = \underbrace{\begin{matrix} & \begin{matrix} 2 & 3 \end{matrix} \\ \begin{matrix} 2 \\ 3 \end{matrix} & \begin{pmatrix} \frac{1}{h^3} & -\frac{1}{h^3} \\ -\frac{1}{h^3} & \frac{1}{h^3} \end{pmatrix} \end{matrix}}_{\underline{A}^3}$$

	Column 1 of $\underline{A}^3$	Column 2 of $\underline{A}^3$
Row 1 of $\underline{A}^3$	Adds to $\tilde{A}_{22}$	Adds to $\tilde{A}_{23}$
Row 2 of $\underline{A}^3$	Adds to $\tilde{A}_{32}$	Adds to $\tilde{A}_{33}$

# Implementation

## Assembly

...The Idea...

$$\underbrace{\begin{array}{c} \text{R0} \\ \text{R1} \\ \text{R2} \\ \text{R3} \\ \text{R4} \\ \vdots \end{array} \left( \begin{array}{ccccc} \text{C0} & \text{C1} & \text{C2} & \text{C3} & \text{C4} \\ & & & & \\ & & & & \\ & & \frac{1}{h^3} & -\frac{1}{h^3} & \\ & & -\frac{1}{h^3} & \frac{1}{h^3} & \\ & & & & \end{array} \right)}_{\tilde{\underline{A}}_h \text{ with } \underline{T}_h^3 \text{ accounted for } \dots} = \underline{\underline{A}}^3 = \begin{pmatrix} \frac{1}{h^3} & -\frac{1}{h^3} \\ -\frac{1}{h^3} & \frac{1}{h^3} \end{pmatrix}$$

## Assembly

## Implementation

...The Idea...

$$T_h^4 \text{ contribution to } \tilde{A}_{hij} = a(\varphi_i, \varphi_j) = \int_0^1 \frac{d\varphi_i}{dx} \frac{d\varphi_j}{dx} dx$$

$$\int_{T_h^4} \frac{d\varphi_{3 \text{ or } 4}}{dx} \frac{d\varphi_{3 \text{ or } 4}}{dx} dx = \underbrace{\begin{matrix} 3 & 4 \\ 4 \begin{pmatrix} \frac{1}{h^4} & -\frac{1}{h^4} \\ -\frac{1}{h^4} & \frac{1}{h^4} \end{pmatrix} \end{matrix}}_{\underline{A}^4}$$

	Column 1 of $\underline{A}^4$	Column 2 of $\underline{A}^4$
Row 1 of $\underline{A}^4$	Adds to $\tilde{A}_{33}$	Adds to $\tilde{A}_{34}$
Row 2 of $\underline{A}^4$	Adds to $\tilde{A}_{43}$	Adds to $\tilde{A}_{44}$

# Implementation

## Assembly

...The Idea...

$$\begin{array}{c} \text{R0} \\ \text{R1} \\ \text{R2} \\ \text{R3} \\ \text{R4} \\ \vdots \end{array} \left( \begin{array}{cccccc} \text{C0} & \text{C1} & \text{C2} & \text{C3} & \text{C4} & \dots \\ & & & & & \\ & & & & & \\ & & \frac{1}{h^3} & -\frac{1}{h^3} & & \\ & & -\frac{1}{h^3} & \frac{1}{h^3} + \frac{1}{h^4} & -\frac{1}{h^4} & \\ & & & -\frac{1}{h^4} & \frac{1}{h^4} & \\ & & & & & \end{array} \right) \quad \underline{\underline{\mathbf{A}^4}} = \begin{pmatrix} \frac{1}{h^4} & -\frac{1}{h^4} \\ -\frac{1}{h^4} & \frac{1}{h^4} \end{pmatrix}$$

$\underline{\underline{\mathbf{A}_h}}$  with  $T_h^3, T_h^4$  accounted for ...

