ERROR ANALYSIS (UNCERTAINTY ANALYSIS)

16.621 Experimental Projects Lab I

TOPICS TO BE COVERED

- Why do error analysis?
- If we don't ever know the true value, how do we estimate the error in the true value?
- Error propagation in the measurement chain
 - How do errors combine? (How do they behave in general?)
 - How do we do an end-to-end uncertainty analysis?
 - What are ways to mitigate errors?
- A hypothetical dilemma (probably nothing to do with anyone in the class)
 - When should I throw out some data that I don't like?
 - Answer: NEVER, but there are reasons to throw out data
- <u>Backup slides</u>: an example of an immense amount of money and effort directed at error analysis and mitigation jet engine testing

ERROR AND UNCERTAINTY

- In engineering the word "error", when used to describe an aspect of measurement does not necessarily carry the connotation of mistake or blunder (although it can!)
- Error in a measurement means the inevitable uncertainty that attends all measurements
- We cannot avoid errors in this sense
- We can ensure that they are as small as reasonably possible and that we have a reliable estimate of how small they are

[Adapted from Taylor, J. R, An Introduction to Error Analysis; The Study of Uncertainties in Physical Measurements]

USES OF UNCERTAINTY ANALYSIS (I)

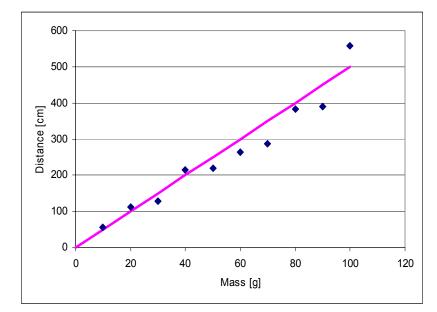
- Assess experimental procedure including identification of potential difficulties
 - Definition of necessary steps
 - Gaps
- Advise what procedures need to be put in place for measurement
- Identify instruments and procedures that control accuracy and precision
 - Usually one, or at most a small number, out of the large set of possibilities
- Inform us when experiment cannot meet desired accuracy

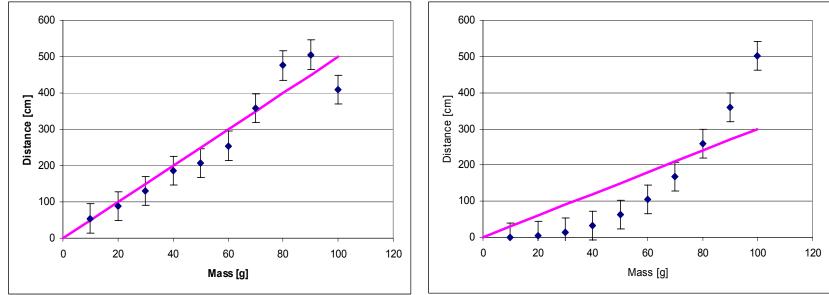
USES OF UNCERTAINTY ANALYSIS (II)

- Provide the only known basis for deciding whether:
 - Data agrees with theory
 - Tests from different facilities (jet engine performance) agree
 - Hypothesis has been appropriately assessed (resolved)
 - Phenomena measured are real
- Provide basis for defining whether a closure check has been achieved
 - Is continuity satisfied (does the same amount of mass go in as goes out?)
 - Is energy conserved?
- Provide an integrated grasp of how to conduct the experiment

[Adapted from Kline, S. J., 1985, "The Purposes of Uncertainty Analysis", ASME *J. Fluids Engineering*, pp. 153-160]

UNCERTAINTY ESTIMATES AND HYPOTHESIS ASSESSMENT





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HOW DO WE DEAL WITH NOT KNOWING THE TRUE VALUE?

In "all" real situations we don't know the true value we are looking for

• We need to decide how to determine the best representation of this from our measurements

• We need to decide what the uncertainty is in our best representation

AN IMPLICATION OF NOT KNOWING THE TRUE VALUE

- We easily divided errors into precision (bias) errors and random errors when we knew what the value was
- The target practice picture in the next slide is an example
- How about if we don't know the true value? Can we, by looking at the data in the slide after this, say that there are bias errors?
- How do we know if bias errors exist or not?

