

# CDIO-3 Product Concept

Requirements Team

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# Mission Statement

- ◆ Project Mission: Demonstrate the feasibility of electromagnetic control for formation flying satellites.
- ◆ Implications:
  - Demonstrate
  - EM Control
  - Formation maneuvering vehicles

# Functional Requirements 1: the Customer

## ◆ Formation flying

- Stability in formation
- Interchangeable/replaceable modules
- Both autonomy and command response

## ◆ EM control

- “Use magnets to generate the ... restoring forces”
- “... will allow between 3 and 6 DoF EMFF”

## ◆ Architectural notes

- High-permeability lightweight solenoid cores
- Necessary heat dissipation
- Reaction wheels

# Functional Requirements 2: the System

- ◆ Top-Level: “The system shall...”
  - Have interchangeable system modules
  - Be tested on a realistic facility
  - Maintain relative separation/attitude
  - Follow steady course, predetermined or MC

## ◆ Subsystems

Power	Flight computer
ADS – Sensing	ACS - Control
Communication	Protection
Testing	Integration

# EM Trades

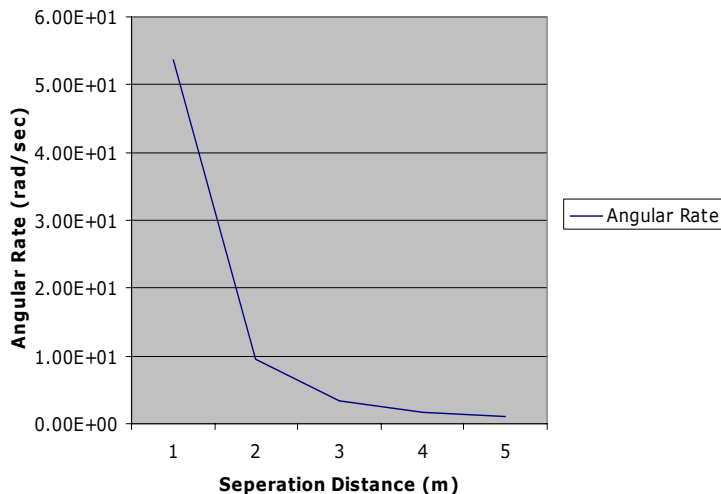
$$\beta = \frac{3}{4\pi} \frac{\mu_0 m_0}{\alpha} \sqrt{\frac{P_w}{\rho_c P_c}}$$

$$F = \frac{3}{2} \mu_0 \pi \frac{(\chi n i a^2)^2}{B^4}$$

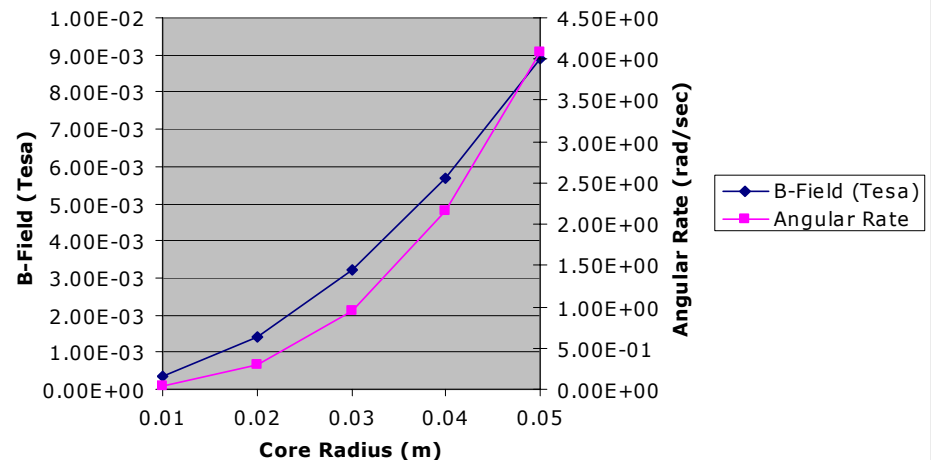
$$\omega = \chi \sqrt{\frac{3\mu_0 \pi}{B^5}} \frac{m_0^{5/6}}{2\pi} \sqrt[3]{\frac{\alpha}{\pi \rho_s}} \sqrt{\frac{P_w}{\rho_c P_c}}$$

$$m_0 = l^3 \pi \alpha^2 \rho_s$$

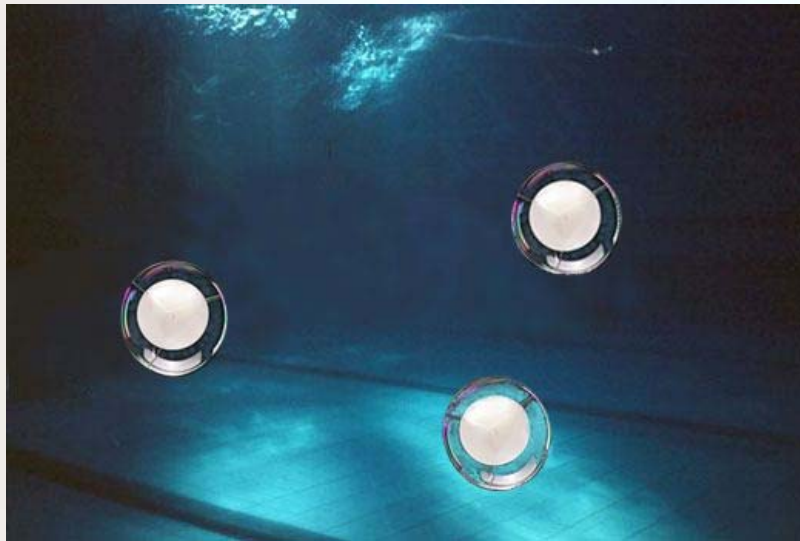
Angular Rate vs. Separation Distance



B-Field vs Core Radius  
Angular Rate vs Core Radius



# Final Design



Inside spheres:

- Reaction Wheels
- Computer
- Battery
- Coil and Core
- Transmitter/Receiver

Steel Core/Copper Coil

Mass = 5.26 kg

Separation = 5m

Length of core = 0.3m

Radius of core = 0.03m

Angular Rate = 0.959  
rad/sec

B-field = 3.20E-03

Force = 58.12 N

# Operations Concept

- ◆ Programmed response only
- ◆ Ground-to-vehicle communication
  - User-initiated autonomous tests
  - Realtime telemetry recording and storage
  - Emergency interrupt sequence
- ◆ Inter-vehicle communication
- ◆ Automated depth control

# Pros and Cons

## ◆ Advantages

- 3D flight
- Simpler test carriage
- Reduces danger of crash

## ◆ Disadvantages

- Instability of water environment
  - ◆ Polarity
  - ◆ Currents
- Increased drag due to high density of test medium