## Assembly

## Implementation

...The Idea...

$$T_h^3 \text{ contribution to } \tilde{F}_{hi} = \ell(\varphi_i) = \int_0^1 f \varphi_i dx$$

$$\int_{T_h^3} f \varphi_{2 \text{ or } 3} dx = \underbrace{\begin{pmatrix} \frac{h^3}{2} \int_{-1}^1 f \mathcal{H}_1 d\zeta \\ \frac{h^3}{2} \int_{-1}^1 f \mathcal{H}_2 d\zeta \end{pmatrix}}_{\underline{F}^3}$$

Row 1 of  $\underline{F}^3$  Adds to  $\tilde{F}_{h2}$

Row 2 of  $\underline{F}^3$  Adds to  $\tilde{F}_{h3}$

## Assembly

## Implementation

...The Idea...

$$\begin{array}{l} \text{R0} \\ \text{R1} \\ \text{R2} \\ \text{R3} \\ \text{R4} \\ \vdots \end{array} \left( \begin{array}{c} \\ \\ F_1^3 \\ F_2^3 \\ \\ \end{array} \right) \quad \underline{F}^3 = \begin{pmatrix} F_1^3 \\ F_2^3 \end{pmatrix}$$

$\underline{\tilde{F}}_h$  with  $T_h^3$  accounted for



## Assembly

## Implementation

...The Idea...

$T_h^4$  contribution to  $\tilde{F}_{hi} = \ell(\varphi_i) = \int_0^1 f \varphi_i dx$

$$\int_{T_h^4} f \varphi_{3 \text{ or } 4} dx = \underbrace{\begin{pmatrix} \frac{h^4}{2} \int_{-1}^1 f \mathcal{H}_1 d\zeta \\ \frac{h^4}{2} \int_{-1}^1 f \mathcal{H}_2 d\zeta \end{pmatrix}}_{\underline{F}^4}$$

Row 1 of  $\underline{F}^4$  Adds to  $\tilde{F}_{h3}$   
Row 2 of  $\underline{F}^4$  Adds to  $\tilde{F}_{h4}$

## Assembly

## Implementation

...The Idea

$$\begin{array}{l} \text{R0} \\ \text{R1} \\ \text{R2} \\ \text{R3} \\ \text{R4} \\ \vdots \end{array} \left( \begin{array}{c} \\ \\ F_1^3 \\ F_2^3 + F_1^4 \\ F_2^4 \\ \\ \end{array} \right) \quad \underline{F}^4 = \begin{pmatrix} F_1^4 \\ F_2^4 \end{pmatrix}$$

$\underline{\tilde{F}}_h$  with  $T_h^3, T_h^4$  accounted for

# Implementation

*Introduce local-to-global mapping:*

$$\theta(k, \alpha): \underbrace{\{1, \dots, K\}}_{\text{element}} \times \underbrace{\{1, 2\}}_{\text{local node number}} \rightarrow \underbrace{\{0, \dots, n+1\}}_{\text{global node number}}$$

such that

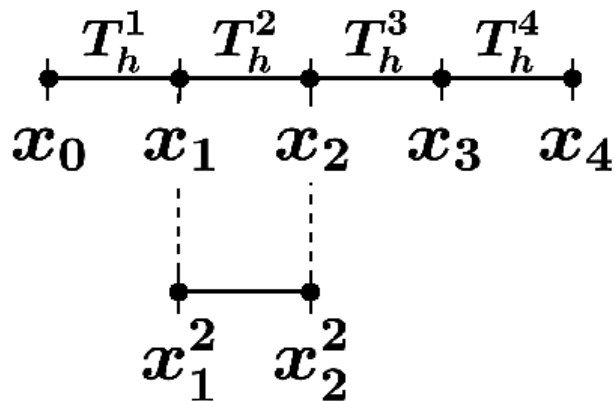
$$\mathbf{x}_{\alpha}^k \text{ (local node } \alpha \text{ in element } k) = \mathbf{x}_{\theta(k, \alpha)} \text{ (global node } \theta(k, \alpha)).$$

# Assembly

...The Algorithm...