A TEAM EXERCISE

- List the variables you need to determine in order to carry out your hypothesis assessment
- What uncertainties do you foresee? (Qualitative description)
- Are you more concerned about bias errors or random errors?
- What level of uncertainty in the final result do you need to assess your hypothesis in a rigorous manner?
- Can you make an estimate of the level of the uncertainty in the final result?
 - If so, what is it?
 - If not, what additional information do you need to do this?

HOW DO WE COMBINE ERRORS?

- Suppose we measure quantity X with an error of dx and quantity Y with an error of dy
- What is the error in quantity Z if:
 - Z = AX where A is a numerical constant such as π ?
 - Z = X + Y?
 - Z = X Y?
 - Z = XY?
 - Z = X/Y?
 - Z is a general function of many quantities?

ERRORS IN THE FINAL QUANTITY

- Z = X + Y
- Linear combination
 - $\mathbf{Z} + |\mathbf{dz}| = \mathbf{X} + |\mathbf{dx}| + \mathbf{Y} + |\mathbf{dy}|$
 - Error in Z is |dz| = |dx| + |dy| BUT this is worst case
- For random errors we could have
 - $|\mathbf{dz}| = |\mathbf{dx}| |\mathbf{dy}|$
 - or |dy| |dx|
 - These errors are much smaller
- In general if different errors are not correlated, are independent, the way to combine them is

$$dz = \sqrt{dx^2 + dy^2}$$

This is true for random and bias errors

THE CASE OF Z = X - Y

• Suppose Z = X - Y is a number much smaller than X or Y

$$dz = \sqrt{dx^2 + dy^2}$$

- Say $\frac{dx}{X} = \frac{dy}{Y} = \epsilon$ (say 2%)
- $\frac{dz}{Z} = \frac{\sqrt{2} dx}{X Y}$ may be much larger than $\frac{dx}{X}$
- MESSAGE ==> Avoid taking the difference of two numbers of comparable size

ESTIMATES FOR THE TRUE VALUE AND THE ERROR

- Is there a "best" estimate of the true value of a quantity?
- How do I find it?
- How do I estimate the random error?
- How do I estimate the bias error?

SOME "RULES" FOR ESTIMATING RANDOM ERRORS AND TRUE VALUE

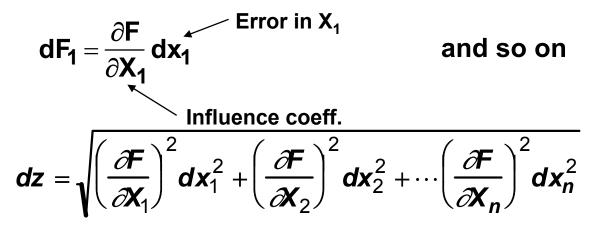
- An internal estimate can be given by repeat measurements
- Random error is generally of same size as standard deviation (root mean square deviation) of measurements
- Mean of repeat measurements is best estimate of true value
- Standard deviation of the mean (random error) is smaller than standard deviation of a single measurement by

 $1/\sqrt{Number of measurements}$

• To increase precision by 10, you need 100 measurements

GENERAL RULE FOR COMBINATION OF ERRORS

- If $Z = F(X_1, X_2, X_3, X_4)$ is quantity we want
- The error in Z, dz, is given by our rule from before
- So, if the error F due to X₁ can be estimated as



 The important consequence of this is that generally one or few of these factors is the main player and <u>others can be ignored</u>

DISTRIBUTION OF RANDOM ERRORS

- A measurement subject to many small random errors will be distributed "normally"
- Normal distribution is a Gaussian
- If x is a given measurement and X is the true value Gaussian or normal distribution = $\frac{1}{\sigma\sqrt{2\pi}} e^{-(x-X^2)/2\sigma^2}$
- σ is the standard deviation