## Implementation

Example:  $K = 4$



		$\theta(k, \alpha)$			
$\alpha \backslash k$	1	2	3	4	
1	0	1	2	3	
2	1	2	3	4	

# Implementation

Procedure for  $\tilde{\mathbf{A}}_h$ :

zero  $\tilde{\mathbf{A}}_h$ ;

{for  $k = 1, \dots, K$

{for  $\alpha = 1, 2$

$i = \theta(k, \alpha)$  ;

{for  $\beta = 1, 2$

$j = \theta(k, \beta)$  ;

$\tilde{\mathbf{A}}_{h\ i\ j} = \tilde{\mathbf{A}}_{h\ i\ j} + \mathbf{A}_{\alpha\beta}^k$  ; } } }

## Implementation

Procedure for  $\tilde{\underline{F}}_h$ :

zero  $\tilde{\underline{F}}_h$ ;

{for  $k = 1, \dots, K$

{for  $\alpha = 1, 2$

$i = \theta(k, \alpha)$  ;

$\tilde{F}_{h i} = \tilde{F}_{h i} + F_{\alpha}^k$  ; } }

# Implementation

## Boundary Conditions

### Point of Departure

$$\frac{1}{h} \underbrace{\begin{pmatrix} 1 & -1 & & & & & \\ -1 & 2 & -1 & & & & \\ & -1 & 2 & -1 & & & \\ & & & \dots & & & \\ 0 & & & & & & \\ & & & & & -1 & 2 & -1 \\ & & & & & -1 & 1 & \\ & & & & & & & \end{pmatrix}}_{\tilde{A}_h} \underbrace{\begin{pmatrix} \tilde{u}_{h0} \\ \tilde{u}_{h1} \\ \vdots \\ \vdots \\ \tilde{u}_{hn} \\ \tilde{u}_{hn+1} \end{pmatrix}}_{\tilde{u}_h} = \underbrace{\begin{pmatrix} \tilde{F}_{h0} \\ \tilde{F}_{h1} \\ \vdots \\ \vdots \\ \tilde{F}_{hn} \\ \tilde{F}_{hn+1} \end{pmatrix}}_{\tilde{F}_h}$$

# Implementation

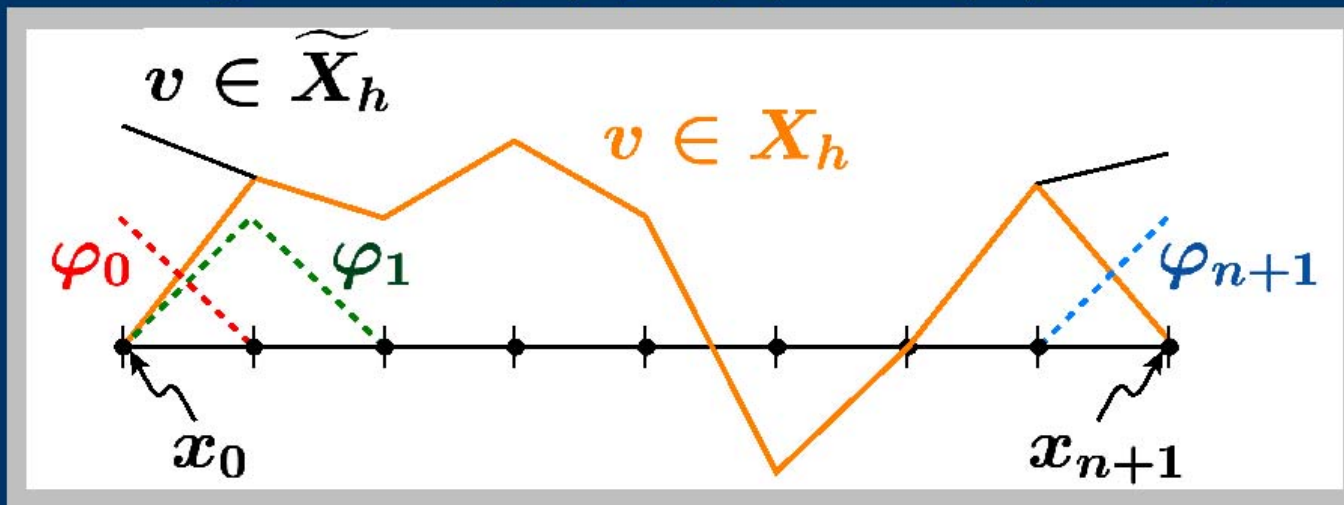
## Boundary Conditions

Homogeneous Dirichlet...