A REVELATION

• The universal gas constant is

accepted *R* = 8.31451 ±0.00007 J/mol K

• This is not a true value but can be "accepted" as one

ONE ADDITIONAL ASPECT OF COMBINING ERRORS

- We have identified two different types of errors, bias (systematic) and random
 - Random errors can be assessed by repetition of measurements
 - Bias errors cannot; these need to be estimated using external information (mfrs. specs., your knowledge)
- How should the two types of errors be combined?
 - One practice is to treat each separately using our rule, and then report the two separately at the end
 - One other practice is to combine them as "errors"
- Either seems acceptable, as long as you show that you are going to deal (have dealt) with both

REPORTING OF MEASUREMENTS

- Experimental uncertainties should almost always be rounded to one significant figure
- The last significant figure in any stated answer should usually be of the same order of magnitude (in the same decimal position) as the uncertainty

COMMENTS ON REJECTION OF DATA

- Should you reject (delete) data?
- Sometimes on measurement appears to disagree greatly with all others. How do we decide:
 - Is this significant?
 - Is this a mistake?
- One criteria (Chauvenaut's criteria) is as follows
 - Suppose that errors are normally distributed
 - If measurement is more than M standard deviations (say 3), probability is < 0.003 that measurement should occur
 - Is this improbable enough to throw out measurement?
- The decision of "ridiculous improbability" [Taylor, 1997] is up to the investigator, but it allows the reader to understand the basis for the decision
 - If beyond this range, delete the data

A CAVEAT ON REJECTION OF DATA

- If more than one measurement is different, it may be that something is really happening that has not been envisioned, *e.g.*, discovery of radon
- You may not be controlling all the variables that you need to
- Bottom line: Rigorous uncertainty analysis can give rationale to decide what data to pay attention to

SUMMARY

- Both the number and the fidelity of the number are important in a measurement
- We considered two types of uncertainties, bias (or systematic errors) and random errors
- Uncertainty analysis addresses fidelity and is used in different phases of an experiment, from initial planning to final reporting
 - Attention is needed to ensure uncertainties do not invalidate your efforts
- In propagating uncorrelated errors from individual measurement to final result, use the square root of the sums of the squares of the errors
 - There are generally only a few main contributors (sometimes one) to the overall uncertainty which need to be addressed
- Uncertainty analysis is a critical part of "real world" engineering projects

SOME REFERENCES I HAVE FOUND USEFUL

- Baird, D. C., 1962, Experimentation: An Introduction to Measurement Theory and Experiment, Prentice-Hall, Englewood Cliffs, NJ
- Bevington, P. R, and Robinson, D. K., 1992, *Data Reduction and Error Analysis for the Physical Sciences*, McGraw-Hill, New York, NY
- Lyons, L., 1991, *A Practical Guide to Data Analysis for Physical Science Students*, Cambridge University Press, Cambridge, UK
- Rabinowicz, E, 1970, An Introduction to Experimentation, Addison-Wesley, Reading, MA
- Taylor, J. R., 1997, *An Introduction to Error Analysis*, University Science Books, Sauselito, CA

BACKUP EXAMPLE: MEASUREMENT OF JET ENGINE PEFORMANCE

- We want to measure Thrust, Airflow, and Thrust Specific Fuel Consumption (TSFC)
 - Engine program can be \$1B or more, take three years or more
 - Engine companies give guarantees in terms of fuel burn
 - Engine thrust needs to be correct or aircraft can't take off in the required length
 - Airflow fundamental in diagnosing engine performance
 - These are basic and essential measures
- How do we measure thrust?
- How do we measure airflow?
- How do we measure fuel flow?

THRUST STANDS

- In practice, thrust is measured with load cells
- The engines, however, are often part of a complex test facility and are connected to upstream ducting
- There are thus certain systematic errors which need to be accounted for
- The level of uncertainty in the answer is desired to be less than one per cent
- There are a lot of corrections to be made to the raw data (measured load) to give the thrust

TEST STAND-TO-TEST STAND DIFFERENCES

- Want to have a consistent view of engine performance no matter who quotes the numbers
- This means that different test stands must be compared to see the differences
- Again, this is a major exercise involving the running of a jet engine in different locations under specified conditions
- The next slide shows the level of differences in the measurements