$u_h \in X_h$  such that  $a(u_h, v) = \ell(v)$ ,  $\forall v \in X_h$ :

$X_h = \{v \in X \mid v|_{T_h} \in \mathbb{P}_1(T_h), \forall T_h \in \mathcal{T}_h\}$  ;

$X = \{v \in H^1(\Omega) \mid v(0) = v(1) = 0\}$  .





## Boundary Conditions

### Implementation

...Homogeneous Dirichlet...

### *Explicit Elimination*

$X_h \Rightarrow \varphi_0, \varphi_{n+1}$  not admissible variations, so

REMOVE  $R_0$  and  $R_{n+1}$  from  $\underline{\tilde{A}}_h$ ;

$\tilde{u}_{h0} = \tilde{u}_{hn+1} = \mathbf{0}$ , so

REMOVE  $C_0$  and  $C_{n+1}$  from  $\underline{\tilde{A}}_h$ .

Recover  $\underline{A}_h \underline{u}_h = \underline{F}_h$

# Implementation

## Boundary Conditions

...Homogeneous Dirichlet

*Big-Number Approach*

penalty

Place  $1/\varepsilon$  ( $\varepsilon \ll 1$ ) on entries  $\tilde{\mathbf{A}}_{h00}$  and  $\tilde{\mathbf{A}}_{h n+1 n+1}$ .

Place  $0$  on entries  $\tilde{\mathbf{F}}_{h0}$  and  $\tilde{\mathbf{F}}_{h n+1}$ .

This replaces  $\mathbf{R}0$  and  $\mathbf{R}n + 1$  with

$$\tilde{\mathbf{u}}_{h0} \cong \mathbf{0}, \tilde{\mathbf{u}}_{h n+1} \cong \mathbf{0}$$

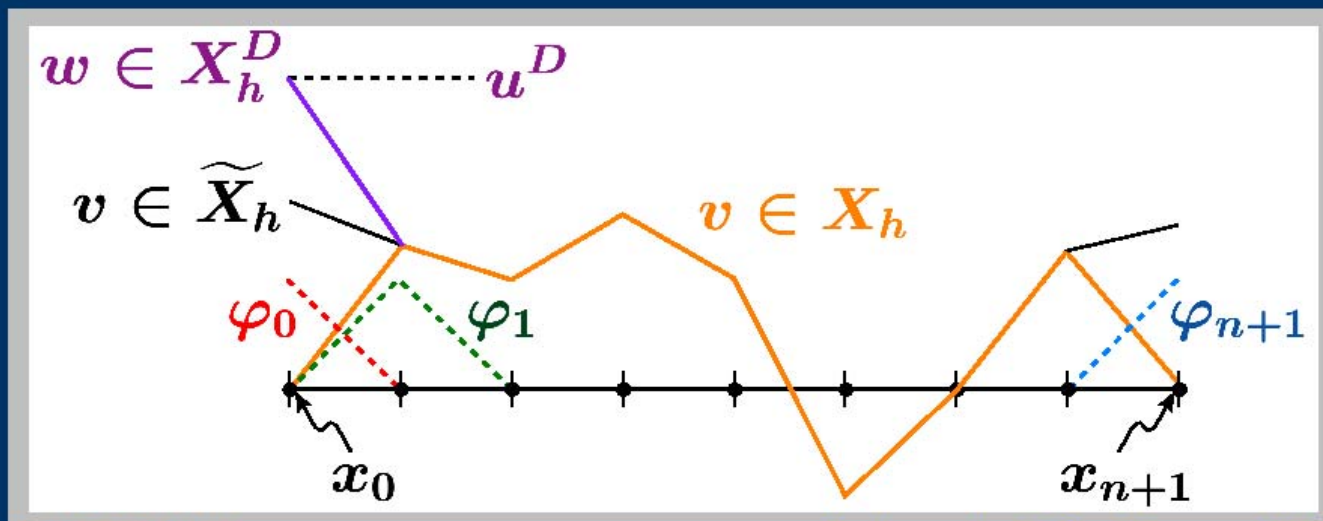
in an “easy,” symmetric way.

# Implementation

## Boundary Conditions

Inhomogeneous Dirichlet...

$u_h \in X_h^D$  such that  $a(u_h, v) = \ell(v)$ ,  $\forall v \in X_h$ :  
 $X_h$  requires  $v(0) = v(1) = 0$  ;  
 $X_h^D$  requires  $w(0) = u^D$ ,  $w(1) = 0$  .



# Implementation

## Boundary Conditions

...Inhomogeneous Dirichlet...

*Explicit Elimination ...*

$X_h \Rightarrow \varphi_0, \varphi_{n+1}$  not admissible variations, so

REMOVE  $R_0$  and  $R_{n+1}$  from  $\underline{\tilde{A}}_h$ ;

$X_h^D \Rightarrow \tilde{u}_{h0} = u^D, \tilde{u}_{hn+1} = \mathbf{0}$ , so

MOVE  $-u^D C_0 - \mathbf{0} C_{n+1}$  to  $\underline{\tilde{F}}_h$ .



## Boundary Conditions

### Implementation

...Inhomogeneous Dirichlet

### *Big-Number Approach*

E7

Place  $1/\varepsilon$  ( $\varepsilon \ll 1$ ) on entries  $\tilde{\mathbf{A}}_{h00}$  and  $\tilde{\mathbf{A}}_{h n+1 n+1}$ .

Place  $(1/\varepsilon) u^D$  on entry  $\tilde{\mathbf{F}}_{h0}$ .

Place  $0$  on entry  $\tilde{\mathbf{F}}_{h n+1}$ .

This replaces  $\mathbf{R0}$  and  $\mathbf{Rn} + 1$  with

$$\tilde{\mathbf{u}}_{h0} \cong u^D, \tilde{\mathbf{u}}_{h n+1} \cong \mathbf{0}.$$

How do we evaluate

$$F_{\alpha}^k = \frac{h^k}{2} \int_{-1}^1 \underbrace{f\left(x_1^k + \frac{(1+\zeta)}{2} h^k\right)}_{f^k(\zeta)} \mathcal{H}_{\alpha}(\zeta) d\zeta$$

for general  $f$ ?

N11

# Implementation

## Quadrature

...Question

### *Approaches*

- “Analytical” Integration
- Symbolic Integration
- Gauss Quadrature ←
- Integration by Interpolation

**N12**



# Implementation

## Quadrature

### Gauss Quadrature...

Approximate

$$\begin{aligned} F_{\alpha}^k &= \frac{h^k}{2} \int_{-1}^1 f^k(\zeta) \mathcal{H}_{\alpha}(\zeta) d\zeta \\ &\approx \frac{h^k}{2} \sum_{q=1}^{N_q} \rho_q f^k(z_q) \mathcal{H}_{\alpha}(z_q): \end{aligned}$$

$\rho_q$ : Gauss-Legendre quadrature weights

$z_q$ : Gauss-Legendre quadrature points.

# Implementation

## Quadrature

### Gauss Quadrature...

The  $\rho_q, z_q, q = 1, \dots, N_q$  are chosen so as

to integrate exactly all  $g \in \mathbb{P}_{2N_q-1}((-1, 1))$ .

N13

To conserve “ideal” convergence rates,

require  $N_q \geq 1$  ( $\geq p$  for  $\mathbb{P}_p$  elements).